Rexroth
Bosch Group

Users manual
Hägglunds Spider Control System
EN723-3BR 2012

Preface

The intention of this manual is to give information about standard Spider II control system that is needed for usage of the system, to answer questions from the customers and to give a good level of information about the functions.
Information about specific order related connections and configuration is attached in the system documentation at delivery.
In order to find particular information, search for the wanted selection as listed in the table of contents.
However, changes in the equipment may occur. We therefore reserve the right to introduce amendments in the manual as we deem necessary without notice or obligations.

All viewpoints that can make this manual better and more useful are welcome

Send your viewpoints to:

documentation@boscrexroth.se

Warning signs

In this manual you will find the following signs which indicate a potential hazard, which can or will cause personal injury or substantial property damage.
Depending on the probability of the hazard, and how serious the injury or property damage could be, there are three levels of classification.

Warning sign (warning triangle): Draws attention to the hazard
Signal word: Identifies the degree of hazard
Type of risk: Specifies the type or source of the hazard
Consequences: Describes the consequences of non-compliance
Precautions: Specifies how the hazard can be prevented

The signal words have the following meaning:

Signal word	Application
	Indicates an **imminently hazardous** situation which, if not avoided, will certainly result in death or serious injury.
	Indicates a **potentially hazardous** situation which, if not avoided, will certainly result in death or serious injury.
	Indicates a **potentially hazardous** situation which, if not avoided, could result in minor or moderate injury or damage to equipment.

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1 Indication and setting

1.1 Description

The Spider unit is a microcontroller based system, configurable to suit different application needs. It is designed to match the two or three door PEC or DU power unit also with a one door unit added. The control system can control pumps with double coil or single coil in one direction.

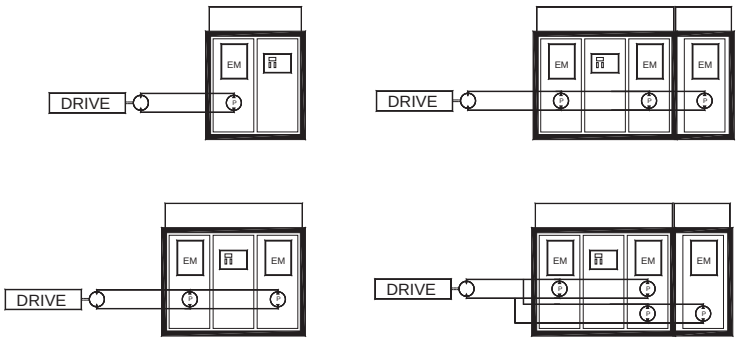
The unit can for PEC be mounted inside the power unit, in the power unit door, on the outside of the power unit or delivered separate with wall brackets or panel flange to be wired in by the customer. Cable sets can be supplied as an option.
The unit will for DU be mounted on the power unit side with the control panel (LIU) on the outside or inside of the front door communicating via CAN.

The front panel of the Spider includes a set of buttons for set up, and a set for drive control (one set/drive).The configuration of the pre-programmed system functions is done using the front panel with help from the text displays or via a serial connection from a laptop. The configuration mode can be protected with a password.

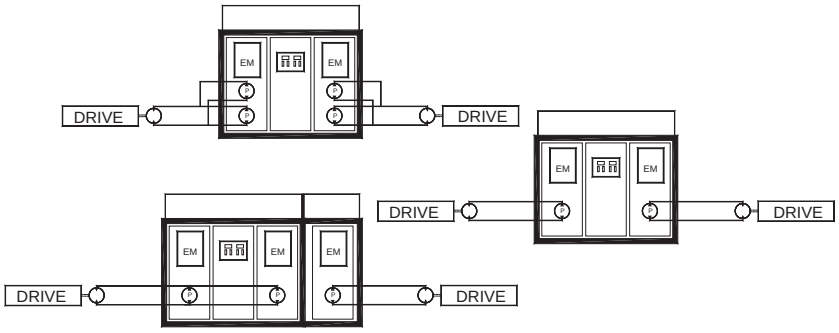
The system includes a drive monitoring function with drive time counters, alarm/warning list and 8 scalable log channels with data download via serial interface. A remote drive monitoring system with access via GSM can be added as an option.

The Spider unit can control the system with different settings of electric motor/pump configuration.

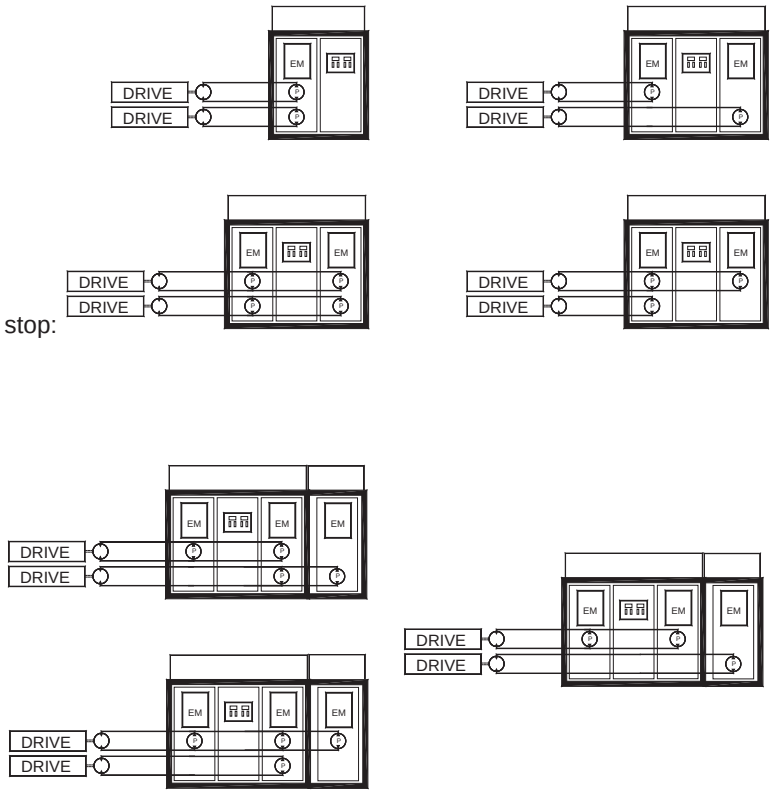
- One to four pumps for one drive:



- Two to four pumps for two drives with separate function:

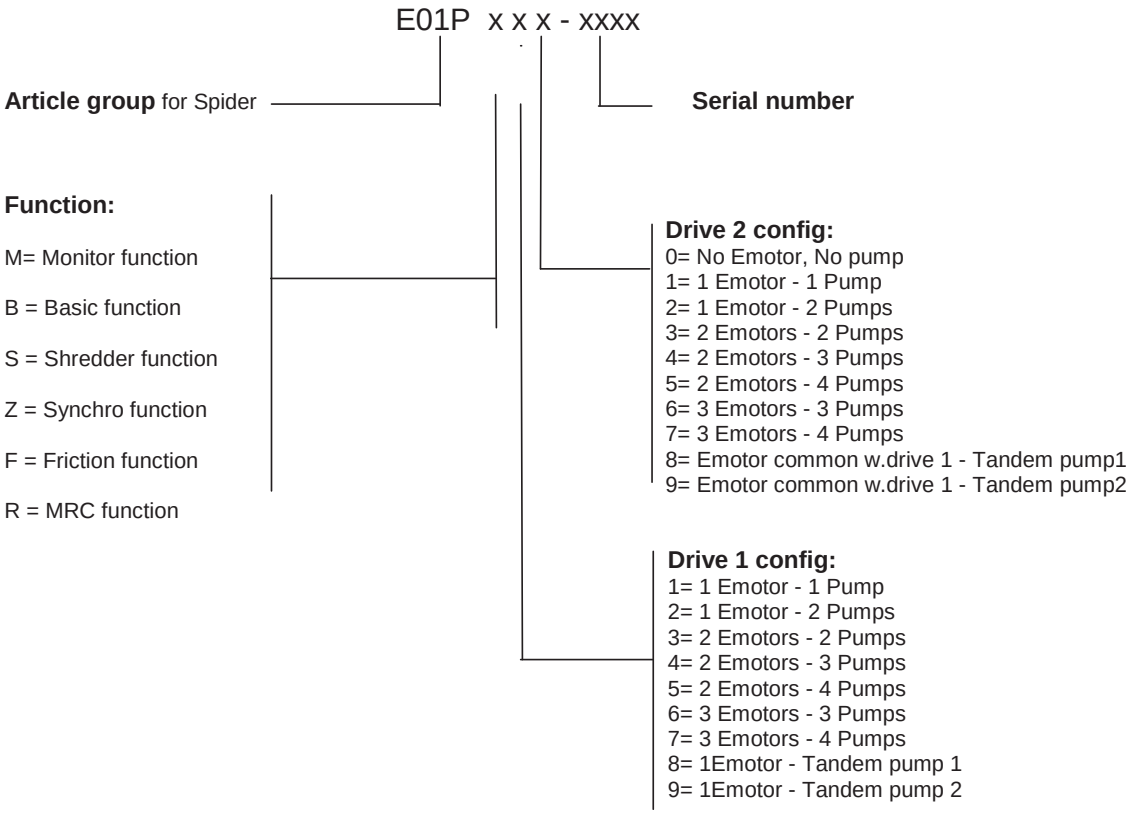


Two to four pumps for two drives with common function. If one stops by a fault the other will also stop:



1.2 Serial number

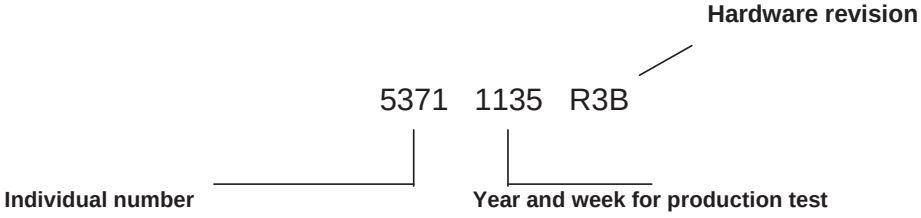
This serial number system is used up to Serial number -4653:



Serial number after -4653 is Cxxxxx without any correlation to the function. C is standing for Controls but the following number is used for all types of different control equipment.

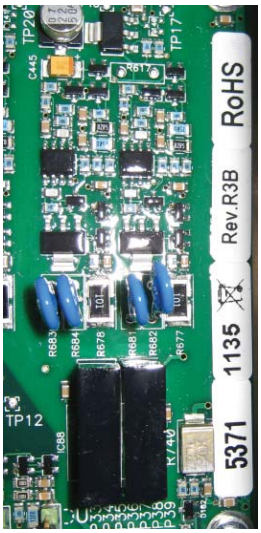
1.3 Card number

The individual card number is marked on the card at final test. The number consists of an individual number and year and week for the production test. The hardware revision marking is adjacent to the card number



Example:

Layout Rev A



Layout Rev B

1.4 Ordering code

A	B	C	D	-	E	F	G	H	I	-	J	-	K	L

A — FUNCTION

M	Monitor	Driver and functions for monitoring of power unit
B	Basic	Monitor with added functions for Speed feedback and power limitations
S	Shredder	Basic with added functions for shredder drives
Z	Synchro	Basic with added functions for synchronization between two drives
F	Friction	Basic with added function for friction control between two drives.
R	MRC	Basic with added functions for synchronization and friction between two drives

B — DRIVE 1 CONFIGURATION

1	1 el. motor - 1 pump
2	1 el. motor - 2 pumps
3	2 el. motors - 2 pumps
4	2 el. motors - 3 pumps
5	2 el. motors -4 pumps
6	3 el. motors - 3 pumps
7	3 el. motors - 4 pumps
8	1 el. motor - Tandem pump 1
9	1 el. motor - Tandem pump 2

C — DRIVE 2 CONFIGURATION

0	No el. motor - No pump
1	1 el. motor - 1 pump
2	1 el. motor - 2 pumps
3	2 el. motors - 2 pumps
4	2 el. motors - 3 pumps
5	2 el. motors -4 pumps
6	3 el. motors - 3 pumps
7	3 el. motors - 4 pumps
8	El. motor 1 - tandem pump 1
9	El. motor 1 - tandem pump 2

D — ASSEMBLING ALTERNATIVE

1	Loose item with brackets excl. cables
2	Loose item with flange excl. cables
4	Mounted inside PU
5	Mounted on PU door
6	Mounted in PU door
7	Mounted on side of PU

E — DISPLAY

0	LCD type (standard)
1	VFD type (Required for Chinese char.)

F — HEATER

0	None
1	Installed in SPIDER box

G — FIELDBUS CARD

0	None
1	Profibus
2	Modbus RTU
3	Controlnet
4	Ethernet IP
6	Profinet
7	Devicenet
8	Modbus TCP
9	CC-link

H — RMS

0	None
1	Installed with antenna on box
2	Installed with external antenna

I — PRESSURE CONTROL

0	None
1	Pressure control Drive 1
2	Pressure control Drive 2
3	Pressure control both drives

J — POWER SUPPLY

0	External 24VDC
1	Internal 250W (standard)

K — POTENTIOMETER

0	None
1	Installed in SPIDER box

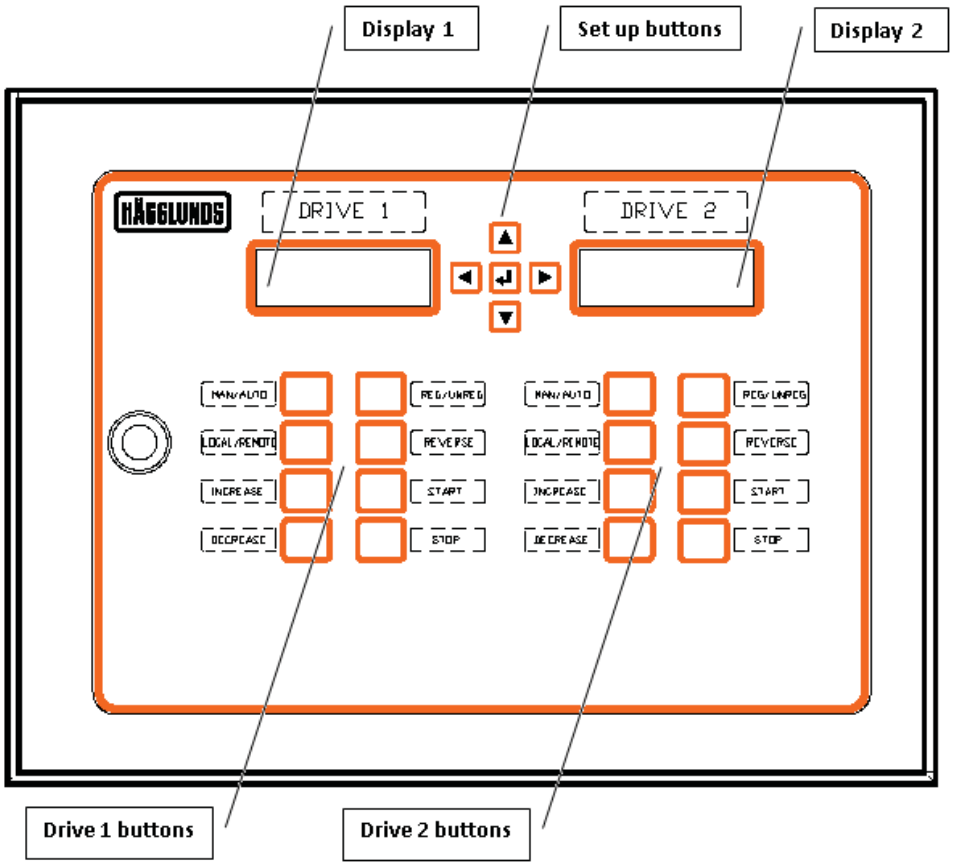
L — PLEXIGLASS WINDOW

0	None
1	Assembled

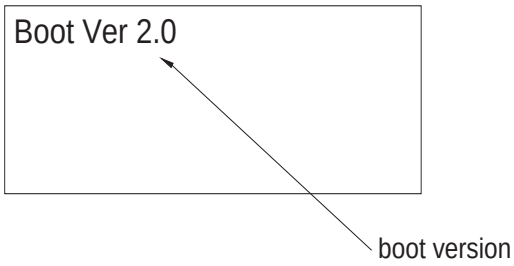
2 DISPLAY AND BUTTONS

2. 1 Display information

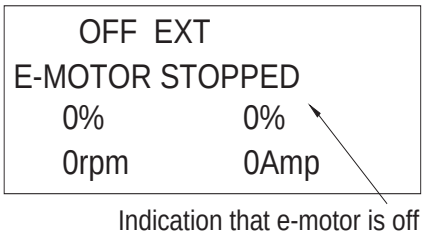
Spider can be equipped with keypads and display for one or two drives. A Spider unit for one drive has one set of display and drive buttons. A Spider unit for two drives has two sets. All units have one set of set up buttons (arrows and enter button).
From main card rev R3A it is possible to place the displays and keypads as a Local interface unit (LIU) separated from the Spider main card box.
For a double display unit the positions of Drive 1 and Drive 2 can be switched.



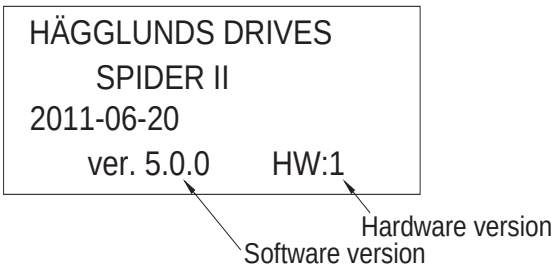
POWER UP SPIDER



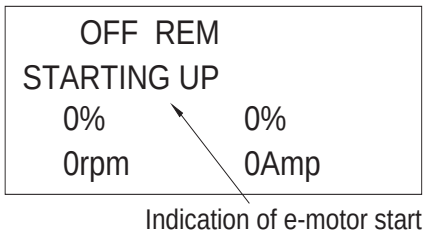
E-MOTOR STOPPED



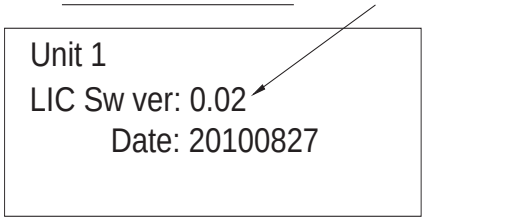
START UP TIME SPIDER



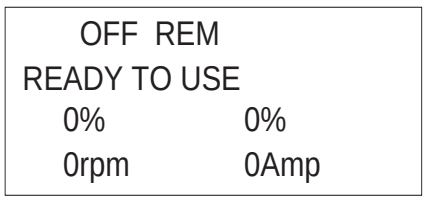
E-MOTOR STARTING



START UP TIME LIU

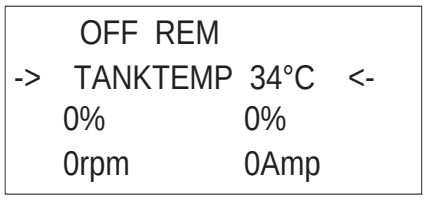


E-MOTOR STARTED
SYSTEM READY TO USE

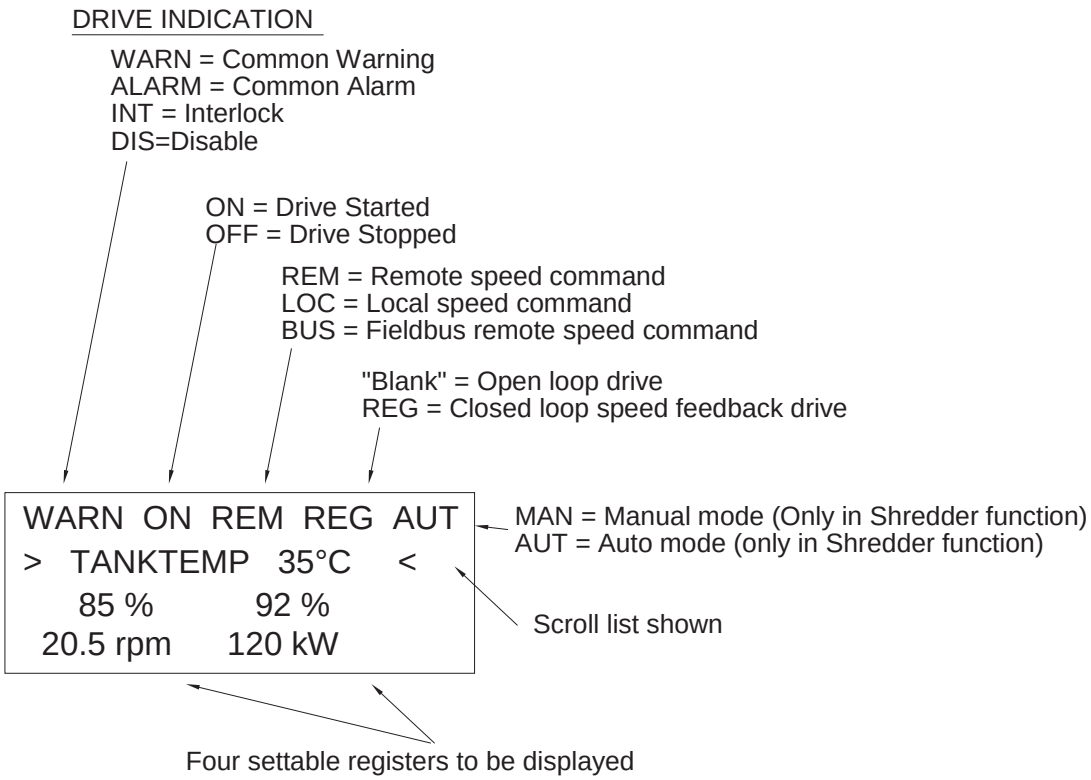


TESTING HARDWARE

DRIVE MODE



2.2 Information on normal drive and alarms



ALARM INDICATION

ALARM DRIVE 1
MIN OIL LEVEL

WARNING INDICATION

WARNING DRIVE 1
LOW OIL LEVEL

INTERLOCK INDICATION

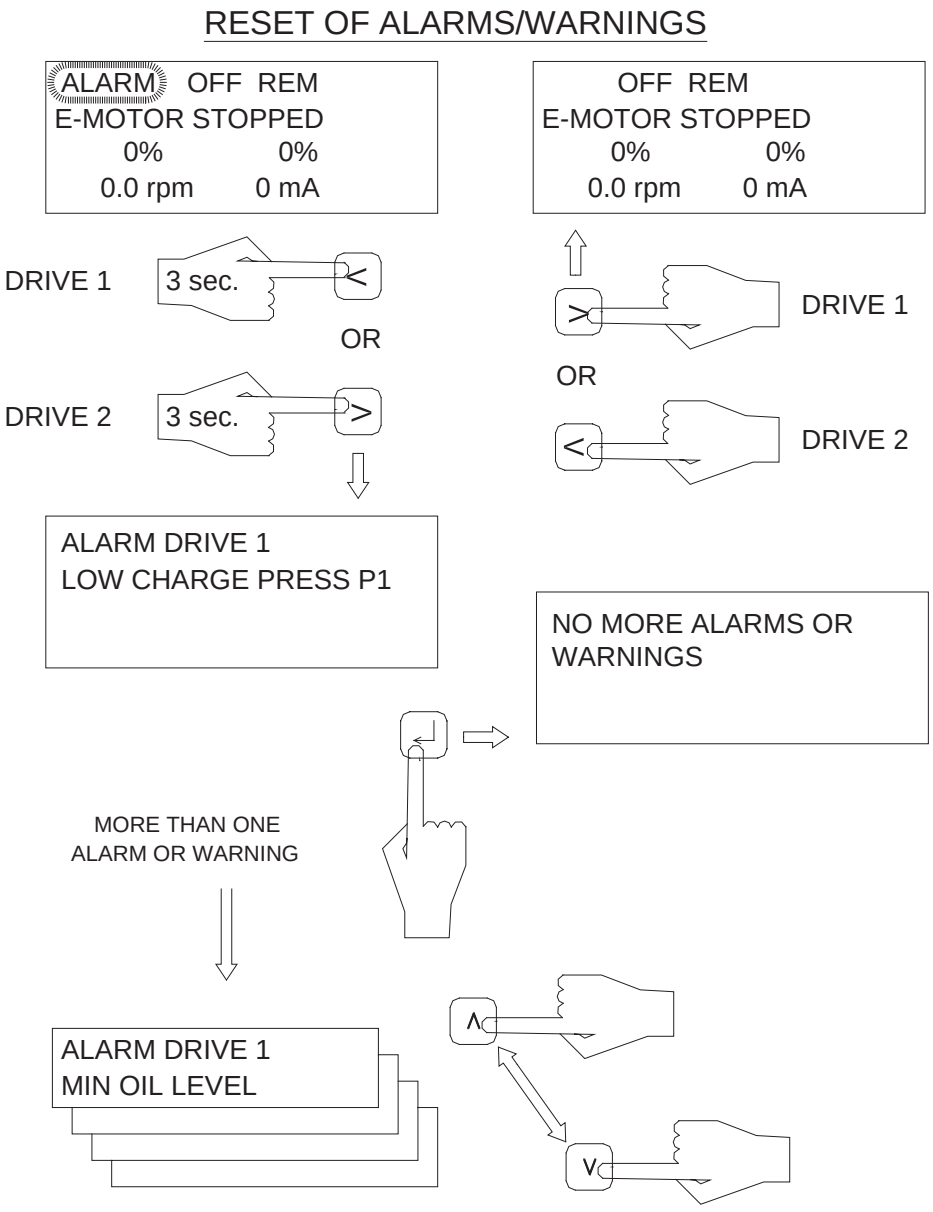
INTERLOCK DRIVE 1
NO EXT FEED

2.3 Reset of alarms and warnings

To enter the list of alarms, warnings and interlocks press an arrow button (◄►) for 3 sec.
If the current Spider has two displays press left arrow to enter list for drive 1, right arrow for drive 2. A common alarm/warning can be seen on both the displays.

The alarms and warnings are showed one and one. If there are several notifications scroll with up and down arrows (▼▲) to see all messages in the list.

To reset a notification go into the alarm/warning list and press the Enter button after the reason for the indication is fixed.
When there is "NO MORE ALARMS OR WARNINGS" push left or right arrow button (◄►) to return to main menu.



2.4 Front panel buttons

2.4.1 Set up buttons

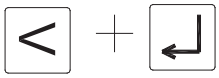
Go down one level in display menu.
Accept a change in parameter.
Reset alarm, warning or interlock

Go up one level in display menu.
Escape without change of parameter.
Select Drive 1 scroll list (short time press)
Select Drive 1 alarm list (press for 3 sec.)

Select Drive 2 scroll list (short time press)
Select Drive 2 alarm list (press for 3 sec.)

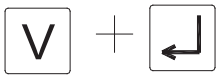
Scroll up in display menu.
Go to next alarm / warning.
Increase parameter.

Scroll down in display menu.
Go to previous alarm / warning.
Decrease parameter.



Press 3 sec. to enter setup list

Inrease contrast on display



Decrease contrast on display

2.4.2 Drive buttons

DRIVE BUTTONS

MAN/AUTO	Switching between manual and auto drive mode (Only avaliable in Shredder function)
LOCAL/ REMOTE	Switching between front panel and external setpoint/start-stop if this function is selected.
INCREASE	Increase speed setpoint when driving in local mode (front panel setpoint).
DECREASE	Decrease speed setpoint when driving in local mode (front panel setpoint).
Same button: FORWARD	Manual forward in Shredder function.
Same button: REG/UNREG	Switching between open and closed loop speed control when speed feedback used. (Not avaliable in Shredder function)
REVERSE	Inch reverse with fixed speed. Manual reverse in Shredder function.
START	Start of drive.
STOP	Stop of drive.
	Toggling of relay output for DU internal light Can be addressed to first and second button in each row

2.5 Error codes

2.5.1 Program start

WARNING EEPROM READING FAILED
This error message indicates that the Spider software can't read saved parameter values from the memory card. This error can occur if : No memory card connected, memory card defect or wrongly mounted or the information on the memorycard is corrupt. Spider software will start with default values on parameters.
WARNING WRONG EEPROM VERSION
This error message indicates that the Spider software can't use the parameter values that's stored on the memorycard because the parameter format stored on the memorycard not is compatible with the Spider software used. Spider software will start with default values on parameters.
WARNING WRONG CPLD VERSION
This error message indicates that the Spider software version used not is compatible with the software version in the CPLD (Complex Programmable Logic Device). The CPLD is used for digital in and outputs, counters, display and Anybus. The Spider will work in an unpredictable way.
WARNING LOG INIT ERROR
This error message indicates that the Spider software can't read the real time clock, saved alarms, warnings, drive times or setpoints from the memory card. These functions will not work.
This error can occur if no memory card is connected, memory card is defect or wrongly mounted or the information on the memorycard is corrupt.
The information will also show with a system where the parameters not have been set (first power-on).
WARNING 3D-LOG INIT ERROR
This error message indicates that the Spider software can't read the 3D-log on the memorycard.
The 3D -log function will not function. This error can occur if no memorycard is connected, memory card is defect or wrongly mounted or the information on the memorycard is corrupt.
The information will also show with a system where the parameters not have been set (first power-on).
WARNING NO SERIAL NUMBER
This error message indicates that the system serial number not is set with parameter NUM under Log function – Serial number. This is number is used in naming of the parameter file from SpiderCom.
WARNING NON COMPATIBLE MEM-C
This error message indicates that the system can't read the memory card.
The memory card is not connected, is of wrong type or is faulty.

2.5.2 Hardware monitoring

HW ERROR, FC 1
This test is to verify that the delay for electric motor interlock set in hardware with SW1 matches the delay set in the Spider parameters (for electric motor interlock). If emergency stop is actuated the relays in the hardware will open after set time 2-32 sec. (in 2 sec. steps). If this test not performes within the below shown limits, the error message "HW ERROR, FC 1" will be displayed.
The test is performed upon system start up.

HW delay < SW delay	Software stops
HW delay > SW delay + 4s	Only Warning, press a button for OK.
HW delay > SW delay + 5s	Software stops

When the software stops both Hardware(M) time and Software(S) time is displayed in 1/10 sec so that the times can be verified/corrected.

HW ERROR, FC 2
This test is to verify that the relay that feeds the PWM-outputs opens. If emergency stop is actuated the Spider hardware for emergency stop open this relay. This test is performed when all e-motors are stopped. If the relay doesn't open on this test, error message "HW ERROR, FC 2" is displayed and

the software stops.

HW ERROR, FC 3
This test is to verify that the electric motor interlock relays opens. When electric motor interlock is OK the relay is closed and open when interlock not is OK. If the relay not opens, error message ”HW ERROR, FC 3” is displayed and the software stops. This test is performed at power on and once when all electric motors are stopped.

HW ERROR, FC 4
Watchdog indication should not be acived during normal program execution. If it happens during normal program execution, error message ”HW ERROR, FC 4” is displayed and the software stops. This test is performed continiously.

HW ERROR, FC 5
If measured current is 50% greater than max configured current a shortcircuit is assumed, error message ”HW ERROR, FC 5” is displayed and the software stops. This test is performed continiously.

2.5.3 Software monitoring

WATCHDOG TIMEOUT
If the software halts or executes incorrect in that way that the control loop or the user interface loop can't execute within set time limits, error message ”WATCDOG TIMEOUT” is displayed and the software stops. Program address where the execution stopped is also displayed.

OUTPUT ERROR Px
If the measured pump current deviates more then the setting in parameter PMx13 from the procentual value of the set current between min and max current (Pox01-04) the output will be cut off. Function can be bypassed with parameter PMx12 set off.

2.5.4 Bus

BUS FAIL
Anybus function is selected but the communication does not function. This error is likely to occur if the bus cable not is connected.

BUS HW FAIL
Anybus function is selected but the hardware is not functioning. This error is likely to occur if the bus module is missing or defect.

2.6 Text settings

Indicating texts in Aux functions, AMx04 can be set via front panel or SpiderCom.
Serial number in drive log must be set via front panel.
The text characters are scrolled with ▲ or ▼buttons and selected with Enter button at the front panel. If the button tapped the characters will change one character at the time. If it is pressed during scroll the character will stopped at fixed positions.

Character sequence:
VFD:

▼ ▼ ▼ (stop points with pressed button are 0, A and a, scroll direction←)

To end..**01..89:;<=>?@AB..YZ[¥]^_´ab..yz{|}→← ÄvÅÖßü♪°C°F▼►◄▲blank!"#$%&'()*+,-./** to beginning

▲ ▲ ▲(stop points with pressed button are 9, Z and z, scroll direction→)

LCD:

▼ ▼ ▼ (stop points with pressed button are 0, A and a, scroll direction←)

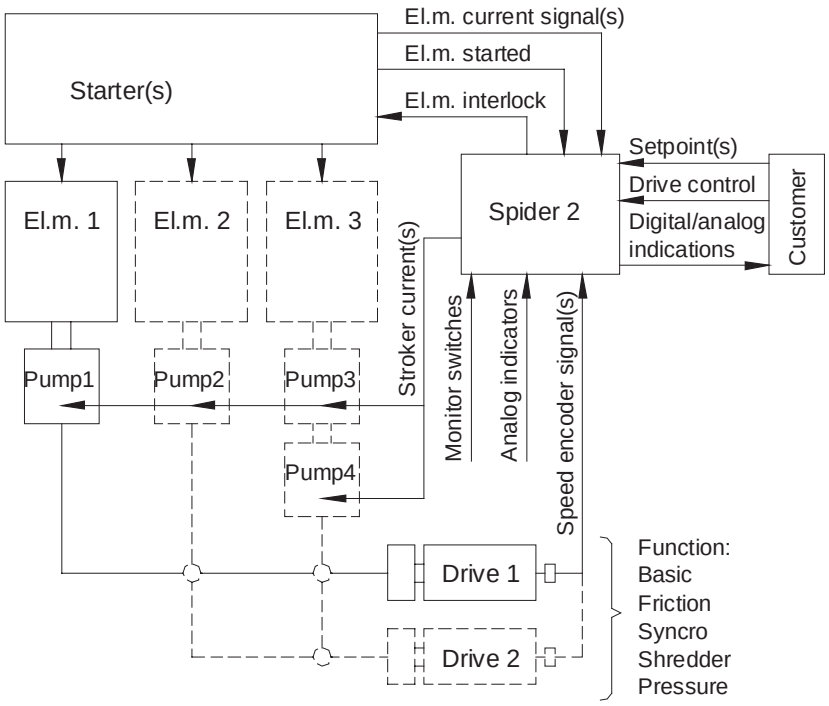
To end..**01..89:;<=>?@AB..YZ[¥]^_´ab..yz{|}→← ÄvÅÖßü blank!"#$%&'()*+,-./** to beginning

▲ ▲ ▲(stop points with pressed button are 9, Z and z, scroll direction→)

Japanese and special characters

3 GENERAL FUNCTIONS

3.1 Block diagram in- and outputs



3.2 Drive controls

The drive control buttons on the front panel are for start and stop of the drive, local/remote, speed set point by increase and decrease in local mode, inch reverse, regulated/non-regulated drive and auto/manual drive in shredder mode. These push-button functions can be bypassed in the configuration of the system functions. All above-mentioned functions can also be activated by remote signals (in addition to a lot of other signals that can be activated remotely).

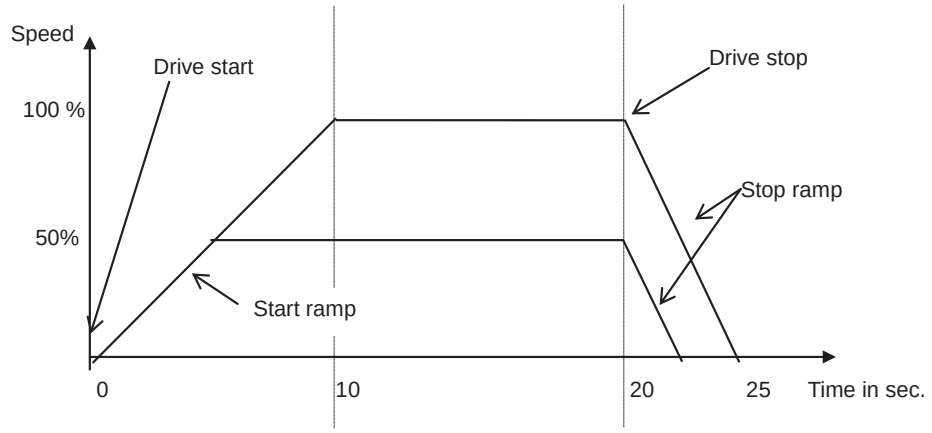
3.3 Speed command

The speed set point command can be the local command or a remote command signal.
The local command is set with the increase and decrease buttons on the front (or externally via digital inputs for increase/decrease).
Remote set point command is a voltage or current signal connected to the terminals (the type is set with a parameter and with jumper SP D1(2)). Remote set point can also be set via fieldbus (optional).
The speed command can be locked to local or remote control or be switchable with the local/remote button (or via digital input).
At local/remote switching the local set point command can either remain or automatically (or by a digital input) be set to zero (depends on the parameter settings).
Local increase/decrease will not affect the local set point when running in remote mode.

3.4 Ramp

The start ramp time is the time it takes for the signal to control the hydraulic pump, to go from zero to 100% if the speed set point is 100% and drive start is activated. The stop ramp is the time it takes to go from 100% to zero when drive stop is activated.
Drive start and stop are ramped commands (as well as fixed forward, fixed reverse and inch reverse). The start ramp is controlled by separate parameters in forward direction and reverse direction. The stop ramp is controlled by separate parameters forward direction and reverse direction.

Example: If the ”up ramp” is set to 10 sec. and the down ramp is set to 5 sec. we will get the following output.
The example is based on 50 and 100% set point.



3.5 Stroker current Output

There are two output channels for each pump (one for forward and one for reverse), with individual settings.
The outputs are Pulse Width Modulated and the PWM frequency is set in acc. with used stroker.
This means the Spider can control pumps with double coil (Denison 9A, Brueninghaus EP, Sauer Sundstrand KA or similar), or single coil in one direction (Denison 5A).

Coil resistance
The system will measure the current in the stroker coil and compensate for the resistance change due to increased temperature.
The nominal resistance of used stroker coil is set with a parameter.
A typical resistance value is:

5A2 (Denison)	25 Ω
9A2 (Denison)	41 Ω
SP (Brueninghaus)	20 Ω
KA (Sauer Sundstrand)	20 Ω

3.6 Digital outputs/inputs

3.6.1 Electric motor interlock outputs

There are 3 normally high off delayed digital outputs for interlock of the electric motors (shall be connected via a relay in the electric motor stop circuit). Each output is high when it is allowed (no alarms) to run corresponding electric motor, and will go low (open) time-delayed after an Alarm.
The delay time is set with an individual parameter for each output.

The normal stop sequence at alarm:
1. The output to the pump is set to zero without ramp.
2. After a time delay (adjustable) the electric motor interlock is opened.

The output relays are monitored to detect faulty relay contacts. At system power-up and when all e-motors are stopped, the relays will be tested if the emergency stop input not is open. To avoid faulty alarms from the relays, they will be switched on and off 5 times to remove oxidation from the contacts before the test.

3.6.2 Digital outputs

There are 13 digital outputs that can be used to monitor the status of Alarm, Warning or Interlock, or of a digital input.

3.6.3 Functions for monitoring

The monitoring function is available in all setups.
There are 43 digital inputs in total. The pre-programmed functions can be used for drive control and monitoring function with 4 different types of indication:
Warning = indication on the display (and by a digital output if this function is set).
Alarm = indication on the display (and by a digital output if this function is set).
This function will stop the drive without ramp and after a short delay open the electric motor interlock output to stop the motor (see "Electric motor interlock outputs" above).
Interlock = same as alarm but without stopping the electric motor.
Disable = same as alarm but without indication in the drive log.

The Warning, Alarm and Interlock indications must be reset in the Alarm/Warning list after the reason for the indication is fixed (see 2.5 Front panel buttons). Disable don't need to be reset.

3.7 Speed feedback

3.7.1 General

Speed feedback requires a speed encoder, digital or analogue (4-20 mA) and makes it possible to maintain a constant speed at the hydraulic motor shaft. The Spider compensates for speed deviations due to load changes. To achieve this, a PID regulator is implemented in the software. This PID regulator compares the actual speed value with the speed set-point. Any deviation between the two signals is detected as an Error signal and transferred to the PID regulator.
The proportional part amplifies the Error signal. The Output is proportional to the Error signal.
The Integral stage integrates the Error signal. A small Error signal will over time create a big Integral stage output.
Derivative stage derives the Error signal. A rapid change will create a big output from the derivative stage.
The results from the three different stages are added to the stroker output.

The use of PI only is most common.
A system set up with speed feedback (regulated drive) can be switched between regulated and unregulated mode, by means of panel button "REG/UNREG" (or by a remote signal).
Note: In case the difference between the set point and the actual speed is bigger than a pre-set value and remains so for >10 sec. the drive will automatically be set to unregulated mode (but it will keep on running), and "ERROR TO LARGE", will be displayed (a digital output will indicate as well, if set).

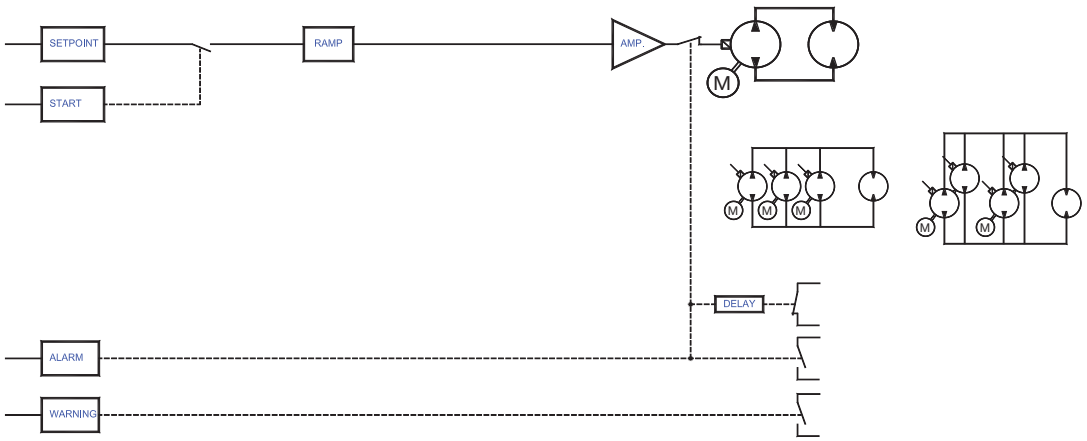
3.8 Power limitation

Power limitation function is not available in the monitor type spider, basic function or higher is needed.
Power limitation requires an analog input signal (voltage or current loop signal) from a current transformer that senses the current of the specific electric motor.

If the current consumption of the electric motor exceeds pre-set limitation value, the output current to the stroker will ramp down (towards zero) until the current consumption of the electric motor decreases below set limitation value which will make the output current to the stroker to ramp up, back to previous value.

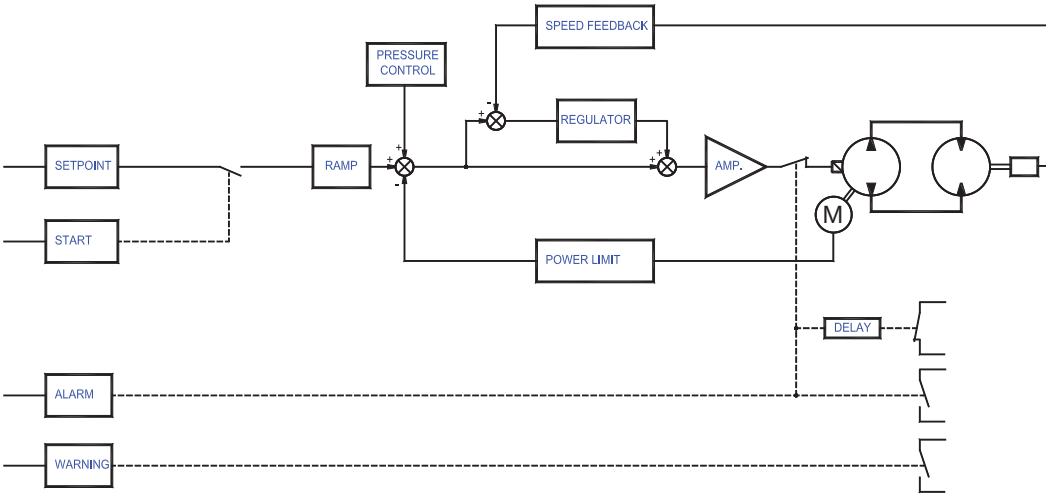
3.9 Monitoring

The Monitor function health monitors the power unit switches and shows information on the text display about warnings or alarms. An alarm will stop the drive (de-stroke the pump) instantly and after a time delay stop the electric motors via the digital interlock output which must be connected to the starter interlock circuit via a relay. Up to 4 pumps can be controlled in parallel for the same drive



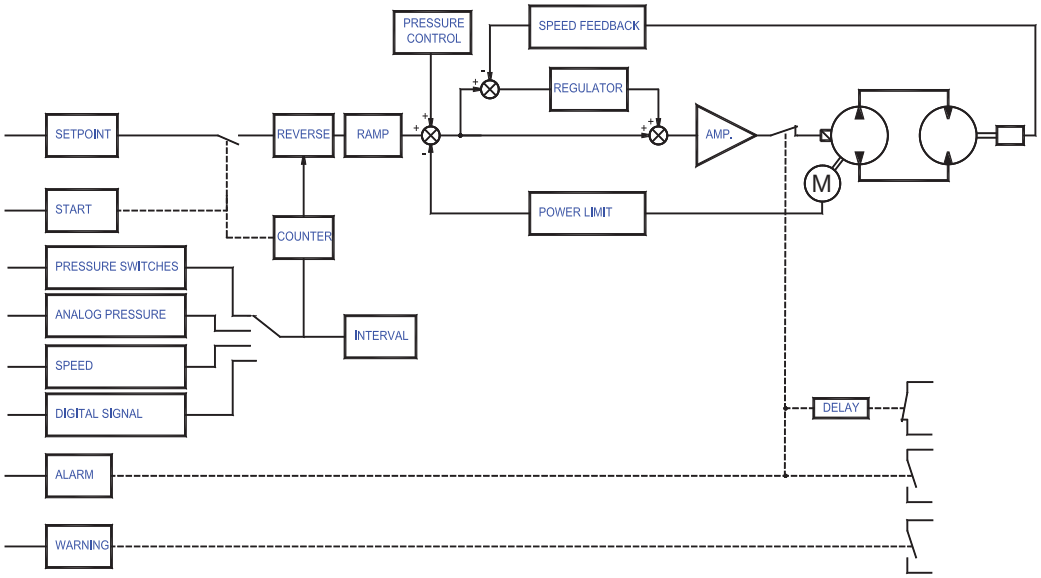
3.10 Basic

The Basic function has added functions for power limitation and closed loop speed feedback via a PID-regulator. Inputs are available for analog or digital speed encoders.
The unit can also monitor analog signals on the display such as speed, E-motor current, pressure etc.



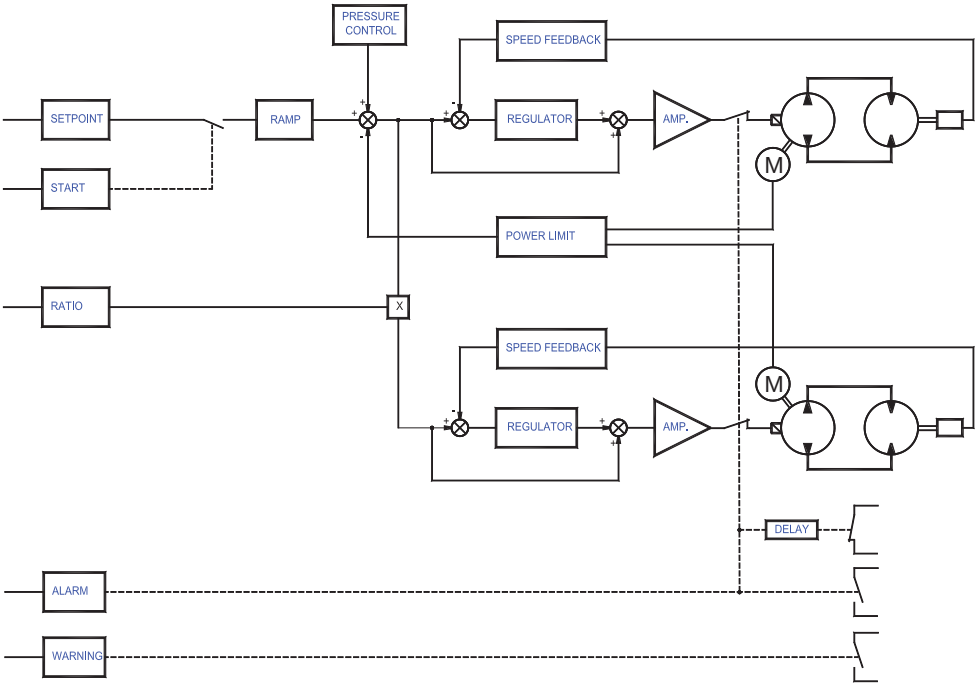
3.11 Shredder

The Shredder function has the same functions as Basic and with added functions for reversing by an overload-stopped drive. It is possible to maximise the number of reversals within a time limit and stop the drive when exceeded. The drive can be set to change direction after an adjustable time interval.



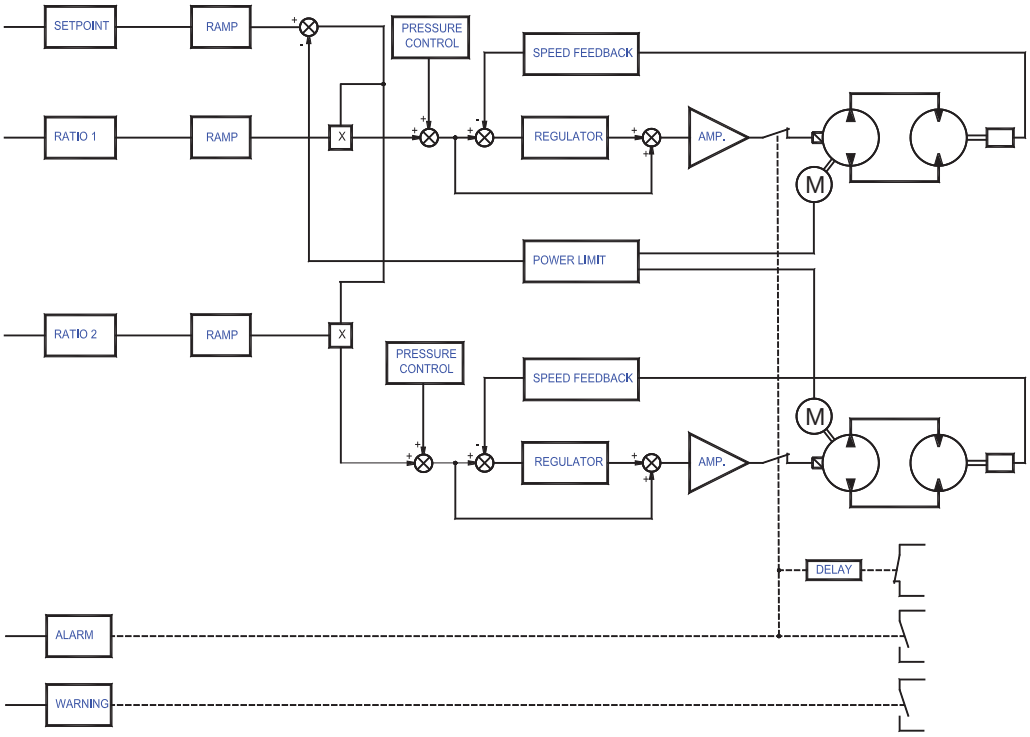
3.12 Friction

The Friction function has the same functions as Basic and with added functions for control of two hydraulic drives driven together with a ratio between the motors.



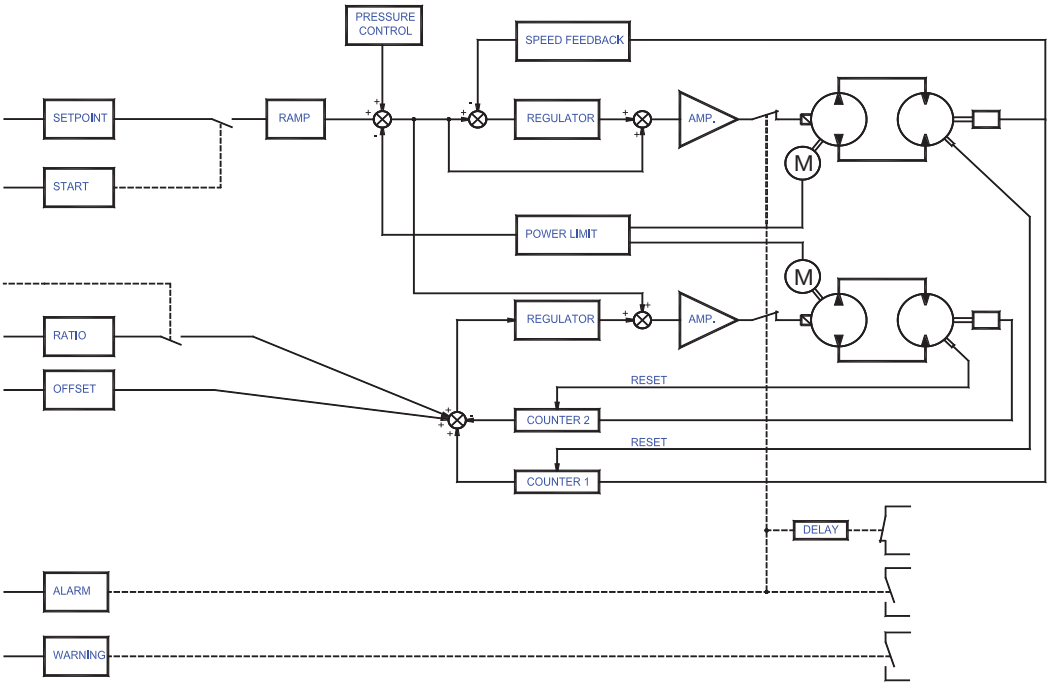
3.13 Friction slave

The Friction slave function has the same functions as Basic and with added functions for control of two hydraulic drives driven together with a ratio in relation to the master set point.



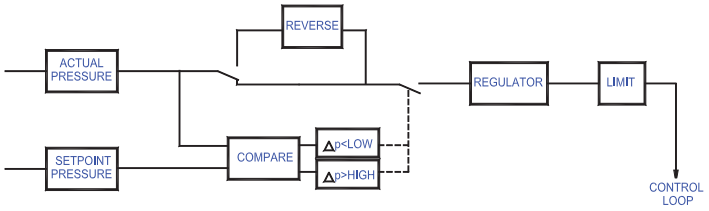
3.14 Synchro

The Synchro function has the same functions as Basic and with added functions for position control between two hydraulic drives. It is possible by an external signal to set the angle between the rolls. Ratio drive is also possible. This mode requires digital speed encoders



3.15 Pressure control

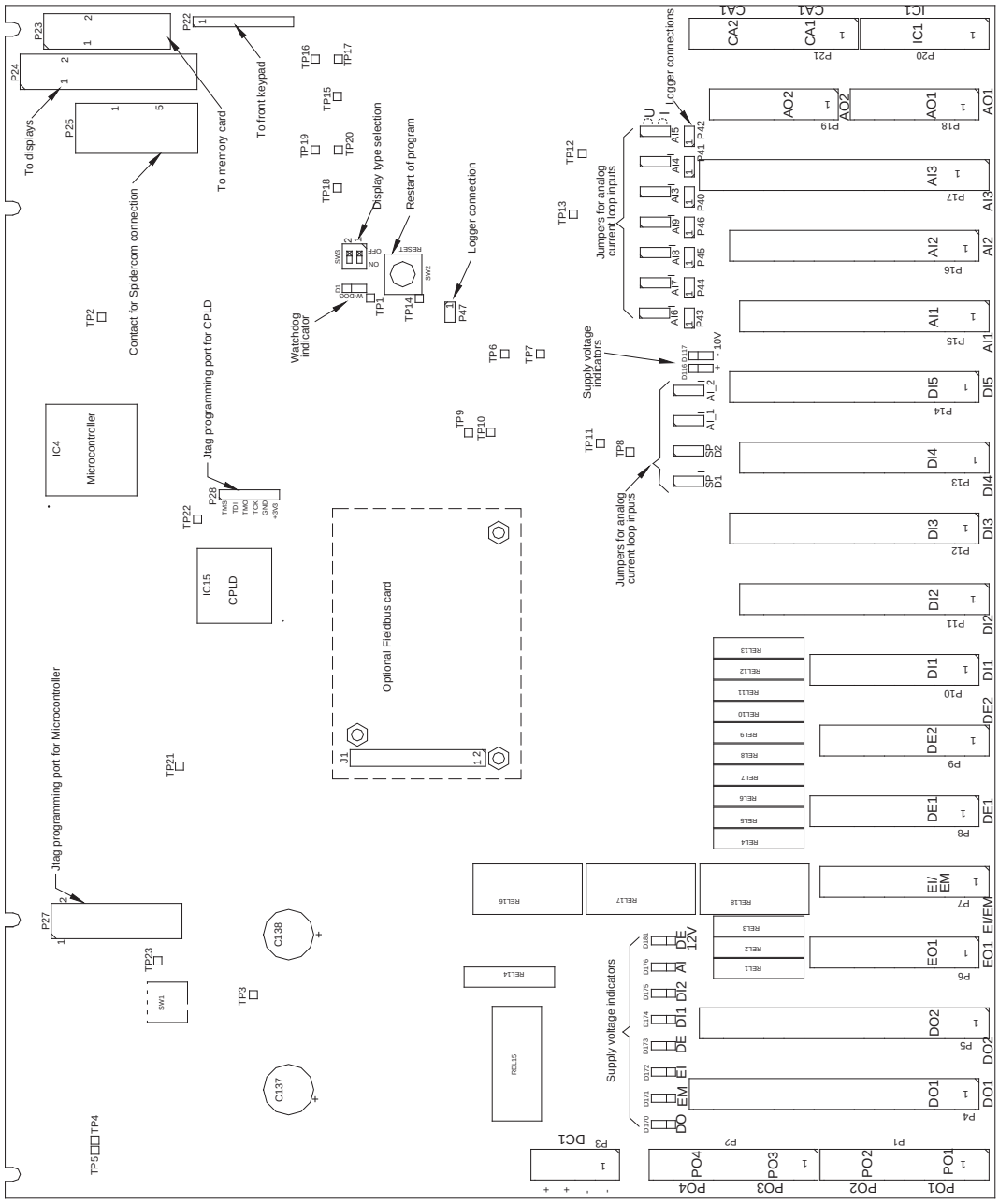
The pressure control function output is added to the ramped flow command. The function compares actual pressure to a set pressure and gives a positive or negative output depending on sign of the difference and action direction of regulation.



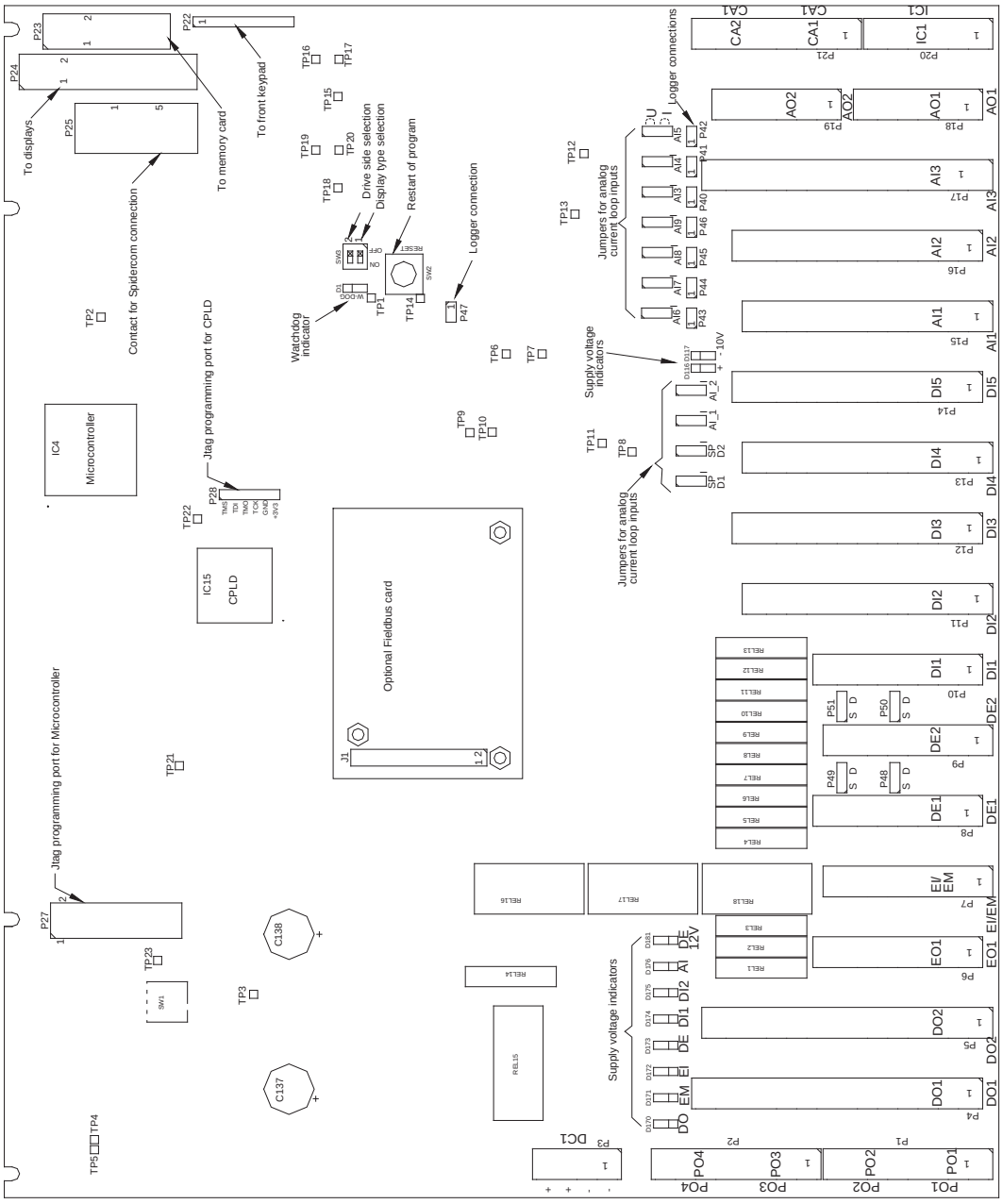
4 MAIN BOARD, JUMPERS & TERMINALS

4.1 Main card jumpers and indications

4.1.1 Revision A



Revision B, C and D



4.1.2 Jumpers

Function	Jumper name	Settings
Signal type for speed setpoint, Drive 1	SP D1	Upper position = voltage signal Lower position = current signal
Signal type for speed setpoint, Drive 2	SP D2	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 1	AI1	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 2	AI2	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 3	AI3	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 4	AI4	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 5	AI5	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 6	AI 6	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 7	AI7	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 8	AI8	Upper position = voltage signal Lower position = current signal
Signal type for configurable analog input 9	AI9	Upper position = voltage signal Lower position = current signal
Switch level selector for pulse 1 on Speed encoder 1	P48	D = Differential pulse encoder S = Single pulse encoder
Switch level selector for pulse 2 on Speed encoder 1	P49	D = Differential pulse encoder S = Single pulse encoder
Switch level selector for pulse 1 on Speed encoder 2	P50	D = Differential pulse encoder S = Single pulse encoder
Switch level selector for pulse 2 on Speed encoder 2	P51	D = Differential pulse encoder S = Single pulse encoder

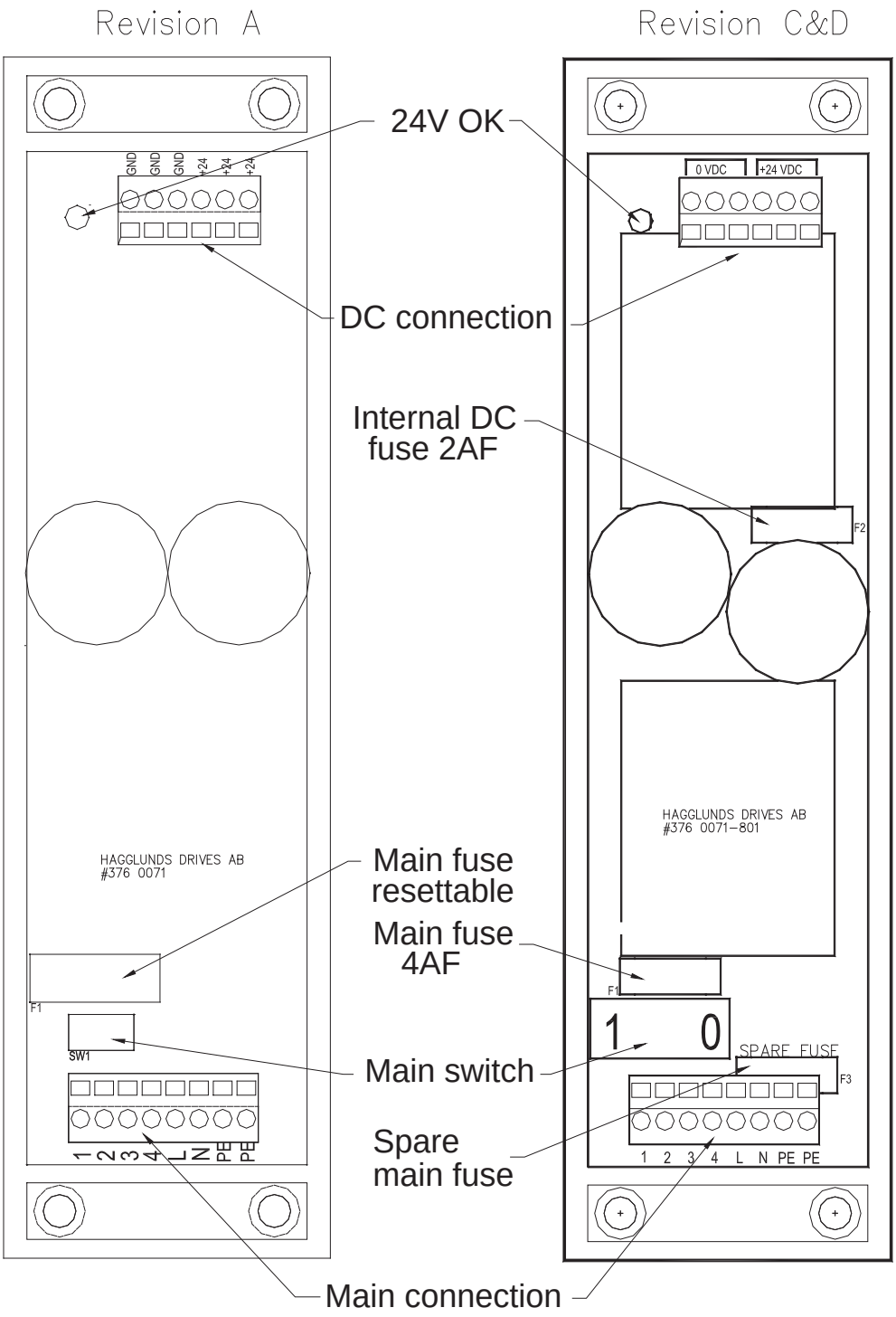
4.1.3 Indicators

Function	Indicator name	Note
Shutdown	D1, red (W-DOG)	Normally off. Will be active by microprocessor watchdog error.
Digital output supply	D170, green (DO)	Normally on. Indicates supply to digital outputs. Will be off by external short circuit or by emergency stop.
Emergency stop supply	D171, green (EM)	Normally on. Will be off by external short circuit
E-motor input supply	D172, green (EI)	Normally on. Will be off by external short circuit
Encoder supply 24V	D173, green (DE)	Normally on. Will be off by external short circuit
Digital input supply 1	D174, green (DI1)	Normally on. Will be off by external short circuit
Digital input supply 2	D175, green (DI2)	Normally on. Will be off by external short circuit
Analog input supply	D176, green (AI)	Normally on. Will be off by external short circuit
Encoder supply 12V	D181, green (DE 12V)	Normally on. Will be off by external short circuit
+10V ref. voltage for potentiometer	D116, green (+10V)	Normally on. Will be off by external short circuit
-10V ref. voltage for potentiometer	D117, green (-10V)	Normally on. Will be off by external short circuit

4.1.4 Switches

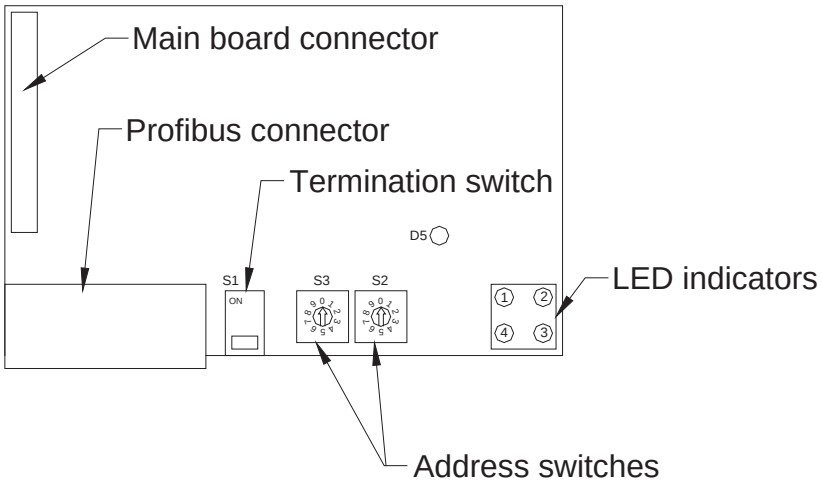
Function	Pot. name	Note
Emergency stop shutdown	SW1	Timer for backup emergency stop shutdown
Display type	SW3-1	On = LCD display type (standard) Off = VFD display type
Drive position on front panel	SW3-2	On = Drive 1 left (standard) Off = Drive 1 right

4.2 Power supply



4.3 Fieldbus card

4.3.1 Profibus



4.3.1.1 Indicators

Indicator name	Description	Function	Information
D1	Not used	Not used	Normal function
D2	On line	Green Off	Module is On-Line and ready, data exchange is possible. Module is not On-Line.
D3	Off line	Red Off	Module is Off-Line. Module is not Off-Line.
D4	Diagnostics	Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz Off	Configuration error. Data length. Configuration error. User parameters. Initialisation error of the Profibus communication ASIC. No error.
D5	Watchdog	Green flashing 1Hz Green flashing 2Hz Red Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz	Initialized and running OK. Not initialised. Unspecified internal error or running in boot loader mode. RAM failure. ASIC or FLASH failure. DPRAM failure.

4.3.1.2 Switches

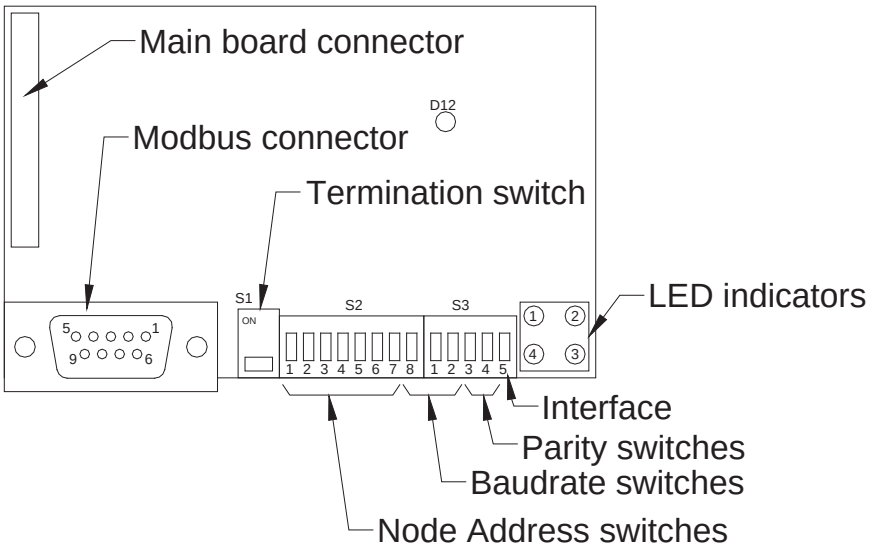
Indicator name	Function	Information
S1	Terminating switch	On= Enabled (if first or last in a network) Off= Disabled
S2	Node Address	x1 for the node address setting
S3	Node Address	x10 for the node address setting

4.3.1.3 Profibus connector (Female 9-pin D-sub)

Pin	Function	Information
Housing	Shield	Connected to PE
1	Not connected	
2	Not connected	
3	B-line	Positive RxD/TxD
4	RTS	Request to send*
5	GND Bus	Isolated from RS485 side*
6	+5V Bus	Isolated from RS485 side*
7	Not connected	
8	A-line	Negative RxD/TxD
9		

* Used for bus termination in special cases. Normally only A-line, B-line and shield are used.

4.3.2 Modbus RTU



4.3.2.1 Indicators

Indicator name	Description	Function	Information
D1	Processing	Green flashing Off	Receiving Query and building response. No Query
D2	Bus error	Red Off	Bus error Normal operation.
D3	Bus ready	Red Off	Module is Off-Line. Module is not Off-Line.
D4	HW setting status	Green Red Off	Bus ready. Normal operation. Bus timeout error. Bus not initialized correctly.
D12	Watchdog	Green flashing 1Hz Green flashing 2Hz Red Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz	Initialized and running OK. Not initialised. Unspecified internal error or running in boot loader mode. RAM failure. ASIC or FLASH failure. DPRAM failure.

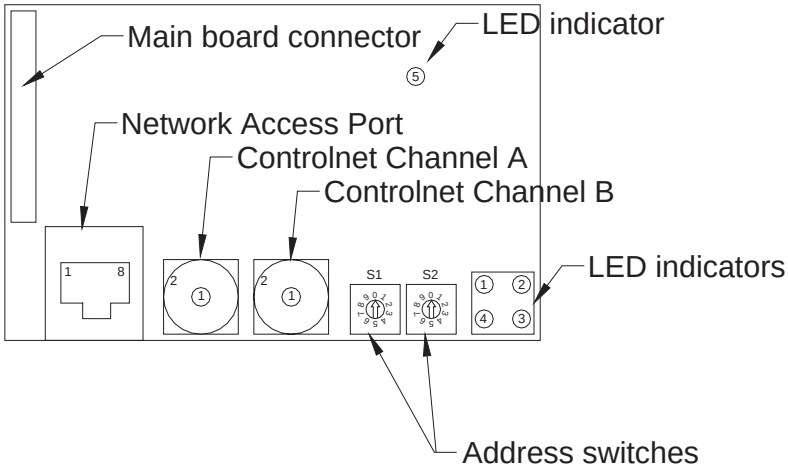
4.3.2.2 Switches

Indicator name	Function	Setting	Information
S1	Terminating switch	On Off	Enabled (if first or last in a network) Disabled
S2: 1-7	Node Address Switch:	Binary value: 1234567 0000000 0000001 0000010 0000011 … … 1111111	 Not valid 1 2 3 … … 127
S2: 8 S3: 1-2	Baud rate Switch:	Binary value: 812 000 001 010 011 100 101 110 111	 Not valid 1200 2400 4800 9600 19200 (Default) 38400 57600
S3: 3-4	Parity Switch:	Binary value: 34 00 01 10 11	 Not valid None(Default) Even Odd
S3:5	Physical interface	0 = RS-485 1 = RS-232	

4.3.2.3 Modbus connector (Female 9-pin D-sub)

Pin	Function	Information
Housing	Shield	Connected to PE
1	Not connected	
2	RS232 - TX	Transmit signal
3	RS232 – RX	Recive signal
4	Not connected	
5	GND Bus	Signal ground
6	+5V Bus	
7	RS485 D0	
8	RS485 D1	
9	Not connected	

4.3.3 ControlNet



Network Access port provides temporary access to the ControlNet network for diagnostics and configuration. ControlNet BNC contacts. If redundant operation is desired both contacts are used otherwise A or B is used

4.3.3.1 Indicators

Indicator name	Description	Function	Information
D1	Module status	Green Green flashing Red Red flashing	Connection in run state Connection idle Major fault Minor fault
D2	ChannelA and ChannelB	Off Red Alternating red/green Red flashing	Module not initialized Major fault Self test Node configuration error, duplicate MAC ID etc.
D3	ChannelA or ChannelB	Off Green Green flashing Red flashing Red & Green flashing	Channel disabled Normal operation of channel Temporary error (node will self correct) or not configured No other nodes or media fault Network configuration error
D4	Module owned	Off Green	No connection has been opened A connection has been opened towards the module

D5	Watchdog	Green flashing 1Hz	Initialized and running OK.
		Green flashing 2Hz	Not initialised.
		Red	Unspecified internal error or running in boot loader mode.
		Red flashing 1 Hz	RAM failure.
		Red flashing 2 Hz	ASIC or FLASH failure.
		Red flashing 4 Hz	DPRAM failure.

4.3.3.2 Switches

Indicator name	Function	Setting	Information
S1	Node Address	x10 for the node address setting	Node Address
S2	Node Address	x1 for the node address setting	Node Address

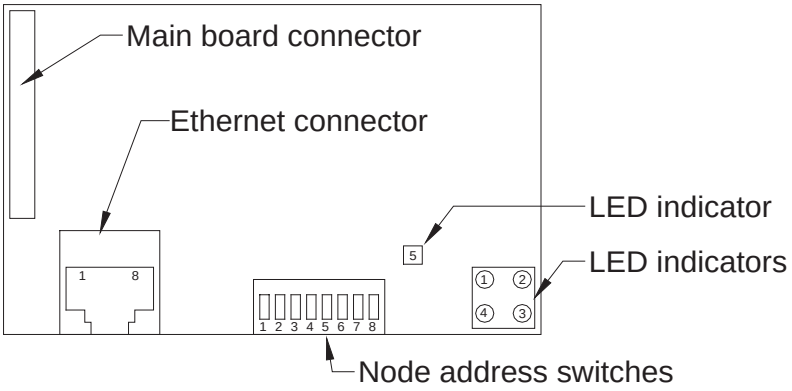
4.3.3.3 ControlNet connector (BNC)

Pin	Function	Information
1	ControlNet	Tip
2	Shield	Ring

4.3.3.4 Network connector (RJ45)

Pin	Function	Information
1	GND	
2	Not connected	Transmit signal
3	Tx_H	Transmit data, positive
4	Tx_L	Transmit data, negative
5	Rx_L	Receive data, negative
6	Rx_H	Receive data, positive
7	Not connected	
8	Shield	Connected to PE

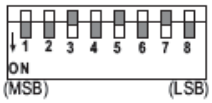
4.3.4 Ethernet/IP



4.3.4.1 Indicators

Indicator name	Description	Function	Information
D1	Link Activity	Off Green	Link not sensed Link sensed
D2	Module Status	Off Green Green, flashing Red flashing Red Alternating green/red	No power Controlled by scanner in run mode Not configured, or Scanner in idle state A minor recoverable fault has been detected A major unrecoverable fault has been detected Self test in process
D3	Network Status	Off Green Green, flashing Red Red, flashing Alterning Green/Red	No power or IP address Online, one or more connections established. Online, no connections established Duplicate IP address, fatal error One or more connections timed out Self test in progress
D4	Activity	Green, flashing	Flashes each time a packet is received or transmitted
D5	Watchdog	Green flashing 1Hz Green flashing 2Hz Red Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz	Initialized and running OK. Not initialised. Unspecified internal error or running in boot loader mode. RAM failure. ASIC or FLASH failure. DPRAM failure.

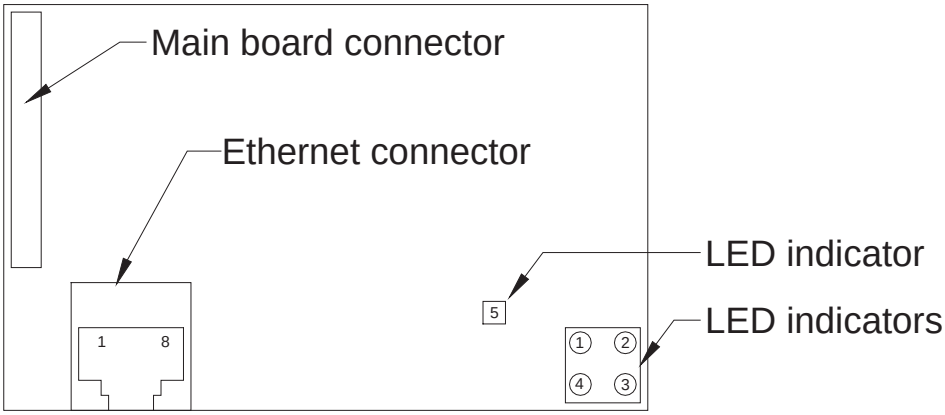
4.3.4.2 Switches

Switch name	Function	Setting
Node address 	IP address: 192.168.0.x (x = Binary value) Gateway: 255.255.255.0 Subnet: 255.255.255.0 DHCP: OFF	Binary value: 0000001 - 192.168.0.1 0000011 - 192.168.0.3 … 1111111- 192.168.0.255

4.3.4.3 Ethernet connector (RJ45)

Pin	Function	Information
1	TD+	
2	TD-	
3	RD+	
4	Termination	
5	Termination	
6	RD-	
7	Termination	
8	Termination	

4.3.5 ProfiNet



4.3.5.1 Indicators

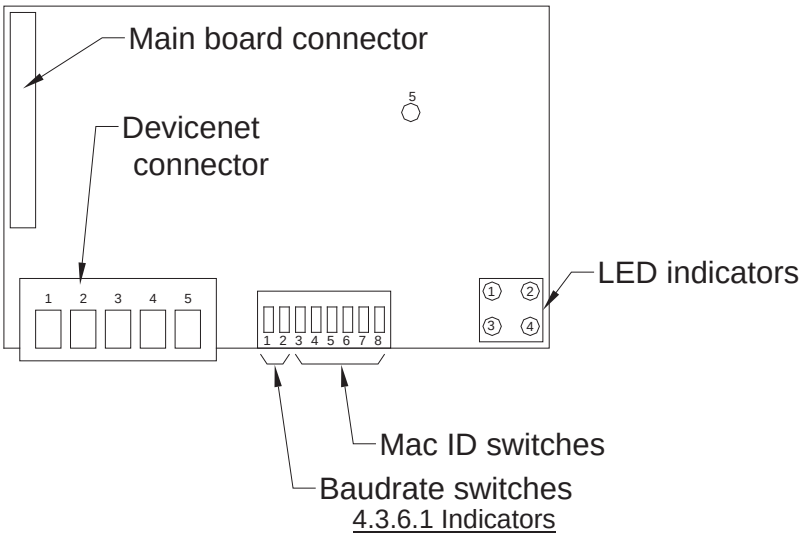
Indicator name	Description	Function	Information
D1	Link (Activity)	Off Green, flashing Green	No link Receiving/Transmitting data Link established
D2	Communication status	Off Green Green 1 flash	Off line Connection established and controller in RUN state Connection established and controller in STOP state
D3	Module status	Off Green Green 1 flash Green 2 flashes Red 1 flash Red 3 flashes Red 4 flashes	No power or not initialized Initialized, no error Diagnostic data available Blink. Used by engineering tool to identify module Configuration error -Too many modules -I/O size derived from controller too large -Configuration mismatch No station address or IP address assigned Internal error

D4	Not used		
D5	Watchdog	Green flashing 1Hz	Initialized and running OK.
		Green flashing 2Hz	Not initialised.
		Red	Unspecified internal error or running in boot loader mode.
		Red flashing 1 Hz	RAM failure.
		Red flashing 2 Hz	ASIC or FLASH failure.
		Red flashing 4 Hz	DPRAM failure.

4.3.5.2 ProfiNet connector (RJ45)

Pin	Function	Information
1	TD+	
2	TD-	
3	RD+	
4	Termination	
5	Termination	
6	RD-	
7	Termination	
8	Termination	

4.3.6 DeviceNet



4.3.6.1 Indicators

Indicator name	Description	Function	Information
D1	Not used		
D2	Network status	Off Green Green flashing Red steady Red flashing	Not powered/Not online Link OK, Online, Connected On line, Not connected Critical link failure Connection timeout
D3	Module status	Off Green Green flashing Red steady Red flashing	No power to device Device operational Data size bigger than configured Unrecoverable fault Minor fault
D4	Not used		
D5	Watchdog	Green flashing 1Hz Green flashing 2Hz Red Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz	Initialized and running OK. Not initialised. Unspecified internal error or running in boot loader mode. RAM failure. ASIC or FLASH failure. DPRAM failure.

4.3.6.2 Switches

Baud rate:

Baud rate	Sw1	Sw2	Information
125kbit/sec	OFF	OFF	
250kbit/sec	OFF	ON	
500kbit/sec	ON	OFF	
Reserved	ON	ON	

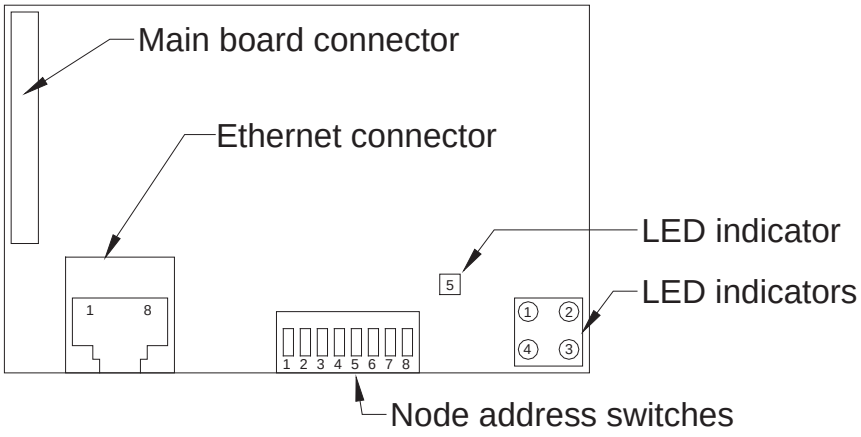
Node address:

Mac ID	Sw 3 (MSB)	Sw 4	Sw 5	Sw 6	Sw 7	Sw8 (LSB)
0	OFF	OFF	OFF	OFF	OFF	OFF
1	OFF	OFF	OFF	OFF	OFF	ON
2	OFF	OFF	OFF	OFF	ON	OFF
3	OFF	OFF	OFF	OFF	ON	ON
…	…	…	…	…	…	…
62	ON	ON	ON	ON	ON	OFF
63	ON	ON	ON	ON	ON	ON

4.3.6.3 DeviceNet connector (Pluggable screw type)

Pin	Function	Information
1	V-	Negative supply (0VDC)
2	CAN_L	CAN-L bus line
3	Shield	Cable shield
4	CAN_H	CAN-H bus line
5	V+	Positive supply (+24VDC)

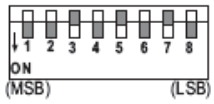
4.3.7 Modbus TCP



4.3.7.1 Indicators

Indicator name	Description	Function	Information
1	Link Activity	Off Green	Link not sensed Link sensed
2	Module Status	Off Green flashing 1Hz Red flashing 1Hz Red flashing 2Hz Red flashing 4Hz Red	No power IP address not set using switch Invalid MAC address Failed to load config. from FLASH Internal error (fatal) Duplicate IP address detected
3	Established connections		Established connections to the module is equal to the number of flashes
4	Activity	Green, flashing	Flashes each time a packet is received or transmitted
5	Watchdog	Green flashing 1Hz Green flashing 2Hz Red Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz	Initialized and running OK. Not initialised. Unspecified internal error or running in bootloader mode. RAM failure. ASIC or FLASH failure. DPRAM failure.

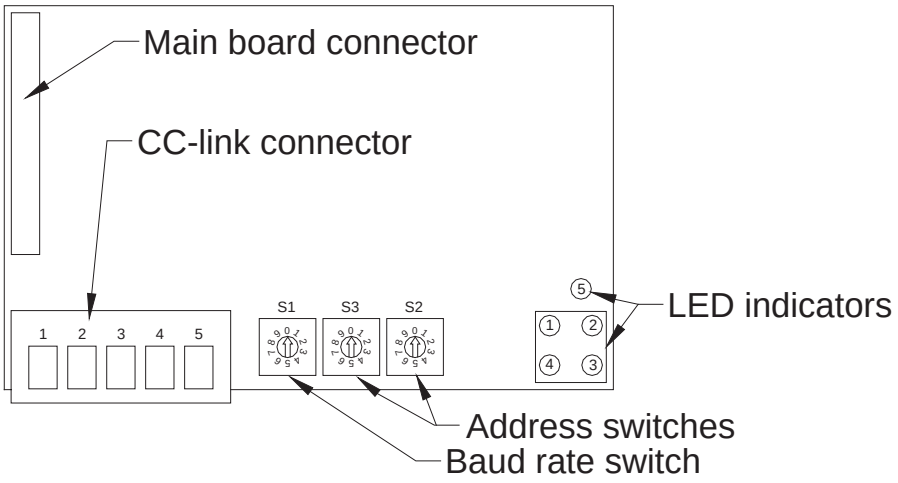
4.3.7.2 Switches

Switch name	Function	Setting
Node address  	IP address: 192.168.0.x (x = Binary value) Gateway: 255.255.255.0 Subnet: 255.255.255.0 DHCP: OFF	Binary value: 0000001 - 192.168.0.1 0000011 - 192.168.0.3 … 1111111- 192.168.0.255

4.3.7.3 Modbus TCP connector (RJ45)

Pin	Function	Information
1	TD+	
2	TD-	
3	RD+	
4		Normally left unused. Internally tied
5		Together and terminated to PE
6	RD-	
7		Normally left unused. Internally tied
8		Together and terminated to PE

4.3.8 CC-link



4.3.8.1 Indicators

Indicator name	Description	Function	Information
D1	RUN	On Off	Normal operation No network connection or Timeout
D2	ERRL	Red Off	CRC error detected Illegal station number Illegal baud rate Normal operation
D3	RDLED	Green Off	Data being received No data reception
D4	SDLED	Green Off	Data being transmitted No data transmission
D5	Watchdog	Green flashing 1Hz Green flashing 2Hz Red Red flashing 1 Hz Red flashing 2 Hz Red flashing 4 Hz	Initialized and running OK. Not initialised. Unspecified internal error or running in boot loader mode. RAM failure. ASIC or FLASH failure. DPRAM failure.

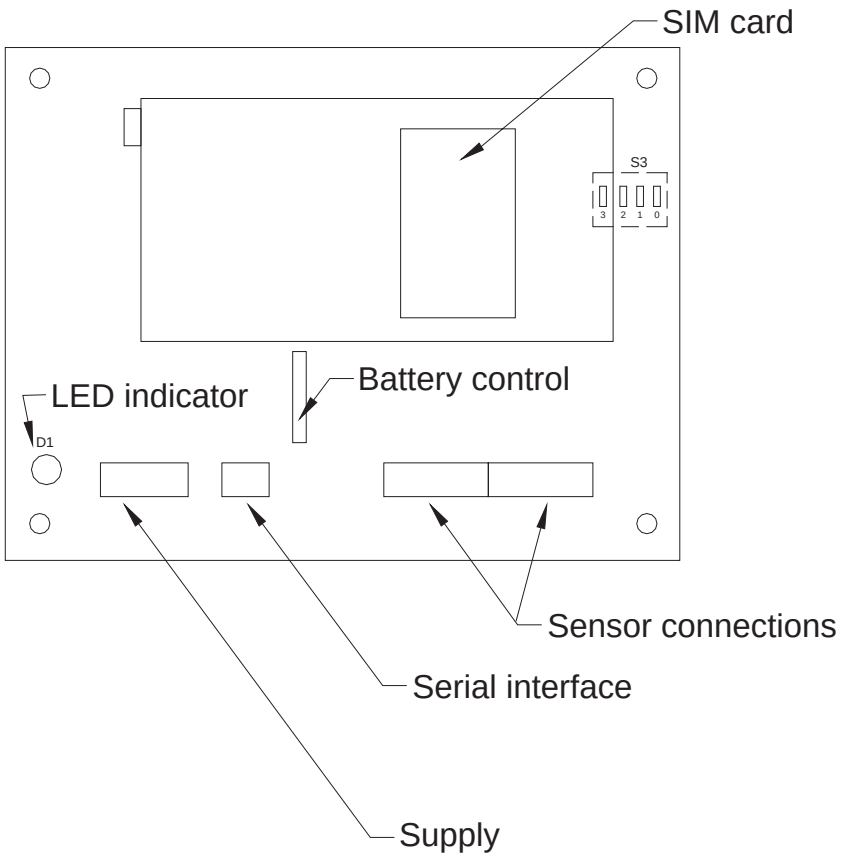
4.3.8.2 Switches

Indicator name	Function	Information
S1	Baud rate switch	0 = 156k 1 = 625k 2 = 2,5M 3 = 5M 4 = 10M 9 = FB_INIT
S2	Node Address	x1 for the node address setting
S3	Node Address	x10 for the node address setting

4.3.8.3 CC-link connector (Pluggable screw type)

Pin	Function	Information
1	DA	Communication line
2	DB	Communication line
3	DG	Digital ground
4	Shield	
5	FG/PE	Frame ground

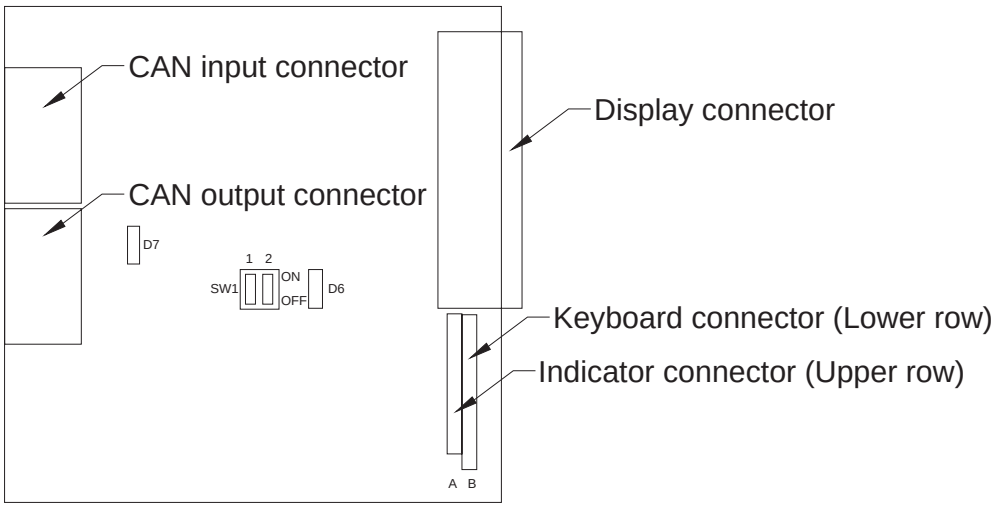
4.4 RMS card



4.4.1 Indicators

Indicator name	Function	Information
D1	Green	Normal function
	Red	No communication with the modem or SIM card
	Blink each 4 sec	Logging in action
	Blink each 8 sec	No logging in action
	2 green blink followed by 2 red blink after 4 sec	Program reset

4.5 LIC card



4.5.1 Indicators

Indicator name	Description	Function	Information
D6	Power	Green	Normal operation, Power OK
D7	Operate	Green 2Hz	Normal operation

4.5.2 Switches

Indicator name	Function	Information
SW1-1	Drive selection	On = One LIC card is used (Jumpered contact must be connected in CAN output connector) Off = Card used for drive 2
SW1-2	Not used	

4.6 Terminal functions

Table of terminal functions.

Row	*Type*	*Name*	*No.*	*Function*
1	**Power Input**	DC1	4	24V_IN (+)
			3	24V_IN (+)
			2	GND (-)
			1	GND(-)
	Pump 4	PO4	4	Common pump 4
			3	Stroker conn. Pump 4. High B
			2	Common pump 4
			1	Stroker conn. Pump 4. High A
	Pump 3	PO3	4	Common pump 3
			3	Stroker conn. Pump 3. High B
			2	Common pump 3
			1	Stroker conn. Pump 3. High A
	Pump 2	PO2	4	Common pump 2
			3	Stroker conn. Pump 2. High B
			2	Common pump 2
			1	Stroker conn. Pump 2. High A
	Pump 1	PO1	4	Common pump 1
			3	Stroker conn. Pump 1. High B
			2	Common pump 1
			1	Stroker conn. Pump 1. High A
2	**Digital outputs**	DO1	14	Configurable Digital output 6
			13	Configurable Digital output 6
			12	Configurable Digital output 5
			11	Configurable Digital output 5
			10	Configurable Digital output 4
			9	Configurable Digital output 4
			8	Configurable Digital output 3
			7	Configurable Digital output 3
			6	Configurable Digital output 2
			5	Configurable Digital output 2
			4	Configurable Digital output 1
			3	Configurable Digital output 1
			2	24V_DO
			1	GND

Row	*Type*	*Name*	*No.*	*Function*
3	**Digital outputs**	DO2	14	Configurable Digital output 13
			13	Configurable Digital output 12
			12	Configurable Digital output 11
			11	Common Digital output 11-13
			10	Configurable Digital output 10
			9	Configurable Digital output 10
			8	Configurable Digital output 9
			7	Configurable Digital output 9
			6	Configurable Digital output 8
			5	Configurable Digital output 8
			4	Configurable Digital output 7
			3	Configurable Digital output 7
			2	24V_DO
			1	GND
4	**E-motor interlocks**	EO1	8	Interlock Electric motor 3
			7	Interlock Electric motor 3
			6	Interlock Electric motor 2
			5	Interlock Electric motor 2
			4	Interlock Electric motor 1
			3	Interlock Electric motor 1
			2	24V_DO
			1	GND
5	**E-motor started inputs**	EI	8	E-motor 3 started
			7	E-motor 2 started
			6	E-motor 1 started
			5	24V_EI
			4	24V_EI
			3	GND
	Em stop	EM	2	Em.stop
			1	24V_EM
6	**Digital speed encoder Drive 1**	DE1	8	Pulse 0 Drive 1+
			7	Pulse 2 Drive 1 -
			6	Pulse 2 Drive 1+
			5	Pulse 1 Drive 1 -
			4	Pulse 1 Drive 1+
			3	12V+
			2	24V_DE
			1	GND
7	**Digital speed encoder Drive 2**	DE2	8	Pulse 0 Drive 2+
			7	Pulse 2 Drive 2 -
			6	Pulse 2 Drive 2+
			5	Pulse 1 Drive 2 -
			4	Pulse 1 Drive 2+
			3	12V+
			2	24V_DE
			1	GND

Row	Type	Name	No.	Function
8	**Configurable digital inputs** Predefined monitoring inputs	DI1	8	Config input 6 (Drain filter)
			7	Config input 5 (Low oil level in tank)
			6	Config input 4 (Min oil level in tank)
			5	Config input 3 (Min oil temperature in tank)
			4	Config input 2 (High oil temperature in tank)
			3	Config input 1 (Max oil temperature in tank)
			2	24V_DI_1
			1	GND
9	**Configurable digital inputs** Predefined monitoring inputs	DI2	12	Config input 15
			11	Config input 14 (Work pressure, pump 2)
			10	Config input 13 (Charge pressure, pump 2)
			9	Config input 12 (Suction line, pump 2)
			8	Config input 11 (Return filter 100%, pump 2)
			7	Config input 10 (Work pressure, pump 1)
			6	Config input 9 (Charge pressure, pump 1)
			5	Config input 8 (Suction line, pump 1)
			4	Config input 7 (Return filter 100%, pump 1)
			3	24V_DI_1
			2	24V_DI_1
			1	GND
10	**Configurable digital inputs** Predefined monitoring inputs	DI3	12	Config input 24
			11	Config input 23 (Work pressure, pump 4)
			10	Config input 22 (Charge pressure, pump 4)
			9	Config input 21 (Suction line, pump 4)
			8	Config input 20 (Return filter 100%, pump 4)
			7	Config input 19 (Work pressure, pump 3)
			6	Config input 18 (Charge pressure, pump 3)
			5	Config input 17 (Suction line, pump 3)
			4	Config input 16 (Return filter 100%, pump 3)
			3	24V_DI_1
			2	24V_DI_1
			1	GND
11	**Configurable digital inputs**	DI4	12	Config input 33
			11	Config input 32
			10	Config input 31
			9	Config input 30
			8	Config input 29
			7	Config input 28
			6	Config input 27
			5	Config input 26
			4	Config input 25
			3	24V_DI_2
			2	24V_DI_2
			1	GND

Row	*Type*	*Name*	*No.*	*Function*
12	**Configurable digital inputs**	DI5	12	Config input 43
			11	Config input 42
			10	Config input 41
			9	Config input 40
			8	Config input 39
			7	Config input 38
			6	Config input 37
			5	Config input 36
			4	Config input 35
			3	Config input 34
			2	24V_DI_2
			1	GND
13	**Analog inputs Isolated**	AI1	12	Config input 2 -
			11	Config input 2+
			10	Config input 1 -
			9	Config input 1+
			8	Remote speed set point Drive 2 -
			7	Remote speed set point Drive 2 +
			6	Remote speed set point Drive 1 -
			5	Remote speed set point Drive 1 +
			4	Isolated 10VREF -
			3	Isolated 10VREF+
			2	Isolated GND
			1	Isolated GND
14	**Analog inputs Not isolated**	AI2	12	Config input 6 -
			11	Config input 6+
			10	Config input 5 -
			9	Config input 5+
			8	Config input 4 -
			7	Config input 4+
			6	Config input 3 -
			5	Config input 3+
			4	24V_AI
			3	24V_AI
			2	GND
			1	GND

Row	*Type*	*Name*	*No.*	*Function*
15	**Analog inputs** **Not isolated**	AI3	14	Tank temp, force low
			13	Tank temp, sense low
			12	Tank temp, sense high
			11	Tank temp, force high
			10	Config input 9 -
			9	Config input 9+
			8	Config input 8 -
			7	Config input 8+
			6	Config input 7 -
			5	Config input 7+
			4	24V_AI
			3	24V_AI
			2	GND
			1	GND
16	**Analog outputs**	AO2	6	Current output 4
			5	Voltage output 4
			4	Current output 3
			3	Voltage output 3
			2	24VDC external supply. Internally supplied from revB
			1	GND (external)
		AO1	6	Current output 2
			5	Voltage output 2
			4	Current output 1
			3	Voltage output 1
			2	24VDC external supply. Internally supplied from revB
			1	GND (external)
17	**CAN1**	CA	8	CAN2 H
			7	CAN2 L
			6	+24V CAN
			5	0V
	CAN2		4	CAN1 H
			3	CAN1 L
			2	+24V CAN
			1	0V
	Spare terminals	IC	6	For interconnection purpose
			5	For interconnection purpose
			4	For interconnection purpose
			3	For interconnection purpose
			2	For interconnection purpose
			1	For interconnection purpose

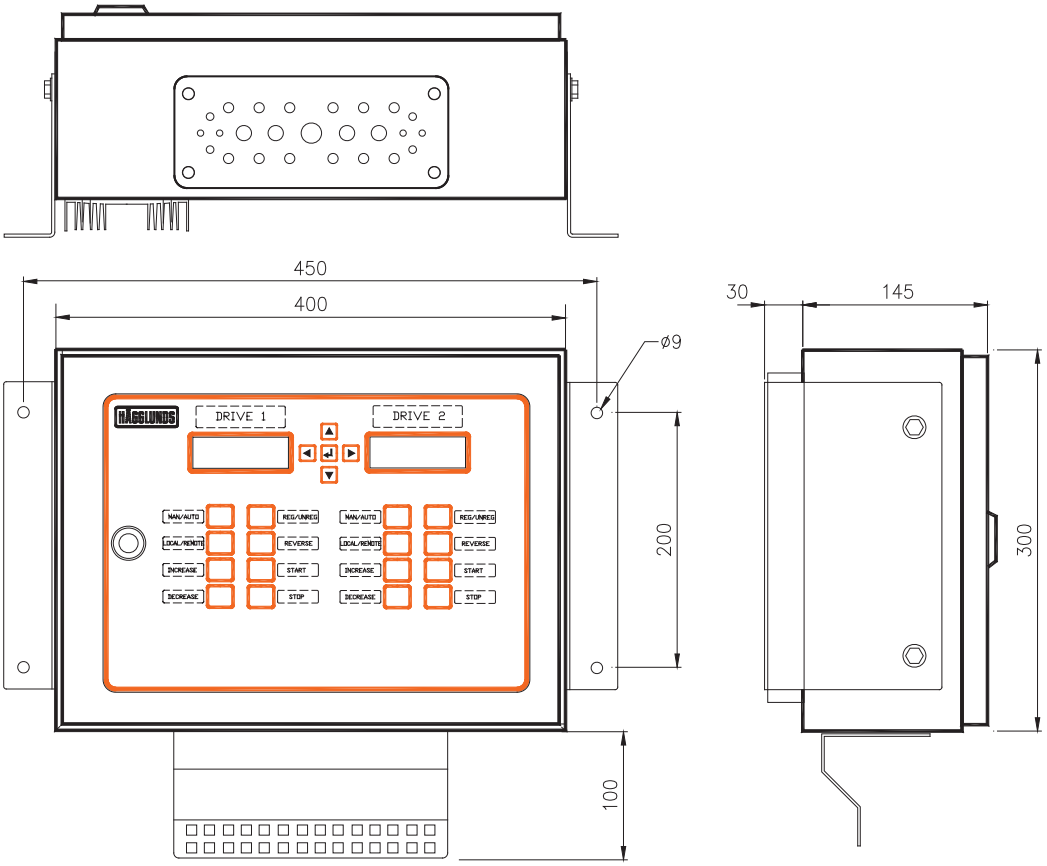
5 TECHNICAL DATA
5.1 Mechanical

5.1.1 Mechanical data

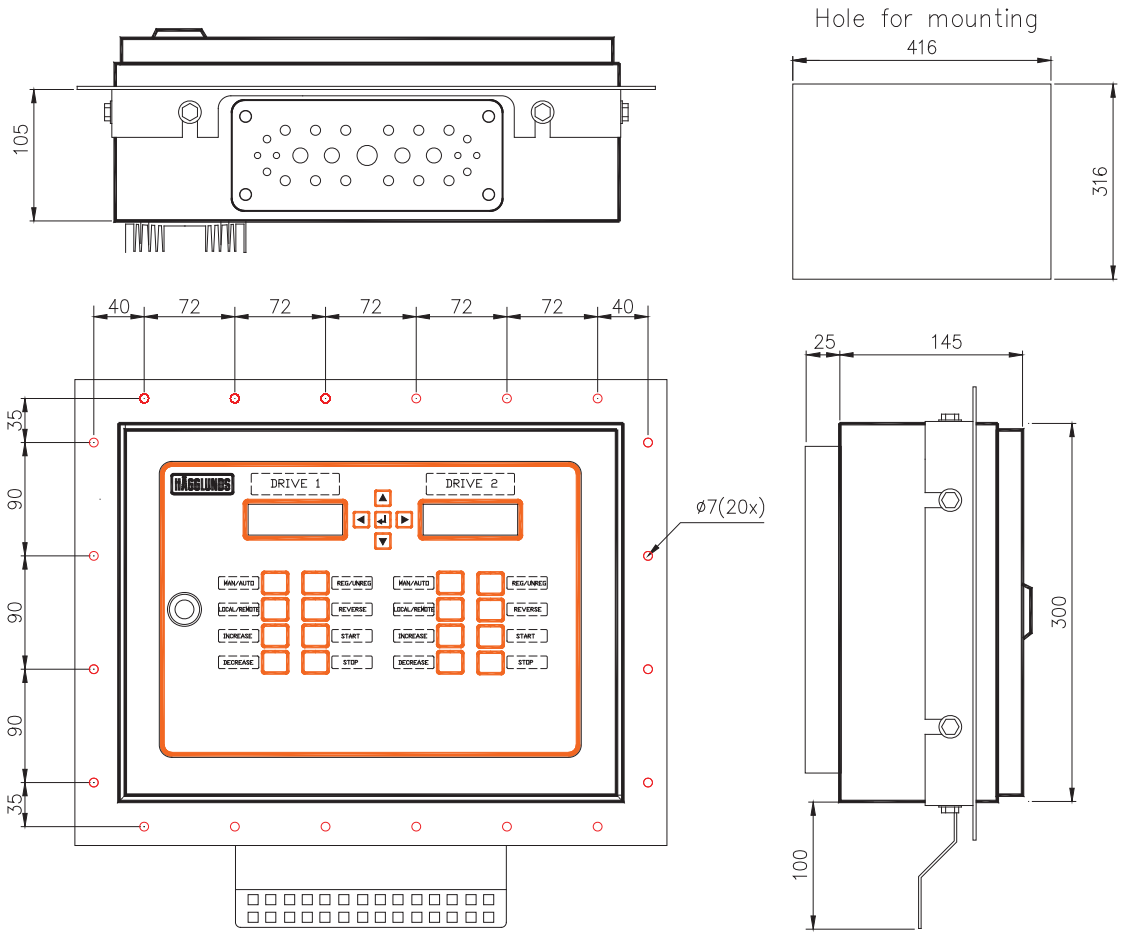
Cubicle dimension	W=400mm H=300mm D=145mm
Encapsulation class	IP 65
Ambient temperature	-20...+50 °C, -40 °C with heater *
Material enclosure	Stainless steel
Material front	Polyester film
Mounting	Wall brackets or flange
Weight	8kg (10kg with brackets or flange)
Cable size	Max 2.5mm²

* Heater supplied as option

5.1.2 Wall bracket mounting



5.1.3 Flange mounting



5.1.4 Polyester front

Chemical resistance to:

- Alcohols
- Dilute acids
- Dilute alkalis
- Esters
- Hydrocarbons
- Ketones
- Household cleaning agents

5.2 Supply and output voltage

5.2.1 Supply voltage

Embedded AC power supply

Main supply voltage	Autoranging 90-132, 180-264 VAC 47-63Hz (No configuration needed)
Power consumption	Max 300VA, Depending on configuration (+50VA with heater)*
Inrush current	Max 30A
Main fuse	6A
Fuses ,Rev B supply Main Internal DC	 4A fast, 5x20mm ceramic, R939004821 (576 6822-400) 2A fast, 5x20mm ceramic, R939004820 (576 6822-200)

* Heater supplied as option

External DC power supply

Card supply	24VDC±10% , Max 8A Depending on configuration
Card consumption (without Load)	320mA

5.2.2 Output voltage

Analog reference voltage (isolated)	+10V -10V	+10VDC 35mA -10VDC 35mA
Digital input supply 1	DI1	+24VDC 0.3A
Digital input supply 2	DI2	+24VDC 0.3A
Digital encoder supply	DE	+24VDC 0.3A
Digital encoder supply	12_DE	+12VDC 0.1A
Analog input supply	AI	+24VDC 0.3A
Emergency stop supply	EM	+24VDC 0.3A
Digital output supply	DO	+24VDC 0.8A
E-motor started supply	EI	+24VDC 0.3A

5.3 Inputs

5.3.1 Analog inputs

No	Description	Type	Impedance
1	Speed set point Drive 1 or Friction set point Drive 1 (isolated)	±0-5VDC ±0-10VDC ±4-20mA ±0-20mA	100kΩ 100kΩ 250Ω 250Ω
1	Speed set point Drive 2 or Friction set point Drive 2 (isolated)	±0-5VDC ±0-10VDC ±4-20mA ±0-20mA	100kΩ 100kΩ 250Ω 250Ω
2	Configurable analog inputs (isolated)	+0-5VDC +0-10VDC +4-20mA +0-20mA	100kΩ 100kΩ 250Ω 250Ω
7	Configurable analog inputs (differential)	+0-5VDC +0-10VDC +4-20mA +0-20mA	100kΩ 100kΩ 250Ω 250Ω
1	Tank temp input, -29...+107 ºC	PT100	

5.3.2 Digital inputs

No	Description	Type	Impedance	Max input
1	Digital speed feedback Drive 1 Differential or single with direction signal	logical 0=0-3,9VDC logical 1=6,6-32VDC		f max 10 kHz
1	Zero position input Drive 1	logical 0=0-3,9VDC logical 1=6,6-32VDC		
1	Digital speed feedback Drive 2 Differential or single with direction signal	logical 0=0-3,9VDC logical 1=6,6-32VDC		f max 10 kHz
1	Zero position input Drive 2	logical 0=0-3,9VDC logical 1=6,6-32VDC		
1	Electric motor 1 started from starter unit	logical 0=0-3,9VDC logical 1=6,6-32VDC	1kΩ	
1	Electric motor 2 started from starter unit	logical 0=0-3,9VDC logical 1=6,6-32VDC	1kΩ	
1	Electric motor 3 started from starter unit	logical 0=0-3,9VDC logical 1=6,6-32VDC	1kΩ	
43	Configurable inputs	logical 0=0-3,9VDC logical 1=6,6-32VDC	3kΩ	
1	Emergency stop input	logical 0=0-4,7VDC logical 1=8,0-32VDC	3kΩ	

5.4 Outputs

5.4.1 Pump control

No	Description	Type	Impedance	Max output
4	Stroker output, dual coil	PWM (Pulse width modulated)	5-100Ω**	2A*

*Total current for all outputs 5A
**Max output reduced above 10Ω to 20/Impedance (A)

5.4.2 Digital outputs

No	Description	Type	Max load
1	Starter interlock E-motor 1	Relay contact	3A, 30VDC, 250VAC
1	Starter interlock E-motor 2	Relay contact	3A, 30VDC, 250VAC
1	Starter interlock E-motor 3	Relay contact	3A, 30VDC, 250VAC
13	Configurable outputs	Relay contact	3A, 30VDC, 250VAC

5.4.3 Analog outputs

No	Description	Type	Max load
4	Configurable analog outputs (isolated, needs external supply, min.21,0VDC)	+0-10VDC +2-10VDC +0-20mA +4-20mA	1kΩ 1kΩ 500Ω 500Ω

5.5 Communication

5.5.1 PC connection

No	Description	Type	Connection to PC
1	RS-232 connection for setup and drive log download	9-pole male D-sub	Null modem cable

5.5.2 Fieldbus connection

No	Description	Type	Connection
1	Connection for fieldbus module (optional module)	Profibus Modbus RTU ControlNet EtherNet IP ProfiNet DeviceNet Modbus TCP CC-link	

5.5.3 CAN connection

No	Description	Type	Connection
2	CAN connection for local system communication	4-pin Terminal	To LIU (Local Interface Unit)

6 MAINTENANCE

6.1 General maintenance

The Spider control system needs only minor maintenance. It is important to keep the inside and outside of Spider box tidy. Avoid excessive exposure to water, vapour and other materials that can cause short circuit, corrosion or abrasive wear.

6.2 Recommeded scheduled service

Inside the Spider box is mounted a VpCI emitter (Vapor phase Corrosion Inhibitor) to protect against oxidation. The emitter contains a pulverous substance and covers all components with a protective layer when the air inside the enclosure is saturated. Life time after installation is two years, expiry date is shown on sticker beside the installed emitter. Item number for the emitter is R978980579 (1241 0001-001).

6.3 Available spare parts

Main circuit board, power supply and displays are some of the key spare parts available in case of a break down. Only trained personnel should perform repairs of the Spider. Contact your reseller for more information of repairs.

Hägglunds Spider Control System

Declaration of conformity

Declaration of Conformity
ACC. TO EC COUNCIL DIRECTIVES
2006/95/EC and 2004/108/EC

HÄGGLUNDS Rexroth Bosch Group

Manufacturer's name:	**Hägglunds Drives AB** **Bosch Rexroth**
Manufacturer's address:	**S-895 80 Mellansel** **Sweden**
Contact Name:	**Frank Nagel**
Product Description:	**SpiderII Control System**

We hereby declare that the products specified above, has been designed and manufactured in accordance with the EC Council Low Voltage Directive 2006/95/EC and the EC Council EMC Directive 2004/108/EC.

Signed: .....

Name and title: **Frank Nagel** **Director R&D**

Date: **2012-04-11**

euemc spider ii en 2012-04-11.doc

Notes