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Double clamping arm provided by customer

ROEMHELD HILMA STARK

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Swing Clamps with Reinforced Swing Mechanism top flange, position monitoring optional, double acting, pendulum eye/fork head, max. operating pressure 500/160 bar



Advantages

- Introduction of clamping force without side loads Compact design Double clamping arm facilitates multiple clamping of similar workpieces
- Pendulum eye for high clamping forces
- Fork head for simple clamping arms
- Alternatively pipe thread or drilled channels
- Reinforced swing mechanism
- FKM wiper standard
- Available with position monitoring

Connecting possibilities

clamped at the same time.

- Pipe thread
- Drilled channels

Description



Application

Hydraulic swing clamps are used for clamping of workpieces, when it is essential to keep the clamping area free of straps and clamping components for unrestricted workpiece loading and unloading.

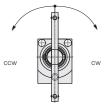
The version with pendulum eye or fork head allows simultaneous clamping of two workpieces with half clamping force.

Function

The hydraulic swing clamp is a double-acting pull-type cylinder where a part of the total stroke is used to swing the piston.

Swing direction

The swing clamps are available with clockwise or counterclockwise swing motion. Off-position is the extended piston position.



Process safety

To improve the process safety when using heavy double clamping arms the swing me chanism has been reinforced and an overload protection device has not been realised.

During clamping the reinforced swing mechanism endures a collision of the clamping arm with the workpiece up to a pressure of 100 bar. All versions are also available with a switch rod at the cylinder bottom. The control cams are mounted at this rod to control the clamping and unclamping position with limit switches or pneumatically.

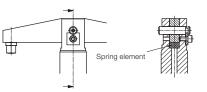
Adaptable position monitorings for inductive or pneumatic control are available as accessory (page 4).

Spring element



Fork head

The fork head allows a max. operating pressure of 160 bar. Advantageous is the fact that relatively simple clamping arms can be manufactured from flat materials.

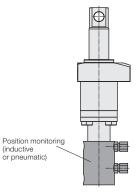


Option - metal wiper

The optionally availabe metallic wiper protects the FKM wiper against mechanical damage due to big or hot swarfs.

position monitoring (accessory)

Function



Important notes Danger of injury

Hydraulic clamping elements generate high clamping forces. Considerable injuries can be caused to fingers in the effective area of the double clamping arm.

Remedy: mount protection devices.

Operating conditions, tolerances and other data see data sheet A 0.100.

Clamping arm

Due to the missing overload protection device a collision with the clamping arm during loading and unloading of the fixture must be avoided. Remedy: mount position adaptor.

The double clamping arm in clamping position should preferably be at right angles to the piston axis to avoid overload of the spring element. Both contact bolts must only contact the workpiece after completion of the swing stroke.

Please consider: For a newly designed double clamping arm, the moment of inertia must be determined to calculate the admissible flow rate using the formula on page 3.

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the unclamped position in horizontal position. Pendulum eye

The sturdy pendulum eye can transmit high clamping forces up to a max, operating pressure of 500 bar. The double clamping arm has to be dimensioned according to the load.

The piston end of this swing clamp is desig-

ned as pendulum eye or fork head. By means

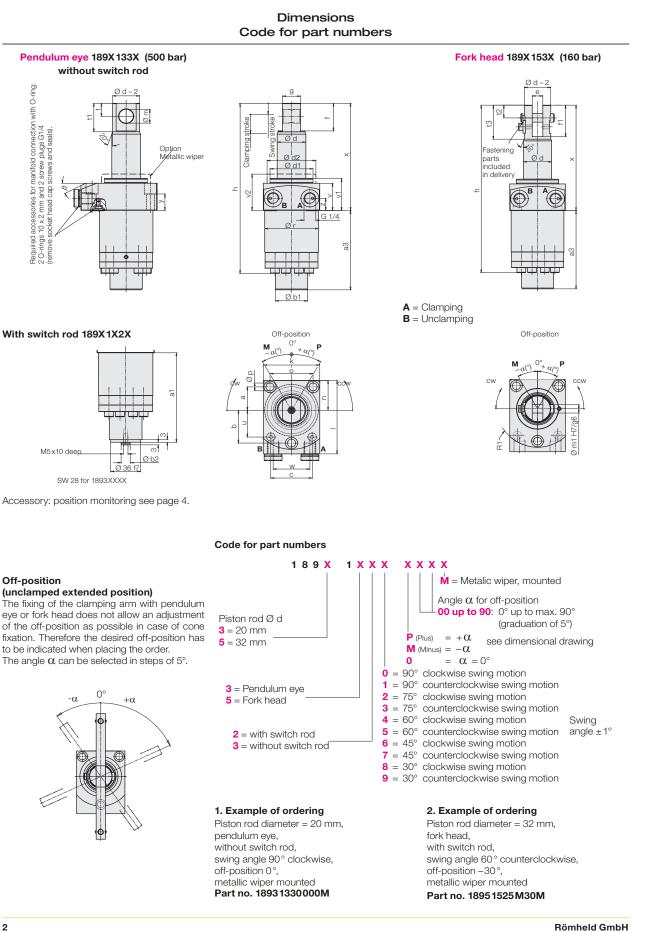
of a double clamping arm 2 workpieces can be

For both versions a springy element is required

in order to maintain the double clamping arm in

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Technical data

Clamping stroke Swing stroke Total stroke Operating pressure, min. Adm. flow rate for moment of inertia Effective piston area Clamping Unclamping Oil volume/stroke Oil volume/return stroke	[mm] [mm] [bar] [cm ³ /s] [kgm ²] [cm ²]	25 9 34 30 8 0.00032	22 13 35 30 20 0.002295	The admissible flow rate applies to the use of c whose moment of inertia chart value.
Total stroke Operating pressure, min. Adm. flow rate for moment of inertia Effective piston area Clamping Unclamping Oil volume/stroke Oil volume/return stroke	[mm] [bar] [cm ³ /s] [kgm ²] [cm ²]	34 30 8 0.00032	35 30 20	whose moment of inertia
Operating pressure, min. Adm. flow rate for moment of inertia Effective piston area Clamping Unclamping Oil volume/stroke Oil volume/return stroke	[bar] [cm³/s] [kgm²] [cm²]	30 8 0.00032	30 20	
Adm. flow rate for moment of inertia Effective piston area Clamping Unclamping Oil volume/stroke Oil volume/return stroke	[cm³/s] [kgm²] [cm²]	8 0.00032	20	chart value.
for moment of inertia Effective piston area Clamping Unclamping Oil volume/stroke Oil volume/return stroke	[kgm²] [cm²]	0.00032		
Effective piston area Clamping Unclamping Oil volume/stroke Oil volume/return stroke	[cm ²]		0.002295	The clamping time is thu
Clamping Unclamping Oil volume/stroke Oil volume/return stroke				and the unclamping time
Unclamping Oil volume/stroke Oil volume/return stroke		1.76	4.52	For new clamping arms
Oil volume/stroke Oil volume/return stroke		4.9	12.56	ment of inertia, the admi
Oil volume/return stroke	[cm3]	4.5	15.8	calculated using the follo
	[cm ³]	16.7	44	
β	[°]	12	27	
a	[mm]	20	27	$Q_2 = Q_1 \times \int \frac{1}{\sqrt{2}}$
a1	[mm]	94	102	γε
a3	[mm]	84	92	$Q_1 = Adm.$ flow rate (cha
b	[mm]	30	38	
Ø b1	[mm]	22	36	$Q_2 = Adm.$ flow rate with
Ø b2 f7	[mm]	10	10	of the new clamping
C	[mm]	32	46	$J_1 = Moment of inertia (c$
Ød	[mm]	20	32	$J_2 =$ Moment of inertia of
Ø d1	[mm]	38	48	arm
Ø d2	[mm]	42	54.5	
e +0.1	[mm]	8	12	
f	[mm]	20	32	
f1	[mm]	26	37	
g f7	[mm]	12	20	
h	[mm]	182	197	
k	[mm]	50	63	
1	[mm]	70	85	
Ø m H7	[mm]	10	16	
Ø m1 H7	[mm]	6	10	
n	[mm]	26.5	34.5	
0	[mm]	37	48	
Øp	[mm]	6.6	9	
Ør – 0.1	[mm]	44.8	59.8	
R1	[mm]	36	45.3	
t	[mm]	9	15	
t1	[mm]	21	33	
t2	[mm]	10	15	
t3	[mm]	29	40	
u	[mm]	26.5	31	
V	[mm]	26.4	31.4	
v1	[mm]	31	37	
v2	[mm]	36	42	
W	[mm]	28	41	
x	[mm]	104.5	124	
У	[mm]	18	19	
Z	[mm]	14	14	
Accessories				
Metallic wiper, complete (custom	er assembly)	0341107	0341 100	
O-Ring 10 x 2		3000347	3000347	
Screw plug G 1/4		3610264	3610264	

The admissible flow rate indicated in the chart applies to the use of double clamping arms whose moment of inertia does not exceed the chart value.

The clamping time is thus approx. 0.8 seconds and the unclamping time approx. 2 seconds. For new clamping arms with a different moment of inertia, the admissible flow rate can be calculated using the following formula:

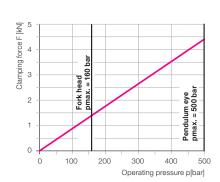
$$Q_2 = Q_1 \times \sqrt{\frac{J_1}{J_2}}$$
 [cm³/s]

Q1 = Adm. flow rate (chart value)

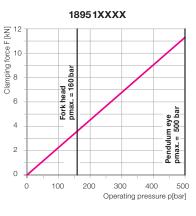
- $Q_2 = Adm$. flow rate with the moment of inertia of the new clamping arm J2
- J₁ = Moment of inertia (chart value)
- J_2 = Moment of inertia of the new clamping arm

Metallic wiper, complete (customer assembly)	0341 107	0341 100
O-Ring 10 x 2	3000347	3000347
Screw plug G 1/4	3610264	3610264

Clamping force F as a function of the operating pressure p



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Accessory - Position Monitorings

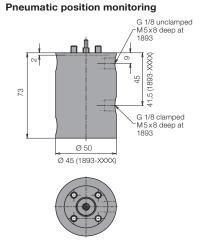
Delivery

The position monitorings are not delivered mounted at the swing clamp.

Fixing screws and signal sleeve are included in the delivery.

Electrical position monitorings are delivered with 2 inductive proximity switches and 2 right angle plugs.

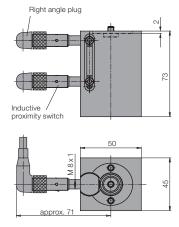
The housings can be mounted rotated by 2x180° (1893) or 8x45°.



for 1893

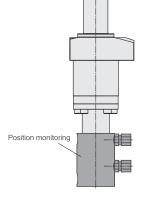
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Electrical position monitoring



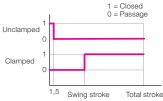
for 1895		for 1893	for 1895
0353808	Part no.	0353868	0353814



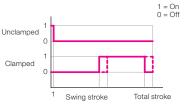


Function chart

Part no.



Function chart



Technical data for proximity switches

Voltage	1030 V DC
Residual ripple max.	15 %
Constant current max.	200 mA
Switching function	interlock
Output	PNP
Body material	stainless steel
Code class	IP 67
Environmental temperature	−25…+70°C
Connection	plug
Length of cable	5 m
LED function display	Yes
Protected against short circuits	Yes

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