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Electric Drives and Controls

Hydraulics

Linear Motion and Assembly Technologies

Pneumatics

Rexroth **Bosch Group**

2-way proportional throttle valve for block installation

RE 29202/07.05 Replaces: 03.00

1/12

Types FE; FEE

Size 16 Component series 2X Maximum operating pressure 315 bar Maximum flow 190 L/min bei $\Delta p = 10$ bar



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Features

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- Pilot operated 2-way proportional throttle valve for block instal-
- 1 - Installation dimensions to DIN ISO 7368-BA-06-2-A 2
- Electrically position-controlled orifice spool
- Direction of flow A to B
 - In the event of a power failure or cable break (or withdrawal of the enable 1) the orifice spool moves automatically to the closed position and blocks the flow from A to B
- 5, 8 - In conjunction with a pressure compensator, can be used for 6, 7 pressure-compensated flow control 9
 - Type FE for external control electronics (separate order), see
 - Type FEE: completely matched unit with integrated electronics (OBE), optionally available with voltage or current interface

¹⁾ Type FEE only



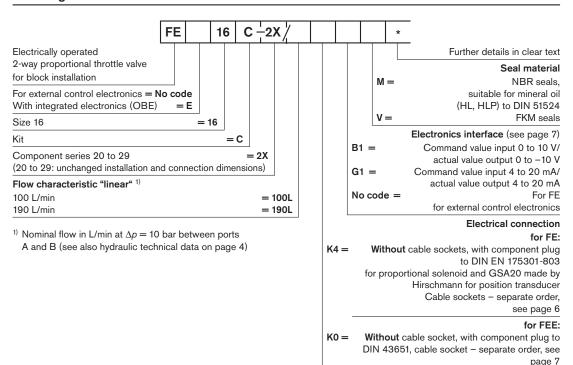
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FE; FEE | RE 29202/07.05

Ordering code



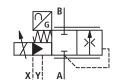
Standard type

Туре	Material no.
FFF 16 C-2X/190LK0B1M	R900954413

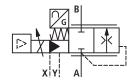
Symbols

Simplified

FE 16 C-2X/... ²⁾



FEE 16 C-2X/... 2)



Direction of flow: A to B (X connected with A)

Mote: Connect pilot oil port X with A

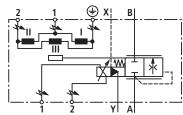
or connect externally

▲ Caution! In the case of external pilot oil supply at X,

the pressure in X must be ≥ pressure in A!

Detailed (example of type FE)

FE 16 C-2X/...



A service port
 B service port
 X pilot oil supply

pilot oil drain



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Function, section

Valves of type FE(E) are pilot operated 2-way proportional throttle valves for block installation for the infinitely variable control of a flow.

Technical structure:

The valve consists of four main assemblies:

- Cover (1) with mounting face for pilot oil ports.
- Main valve (2) with orifice spool (3).
- Pilot valve (4) with proportional solenoid (5).
- Integrated control electronics (6) (not provided for type FE) with position transducer (7).

General function:

- Command value-related closed-loop position control of orifice spool (3) and therefore defined opening of orifice (8).
- The flow depends on the Δp across orifice (8) and the position of orifice spool (3).
- Actual value acquisition of the position of orifice spool (3) by position transducer (7); command/actual value comparison in electronics (6); deviations are conditioned and passed on to proportional solenoid (5) of pilot valve (4) in the form of a control output for correcting the position of orifice spool (3).
- Area ratio of area (15) to area (12) = 1:1.
- Direction of flow A → B; connect X to A or connect externally.
- Caution! With external pilot oil supply, the pressure in X must be ≥ pressure in A to ensure proper functioning of the valve.
- A pilot oil by-pass via nozzle (16) increases vibration damping.
- When the enable is withdrawn, orifice spool (3) moves against mechanical limit stop (17) in the valve bushing (closed position) and blocks the flow A → B.
- The orifice spool position is already controlled at a command value of 0 V or 4 mA, with orifice (8) still being in the positive overlap position and closing A → B.
- For leakage across orifice spool (3) and pilot valve (4) at command 0 V or 4 mA and inactive enable, see Technical data on page 4.

Function of opening orifice spool:

Flow A \rightarrow B and A connected with X

 Proportional solenoid (5) shifts pilot spool (4.1) against spring (13) and opens the connection between control chamber (12) and Y; the pressure in control chamber (12) is reduced, and orifice spool (3) moved to the direction of opening by the pressure in A that acts on area (15).

Function of closing orifice spool:

Flow A \rightarrow B and A connected with X

Current reduced in proportional solenoid (5); spring (13) shifts pilot spool (4.1) against the proportional solenoid and opens the connection between X and control chamber (12); pressure builds up in control chamber (12); the pressure acting on the orifice spool area in control chamber (12) plus spring force (10) shift orifice spool (3) in the closing direction.

Flow control function:

 In conjunction with a pressure compensator, can be used for the pressure-compensated control of a flow.

Failure of the supply voltage:

- The integrated electronics de-energises the solenoid in the event of a supply voltage failure or cable break in position transducer (7).
- The spool is shifted to the closed position by the pressure applied to pilot port X plus spring force (10) and blocks the flow A → B.

6 5 1 13 12 4.1 10 2 16 15 Type FEE 16 C-2X/... 7 1,01111) Type FE 16 C-2X/...

▲ Caution: A voltage supply failure results in a sudden standstill of the controlled axis. Accelerations that can occur in conjunction with this can cause damage to machines!



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Technical data (for applications outside these parameters, please consult us!)

	· · · · · · · · · · · · · · · · · · ·			7.1
General				
Weight - FE kg		kg	2.7	
		- FEE	kg	2.9
Installation orientatio	n			Optional
Storage temperature	range		°C	- 20 to + 80
Ambient		– FE	°C	- 20 to + 70
temperature range		- FEE	°C	- 20 to + 50
Hydraulic (meas	ured with HLP 46; ϑ_{c}	_{oil} = 40 °	C ± 5 °	°C)
Max. operating pressure-			bar	315
Max. pilot pressure -	- Port X		bar	315
Return flow pressure-	- Port Y			At zero pressure to tank
Min. inlet pressure	in A (direction of flow A	→ B)	bar	7
Max. flow $q_{V_{max}}$ of ma	in valve at Δp 10 bar			
	Direction of flow $A \rightarrow B$		L/min	190
Pilot oil volume for sw	itching process from seated	d position		
(0 → 100%		cm ³	0.9
Max. pilot oil flow in p	oort Y:			
1	With stepped input signal		L/min	2.5
Direction of flow				$A \rightarrow B$
Pilot oil port				Connect X to A or connect externally. ★ Caution! With external pilot oil supply, the pressure in X must be ≥ pressure in A.
Leakage fluid - State: Command value 0 V or 4 mA		From A \rightarrow B, see characteristic curve on page 9 Max. 0.4 L/min from A \rightarrow X and across the nozzle in the main spool to Y at Δp 315 bar		
-	- State: Enable inactive (solenoid de-er	le inactive noid de-energised)		Max. 1.5 L/min from A \rightarrow B at $\Delta \rho$ 315 bar; max. 0.2 L/min from A \rightarrow X and across the nozzle in the main spool to Y at $\Delta \rho$ 315 bar
Hydraulic fluid				Mineral oil (HL, HLP) to DIN 51524; further hydraulic fluids on enquiry!
Hydraulic fluid tempe	rature range		°C	- 20 to + 80
Viscosity range			mm²/s	15 to 380
Max. permissible degre	e of contamination of the hyd	draulic fluid		
Cleanliness class - Pilot valve			Class 17/15/12 1)	
to ISO 4406 (c)	- Main valve			Class 20/18/15/ 1)
Hysteresis			%	< 0.2
Response sensitivity			%	< 0.1
Range of inversion			%	< 0.15
Range of inversion			%	< 0.15

¹⁾ The cleanliness classes specified for components must be adhered to in hydraulic systems. Effective filtration prevents malfunction and, at the same time, prolongs the service life of components.

For the selection of filters, see data sheets RE 50070, RE 50076, RE 50081, RE 50086 and RE 50088.



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Technical data (for applications outside these parameters, please consult us!)

Technical data (for applications outside these parameters, please consult us:)					
electronics					
alve for type FE)					
Type of voltage V		24 DC			
Nominal current mA		1000			
e at 20 °C	Ω	12.7			
value	Ω	19.3			
(%	100			
Electrical connection		With component plug to DIN EN 175301-803			
		Cable socket to DIN	N EN 175301-803 ¹⁾		
Type of protection of the valve to EN 60529		IP65 with cable socket mounted and locked			
n transducer (main stag	ge)				
ance of coils between		1 and 2	2 and ≟	≟ and 1	
at 20 °C (see Symbols on page 2) Ω		31.5	45.5	31.5	
Inductance mH		6 to 8			
Oscillator frequency kHz		2.5			
Electrical connection		With component plug GSA20 made by Hirschmann			
		Cable socket GM209N (Pg9) made by Hirschmann 1)			
Type of protection to EN 60529		IP65 with cable socket mounted and locked			
Electrical position measuring system		Differential throttle			
E only; separate order))				
	electronics alve for type FE) me at 20 °C value EN 60529 In transducer (main stage ance of coils between) me kh	electronics Alve for type FE) V MA te at 20 °C Ω value Ω EN 60529 In transducer (main stage) ance of coils between D MH kHz	V 24 DC mA 1000 12.7 1000 100	V 24 DC mA 1000 100	

Type FEE - integrated electronics (OBE)

Electrical		
Duty cycle	%	100
Current consumption – I _{max}	Α	1.3
- Pulse load	Α	1.5
Electrical connection		With component plug to DIN 43651
		Cable socket to DIN 43651 11-pin + PE/Pg16 2)
Type of protection of the valve		IP65 with cable socket mounted and locked
Control electronics		Integrated in the valve (see page 8)

analogue

VT-VRPA1-50-1X to data sheet RE 30117

Amplifier in Euro-card format

Mote:

For details regarding **environment simulation testing** in the fields of EMC (electromagnetic compatibility), climate and mechanical stress, see RE 29202-U (declaration on environmental compatibility).

¹⁾ Separate order, see page 6

²⁾ Separate order, see page 7



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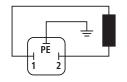


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Electrical connection, cable sockets (nominal dimensions in mm)

Type FE - for external ontrol electronics

Connection to component plug



Connection to cable socket

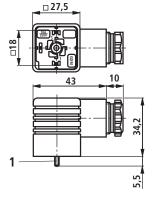


Cable socket to DIN EN 175301-803

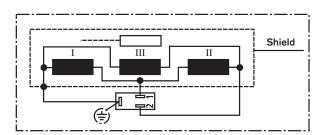
Separate order stating material no. R901017011

(plastic version)

1 Fixing screw M3 Tightening torque $M_{\rm T} = 0.5 \, \rm Nm$



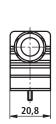
Inductive position transducer

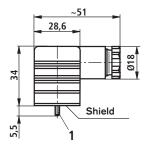


Cable socket GM209N (Pg 9) made by Hirschmann

Separate order stating material no. R900013674

(plastic version)





1 Fixing screw M3 Tightening torque $M_{\rm T} = 0.5$ Nm



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Electrical connection, cable sockets (nominal dimensions in mm)

Type FEE - with integrated electronics (OBE)

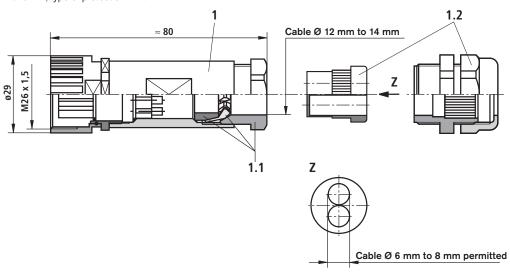
Cable socket to DIN 43651/11-pin + PE/Pg16

Separate order stating material no. R900884671 (plastic version)

Assembly consisting of items 1 and 1.1 or items 1 and 1.2, type of protection IP65

Note:

- If one cable is used, combine item 1 with item 1.1
- If two cables are used, combine item 1 with item 1.2



	EP.	O THE CO		
Pin	Function	Conditions		
1	Operating voltage +UL	$U_{\rm O} = 24 \text{ VDC}; u_{\rm O}(t)_{\rm max} = 36 \text{ V}; u_{\rm O}(t)_{\rm min} = 21,6 \text{ V}$		
2	Ground L0			
3	Enable input / reference for pin 2	log 1 = 10 V to 36 V; log 0 = U < 8 V		
		Type FEE/B1	Type FEE/G1	
		Voltage interface	Current interface	
4	Command value input	0 V to + 10 V ($R_i > 50$ kΩ)	$+$ 4 mA to $+$ 20 mA / load $=$ 100 Ω	
5	Command value input, reference			
6	Actual value output	0 V to - 10 V (I _{max} = 5 mA)	+ 4 mA to + 20 mA / load \leq 500 Ω	
7	Actual value output, reference			
8	free			
9	free			
10	free			
11	Ready for operation (output)	Valve not ready for operation:	U _{Pin11} < 8 V;	
		Valve ready for operation:	$U_{\text{Pin11}} = U_{\text{O}} - 3 \text{ V}$	
		Reference – pin 2:	(I _{max} against 0 V; 50 mA);	
PE	Protective conductor \(\frac{1}{2} \)			

Recommended connecting cable - Up to 25 m min. 0.75 mm² per wire – Up to 50 m min. 1.5 mm² per wire

- Connect shield to PE only on the supply side

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Integrated electronics (OBE) bei Type FEE

Function

1. Making operation/disturbance characteristic:

After the supply voltage of 24 V was applied, the electronics is ready for operation, if the following conditions are fulfilled:

- Operating voltage $U_{\rm O}$ > 18 VDC
- The internal ± 7.5 V supply voltage is symmetrical
- The connection to the position transducer is not interrupted.
- The command value cable is not interrupted (only with 4 mA to 20 mA interface)

If one of these conditions is not fulfilled, the controller and the output stage are blocked and the signal "ready for operation" is set to < 8 V.

2. Normal operation

When the enable is inactive (< 8 V) and an optional command value is fed forward (0 to 10V or 4 to 20 mA) the orifice spool is in the seated position and blocks the flow from A to B.

By applying a voltage > 10 V to the enable, the position controller for the orifice spool and the output stage for the pilot valve are switched on. At the same time, the position control-

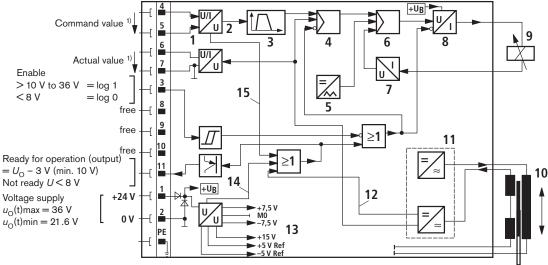
ler (PID) compares the actual value of the orifice spool position with the applied command value, and a control output is fed to the output stage, which changes the solenoid current until the orifice spool position corresponds to the command value.

The actual value of the orifice spool position is sensed by an inductive position transducer. The signal of the latter is rectified by the demodulator and fed back to the PID-controller.

The following output signals are available on the plug:

- Actual position value FEE.../...B1 (pin 6)
- 0 V to 10 V corresponds to 0 % to 100 % valve opening
- Orifice spool at mechanical limit stop \rightarrow actual value > 0.2 V
- Actual position value FEE.../...G1 (pin 6)
 - \bullet 4 mA to 20 mA corresponds to 0 % to 100 % valve opening
 - Orifice spool at mechanical limit stop \rightarrow actual value < 3.65 mA
- Signal "ready for operation" (pin 11)
- All conditions listed above are fulfilled \rightarrow > 10 V
- One of the conditions is not fulfilled \rightarrow < 8V

Block circuit diagram / pin assignment of integrated electronics



 $^{1)}$ With current version (4 mA to 20 mA), please observe: Between connections 5 and 4, load = 100 Ω Between connections 6 and 7, load \leq 500 Ω

Stroke s in mm

- 1 Input
- 2 Output
- 3 Fixed ramp
- 4 Position controller
- 5 Clock pulse
- 6 Current regulator
- 7 I/U converter
- 8 Output stage

- 9 Proportional solenoid
- 10 Position transducer
- 11 Oscillator / demodulator
- 12 Fault signal of position transducer
- 13 Power supply unit
- 14 Fault signal in the event of +U_O undervoltage and asymmetry in the power supply unit
- 15 Cable break signal with current command value



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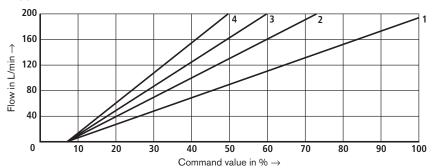
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Characteristic curves (measured with HLP 46 and $\vartheta_{\text{oil}} = 40 \, ^{\circ}\text{C} \pm 5 \, ^{\circ}\text{C}$)

Flow characteristic linear

FE(E) 16 C...



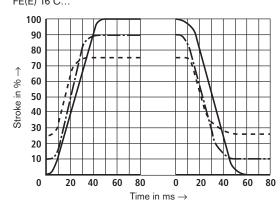
10 bar

20 bar $\Delta p =$

3 $\Delta \rho =$ 30 bar

4 $\Delta p = 50 \text{ bar}$

Transient function with stepped command value change 1) FE(E) 16 C...



0 - 100 - 0% Step responses 10 - 90 - 10 % -----25 - 75 - 25 % ----

1) Measurement conditions Pressure in A = 50 bar

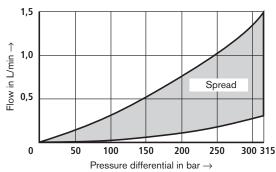
Command value change $0 \rightarrow 100\%$

Pressure in A \leq 50 bar \rightarrow actuating time extends Pressure in A > 50 bar \rightarrow actuating time shortens

Command value change $100 \rightarrow 0\%$

No change in actuating time, if pressure in X = A

Leakage from $A \rightarrow B$ in dependence upon the pressure differential Δp (command value 0 V or 4 mA, resp.) FE(E) 16 ../..190L.

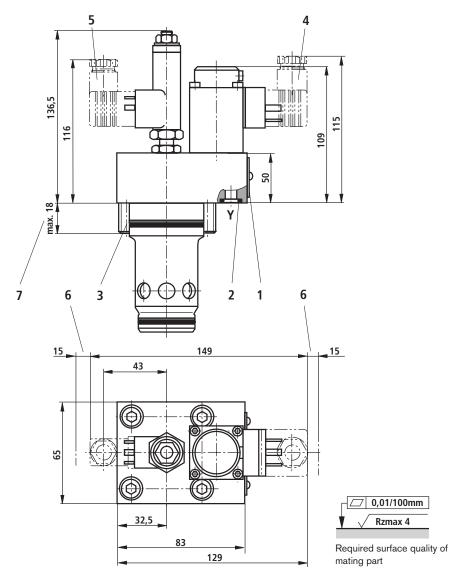




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Unit dimensions: Type FE (nominal dimensions in mm)



- 1 Nameplate
- 2 Identical seal rings for ports X and Y
- 3 Valve fixing screws (included in the scope of supply) 4 socket head cap screws M8 x 35 to ISO 4762-10.9 (friction coefficient 0.09 ... 0.14 to VDA 235-101) Tightening torque $M_{\rm T}=25~{\rm Nm}$
- 4 Cable socket to DIN EN 175301-803 Separate order, see page 6
- 5 Cable socket GM209N (Pg 9) made by Hirschmann Separate order, see page 6
- 6 Space required to remove cable socket
- 7 Screw-in length of valve fixing screws



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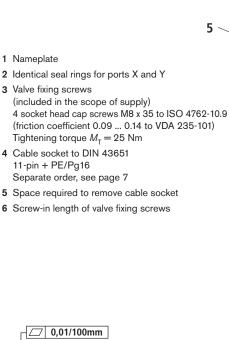


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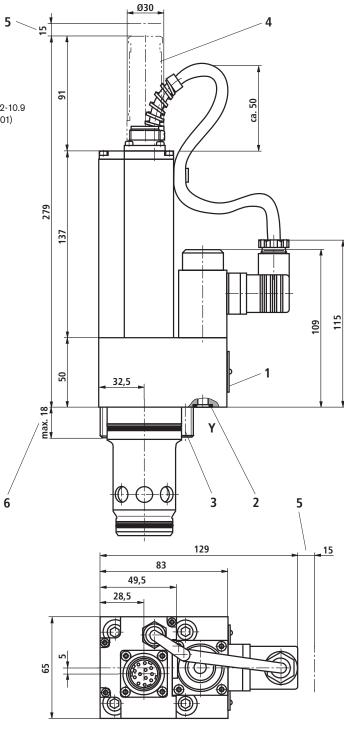
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Unit dimensions: Type FEE (nominal dimensions in mm)



Rzmax 4

Required surface quality of mating part





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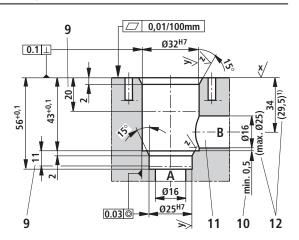
Installation dimensions (nominal dimensions in mm)

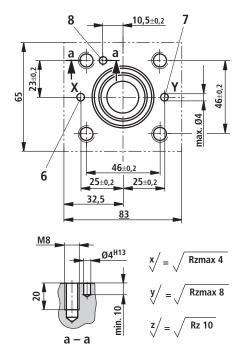
Installation dimensions to DIN ISO 7368-BA-06-2-A

- 6 Port X
- 7 Port Y
- 8 Locating bore for locating pin
- 9 Depth of fit
- 10 Reference dimension
- 11 Port B can optionally be arranged around the central axis of port A. However, care must be taken that the fixing bores and pilot bores are not drilled.
- 12 In the case of a diameter of port B other than specified, the distance from the cover contact face to the centre of the bore must be calculated.
- Minimum distance (29.5 mm) with maximum diameter (Ø25 mm)

Tolerances to:

- General tolerances ISO 2768-mK





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