

RE 29395

Edition: 2022-03 Replaces: 2019-07



Directional control valve, direct operated, with integrated field bus (IFB-Multi-Ethernet)

Type 4WRPFH



- ▶ Size 6
- ► Component series 3X
- ▶ Maximum operating pressure 350 bar
- ► Rated flow 40 l/min (**Δp** = 35 bar)



Features

- Integrated fieldbus (IFB Multi-Ethernet)
- Bus connection/service interface (Sercos, EtherCAT, EtherNet/IP, PROFINET RT, VARAN)
- ► Scalable
 - 2 configurable analog pressure sensor inputs
- ▶ Safe
 - Internal safety function (can be used up to category 4/PL e according to EN 13849-1)
 - CE conformity according to EMC Directive 2014/30/EU
- ► Precise
 - Integrated pressure/force control, optional
 - High response sensitivity and low hysteresis

Contents

| Features | 1 |
|---|--------|
| Ordering code | 2, 3 |
| Symbols | 3, 4 |
| Function | 5, 6 |
| Technical data | 7 9 |
| Representation in the system network | 10 |
| Block diagram/controller function block | 11 |
| Electrical connections, assignment | 12 |
| LED displays | 13 |
| Characteristic curves | 14, 15 |
| Dimensions | 16 18 |
| Accessories | 18, 19 |
| Project planning and maintenance instructions | 20 |
| Further information | 20 |



Ordering code

| | iernig (| | | | | | | | | | | | | | | | | | | | |
|---------------------|---|--|--|--|--------------------|------------|-------------|---------|---------|----------|---------|---------|-----------------|----------------|---------|----------------|---------|---------|------|----------|----------------------------------|
| 01 | 02 | 03 | 04 | 05 | 06 | 07 | 08 | 09 | | 10 | | 11 | 12 | 13 | | 14 | 15 | 16 | 17 | 18 | |
| 4 | WRP | F | Н | 6 | | В | | | - | ЗХ | / | | | | / | 24 | | D9 | | | |
| 01 | 4 main p | orts | | | | | | | | | | | | | | | | | | | 4 |
| 02 | Direction | | ontrol | valve | | | | | | | | | | | | | | | | \vdash | WRP |
| 03 | With inte | | | | | | | | | | | | | | | | | | | | F |
| 04 | Control | | | | | | | | | | | | | | | | | | | | н |
| 05 | Size 6 | 3000 | , 5100 | | | | | | | | | | | | | | | | | | 6 |
| | 1 | | | | | | | | | | | | | | | | | | | | - |
| 06 | Symbols | e.g. | C, C1 | etc.; | tor po | ssible | vers | ion, se | e pag | ge 3 | | | | | | | | | | | |
| 07 | Installat | ion s | de of | the in | nductiv | e pos | ition | transo | ducer | | | | | | | | | | | | В |
| Rated | d flow at | 70 ba | ar pre | ssure | differe | ential | (35 b | ar/cor | ntrol e | edge) | | | | | | | | | | | |
| 08 | | | | | | | | | | Fle | ow ch | aracte | ristic | | | | | | | | |
| | | | | | | "L | " | | | "P' | ' (infl | ection | 40%) | | | "P" (ir | ıflecti | on 609 | 6) | | |
| | 2 l/min | | | | | ✓ | | | | | | _ | | | | | _ | | | | 02 |
| | 4 l/min | | | | | ✓ | | | _ | | | ✓ | | | | | _ | | | | 04 |
| | 12 l/min | | | | | ✓ | | | | | | _ | | | | | _ | | | | 12 |
| | 15 l/min | ı | | | | _ | | | | | | - | | | | | ✓ | | | | 15 |
| | 24 l/min | 1 | | | | ✓ | | | | _ | | | | | | | _ | | | | 24 |
| | 25 l/min | 1 | | | | _ | | | | _ | | | | | | ✓ | | | | | 25 |
| | 40 l/min | | | | | ✓ < | > | | | | | ✓ | | | | | - | | | | 40 |
| Flow | characte | ristic | : | | | | | | | | | | | | | | | | | | |
| 09 | Linear | | | | | | | | | | | | | | | | | | | | L ♦ |
| | Inflected | d cha | racter | istic o | curve (| inflec | tion 6 | 60% fc | r NG | with i | ated | flows | " 15 " a | nd " 25 | i", oth | erwise | infle | ction 4 | 10%) | | Р |
| | | | | | |) 30 |). unc | hange | d ins | tallatio | n and | l conne | ection | dimer | sions | 5) | | | | | ЗХ |
| 10 | Compon | ent s | eries | 30 | 39 (30 | , J | o: unc | | | | | | | | | | | | | | |
| | | | | | | | | | drauli | c fluid | | see p | age 8) | | | | | | | | |
| Seal | material | (obse | | | | | | | drauli | c fluid | | see p | age 8) | | | | | | | | M ♦ |
| | | (obse | | | | | | | drauli | c fluid | | see p | age 8) | | | | | | | | M ♦ |
| Seal 11 | material NBR sea FKM sea | (obse ls ls | erve c | ompa | tibility | | | | drauli | c fluid | | see p | age 8) | | | | | | | | |
| Seal 11 | material NBR sea FKM sea | (obse ls ls or (p | erve c | ompa re rati | tibility | | | | drauli | c fluid | | see p | age 8) | | | | | | | | |
| Seal 11 Press | material NBR sea FKM sea | (obse | ressu | ompa re rati | tibility | | | | drauli | c fluid | | see p | age 8) | | | | | | | | V |
| Seal 11 Press 12 | material NBR sea FKM sea sure sense Without Pressure | (observed) ls or (p presserved) | ressu sure r | ompa re rati rating 0 bar | tibility | | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 |
| Seal 11 Press 12 | material NBR sea FKM sea sure sense Without Pressure | (obsells or (p presseration | ressu sure r | ompa re rati rating 0 bar r (pos | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 |
| Seal 11 Press 12 | material NBR sea FKM sea sure sense Without Pressure | (obse | ressu sure r | ompa re rati rating 0 bar r (pos | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G |
| Seal 11 Press 12 | material NBR sea FKM sea Sure sens Without Pressure nal press Without | (obsettles) or (p presset ration ure s inter | ressu sure r | ompa re rati rating 0 bar r (pos | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | V 0 G |
| Seal 11 Press 12 | material NBR sea FKM sea Sure sens Without Pressure mal press Without In port A | (obsection) (obsec | ressu sure r ng 280 ensor | ompa re rati rating 0 bar r (pos | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G |
| Seal 11 Press 12 | material NBR sea FKM sea Without Pressure Mithout In port A In port E | (observations) (obser | ressu sure r ng 280 ensor nal pi | ompa re rati rating 0 bar r (pos ressur | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G 0 A B |
| Seal | material NBR sea FKM sea Sure sens Without Pressure Mithout In port A In ports | (observed) (obser | ressu sure r ng 280 ensor nal pi | ompa re rati rating 0 bar r (pos ressur | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G 0 A B C |
| Seal | material NBR sea FKM sea Without Pressure mal press Without In port A In ports Supply v | (obsections) or (ppressions) representations interpresentations A annotage face | ressu sure r ng 280 ensor nal pi | ompa re rati rating 0 bar r (pos ressur | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G 0 A B C |
| Seal | material NBR sea FKM sea Sure sense Without Pressure Mithout In port A In ports Supply v | (obseduls or (p press press ratin A A A and roltage face | ressu sure r ng 280 ensor nal pr | ompa re rati rating 0 bar r (pos ressur | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G 0 A B C |
| 11 | material NBR sea FKM sea Sure sens Without Pressure Mithout In port A In ports Supply v rnet inter | (obseduls or (p press press ratin A A A and roltage face | ressu sure r ng 280 ensor nal pr | ompa re rati rating 0 bar r (pos ressur | tibility ing) | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G 0 A B C |
| Seal | material NBR sea FKM sea Sure sens Without Pressure Mithout In port A In ports Supply v rnet inter EtherNE PROFINE | (observed) | ressu sure r nal pri nal pri | omparer rational representations of the comparer of the compar | ing) ition) e sens | of se | | | drauli | c fluid | | see p | age 8) | | | | | | | | 0 G 0 A B C 24 |



Directional control valve | 4WRPFH 3/20

Ordering code

| 01 | 02 | 03 | 04 | 05 | 06 | 07 | 80 | 09 | | 10 | | 11 | 12 | 13 | | 14 | 15 | 16 | 17 | 18 |
|----|-----|----|----|----|----|----|----|----|---|----|---|----|----|----|---|----|----|----|----|----|
| 4 | WRP | F | Н | 6 | | В | | | _ | ЗХ | / | | | | 1 | 24 | | D9 | | |

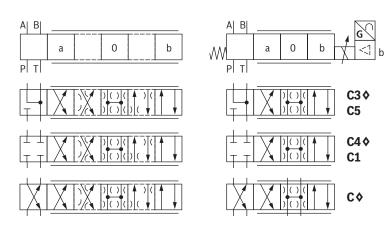
Connector

| 16 | Voltage supply, enable acknowledgment | D9 |
|-------|---|-------------|
| Press | sure sensor interface | |
| 17 | Without interface | 0 |
| | Analog, a maximum of 3 external pressure sensors (0 10 VDC) | 5 1) |
| 18 | Further details in the plain text | * |

Only with version "0" at positions 12 and 13 ("4WRPFH 6 .B..-3X/.00/24.D95")



Symbols



With symbols C5 and C1: 1)

 $\begin{array}{ll} \mathsf{P} \to \mathsf{A} \colon \textbf{\textit{q}}_{\mathsf{V} \; \mathsf{nom}} & \mathsf{B} \to \mathsf{T} \colon \textbf{\textit{q}}_{\mathsf{V} \; \mathsf{nom}} / 2 \\ \mathsf{P} \to \mathsf{B} \colon \textbf{\textit{q}}_{\mathsf{V} \; \mathsf{nom}} / 2 & \mathsf{A} \to \mathsf{T} \colon \textbf{\textit{q}}_{\mathsf{V} \; \mathsf{nom}} \end{array}$

Notice:

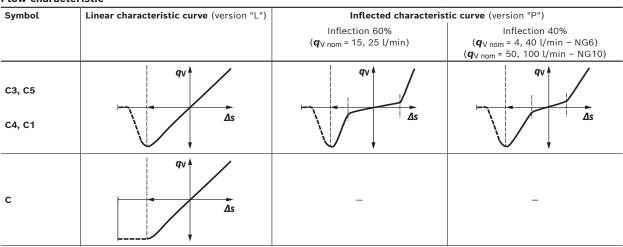
Representation according to DIN ISO 1219-1.
Hydraulic interim positions are shown by dashes.

1) Standard = 1:1, **q**_{V nom} 2:1 from rated flow = 40 l/min (version "40")



Symbols

Flow characteristic





Directional control valve | 4WRPFH 5/20

Function

General

The **IFB Multi-Ethernet** valve (Integrated **F**ield**b**us) is a digital directional control valve with integrated fieldbus.

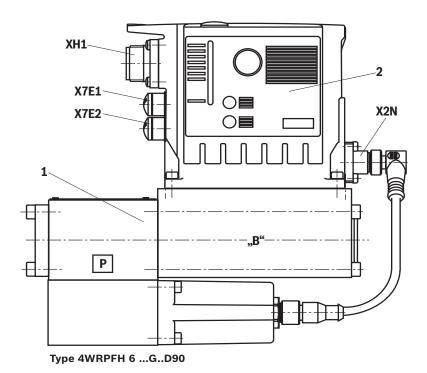
The following operating modes are possible:

- ► Standard:
 - Valve direct control
 - Flow control
- ▶ Version "5" or with internal pressure sensors:
 - Pressure/force control
 - Active damping
 - Alternating control (flow pressure/force);
 pQ function (flow-controlled)
- ► Command value presetting is done purely digitally via the Ethernet interface (X7E1 or X7E2)
- ► The feedback information of the actual value signals to the higher-level control is provided via the Ethernet interface (X7E1 or X7E2)
- ► The controller parameters are set via the Ethernet interface (X7E1 or X7E2)

Set-up

The directional control valve with IFB Multi-Ethernet electronics mainly consists of:

- Direct operated directional control valve (1) with control spool and sleeve in servo quality
- ► Integrated fieldbus (3) with:
 - connector, voltage supply, safety shut-down (XH1)
 - Ethernet interfaces (X7E1, X7E2)
 - Analog sensor interfaces (X2N, optional)





Function

Function

When the control solenoid of the valve is switched off (enable pin D, low signal), the spring-operated control spool is in the fail-safe position.

When the control solenoid is activated (enable pin D, high signal), the digital electronics (OBE) compares the specified command value to the position actual value. In case of control deviations, the control of the solenoid is changed so as to be compensated. Due to the change in magnetic force, the control spool is adjusted against the spring. Stroke/control spool cross-section is regulated proportionally to the command value. In case of a command value presetting of 0, the electronics adjusts the control spool against the spring to central position. In deactivated condition, the spring is untensioned to a maximum and the valve is in fail-safe position.

Safety function

Thanks to the control solenoid (enable pin D, low signal) at the connector (XH1), shut-off is enabled. After shut-off, the control spool of the valve is in fail-safe position.

Enable acknowledgment pin C for solenoid B is "high". By connection of the control solenoid (enable pin D, high signal), the valve can be regulated in both directions by command value presetting. Enable acknowledgment pin C for solenoid B is "low".

The integrated control electronics of the valve enables the additional shut-off of a channel according to EN 13849-1 in the direction P to A (depending on the application, the fail-safe position must be adhered to). For this purpose, a suitable control system must be provided to perform the plausibility check between the direction-dependent valve signals "enable input" and "enable acknowledgment" (diagnosis signal fed back by the valve) and react in an error case. It is not possible to switch off direction P→B in a safety-relevant manner according to EN 13849-1 (depending on valve type).

Monitoring

The digital control electronics enable comprehensive monitoring functions/error detection including:

- ▶ Undervoltage
- Communication error
- Cable break for analog sensor inputs
- ► Monitoring of the microcontroller (watchdog)
- ► Temperature of the integrated electronics

IndraWorks DS PC program

To implement the project planning task and to parameterize the valve, the user may use the IndraWorks DS engineering tool (see accessories):

- ▶ Project planning
- ▶ Parameterization
- Commissioning
- ▶ Diagnosis
- ► Comfortable administration of all data on a PC
- ▶ PC operating systems: Windows 7-10

Motice:

- ▶ 4/4 directional control valves do not have a leakage-free basic locking when deactivated. Leakage must be considered when designing the drive. While the electrical supply voltage is being switched off, the drive may be accelerated for a short time in functional direction P->B.
- ➤ Valve type 4WRPFH can be used as shut-off element cat. 3 or 4 (up to PL e according to EN 13849-1). For both categories, an additional shut-off element is required to achieve a two-channel shut-off. For further information on the safety application, see operating instructions 29391-B.

7/20



Directional control valve | 4WRPFH

Technical data

(For applications outside these values, please consult us!)

| General | | | | | | | |
|--|---|-------|---|--|--|--|--|
| Type of connection | n | | Subplate mounting | | | | |
| Porting pattern | | | ISO 4401-03-02-0-05 | | | | |
| Weight | ► Versions "00D90" and "00D95 | kg | 3.5 | | | | |
| | ► Versions "GAD90", "GBD90" and "GCD90" | kg | 4.8 | | | | |
| Installation position | on | | any | | | | |
| Ambient temperat | ure range | °C | -20 +60 | | | | |
| Storage temperature range | | | +5 +40 | | | | |
| Maximum storage time | | | 1 (if the storage conditions are observed, refer to the operating instructions 07600-B) | | | | |
| Maximum relative | humidity (no condensation) | % | 95 | | | | |
| Maximum surface | temperature | °C | 150 | | | | |
| MTTF _d value accor | rding to EN ISO 13849 | years | 150 (for further details, see operating instructions 29391-B) | | | | |
| Sine test accordin | g to DIN EN 60068-2-6 | | 10 2000 Hz/maximum of 10 g/10 cycles/3 axes | | | | |
| Noise test accordi | ng to DIN EN 60068-2-64 | | 20 200 0Hz/10 g _{RMS} /30 g peak/30 min./3 axes | | | | |
| Transport shock a | ccording to DIN EN 60068-2-27 | | 15 g / 11 ms / 3 axes | | | | |
| Conformity | ► CE according to EMC directive 2014/30/EU, tested according to | | EN 61000-6-2 and EN 61000-6-3 | | | | |
| | ► RoHS directive | | 2011/65/EU ¹⁾ | | | | |
| Protection class according to EN 60529 | | | IP65 (if suitable and correctly mounted mating connectors are used) | | | | |

| Hydraulic | | | | | | | | | | |
|------------------------------------|--|---------|-----------|---------------------|-------|-------|-------|-------|--|--|
| Maximum operating | ▶ Ports A, B, P | bar | 350 | | | | | | | |
| pressure | ▶ Port T | bar | 250 | | | | | | | |
| Hydraulic fluid | | | | page 8 | | | | | | |
| Hydraulic fluid temper | rature range (flown-through) | °C | -20 +60 |) | | | | | | |
| Viscosity range | ► Recommended | mm²/s | 20 100 | | | | | | | |
| | ► Maximum admissible | mm²/s | 10 800 | | | | | | | |
| | degree of contamination of the iness class according to ISO 4406 (c) | | Class 18/ | 16/13 ²⁾ | | | | | | |
| Rated flow (Δp = 35 b | ar per control edge ³⁾) | l/min | 2 | 4 | 12 | 15 | 24/25 | 40 | | |
| Leakage flow | ► Linear characteristic curve "L" | cm³/min | < 150 | < 180 | < 300 | - | < 500 | < 900 | | |
| (at 100 bar) | ► Inflected characteristic curve "P" | cm³/min | - | - | - | < 180 | < 300 | < 450 | | |
| Limitation of use | ► Symbols C3, C5 | bar | 350 | 350 | 350 | 350 | 350 | 160 | | |
| (transition to fail-safe position) | ► Symbols C4, C1 | bar | 350 | 350 | 350 | 280 | 250 | 100 | | |

¹⁾ The product fulfills the substance requirements of the RoHS directive 2011/65/EU.

3) Flow for deviating Δp (per control edge):

$$q_x = q_{Vnom} \times \sqrt{\frac{\Delta p_x}{35}}$$

²⁾ The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components.



Technical data

(For applications outside these values, please consult us!)

| Hydraulic fluid | | Classification | Suitable sealing materials | Standards | Data sheet | |
|-----------------|----------------------|--|----------------------------|-----------|------------|--|
| Mineral oils | | HL, HLP, HLPD, HVLP, HVLPD | NBR, FKM | DIN 51524 | 90220 | |
| Bio-degradable | ► Insoluble in water | HETG | FKM | 150 15200 | | |
| | | HEES | FKM | ISO 15380 | 90221 | |
| | ► Soluble in water | HEPG | FKM | ISO 15380 |] | |
| Flame-resistant | ▶ Water-free | HFDU (glycol base) | FKM | | | |
| | | HFDU (ester base) | FKM | ISO 12922 | 90222 | |
| | | HFDR | FKM | | | |
| | ► Containing water | HFC (Fuchs: Hydrotherm 46M, Renosafe 500; Petrofer: Ultra Safe 620; Houghton: Safe 620; Union: Carbide HP5046) | NBR | ISO 12922 | 90223 | |

Important information on hydraulic fluids:

- ► For further information and data on the use of other hydraulic fluids, please refer to the data sheets above or contact us.
- ➤ There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.).
- ► The ignition temperature of the hydraulic fluid used must be 50 K higher than the maximum surface temperature.
- ▶ Bio-degradable and flame-resistant containing water:

 If components with galvanic zinc coating (e.g. version "J3" or "J5") or parts containing zinc are used, small amounts of dissolved zinc may get into the hydraulic system and cause accelerated aging of the hydraulic fluid. Zinc soap may form as a chemical reaction product, which may clog filters, nozzles and solenoid valves particularly in connection with local heat input.

► Flame-resistant – containing water:

- Due to the increased cavitation tendency with HFC hydraulic fluids, the life cycle of the component may be reduced by up to 30% as compared to the use with mineral oil HLP. In order to reduce the cavitation effect, it is recommended – if possible specific to the installation – backing up the return flow pressure in ports T to approx. 20% of the pressure differential at the component.
- Dependent on the hydraulic fluid used, the maximum ambient and hydraulic fluid temperature must not exceed 50 °C.
 In order to reduce the heat input into the component, the command value profile is to be adjusted for proportional and high-response valves.

| Static/dynamic | | | | |
|--|-----------|-------------------|--|--|
| Hysteresis | % | ≤ 0.2 | | |
| Manufacturing tolerance q _{Vmax} | % | ≤10 | | |
| Temperature drift | %/10 K | Zero shift < 0.25 | | |
| Pressure drift | %/100 bar | Zero shift < 0.15 | | |
| Zero point calibration | % | ±1 (ex works) | | |



Directional control valve | 4WRPFH

9/20

Technical data

(For applications outside these values, please consult us!)

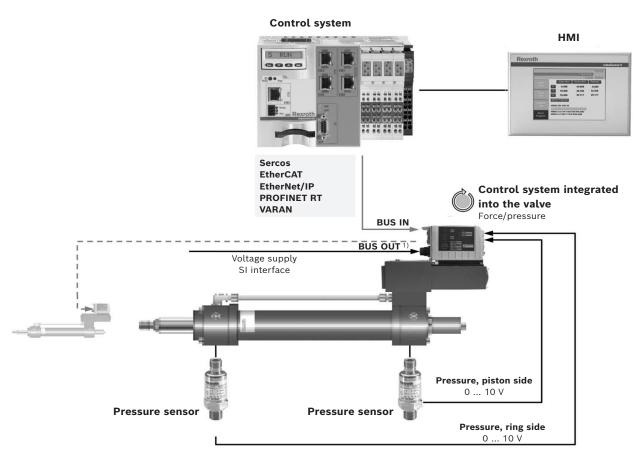
| Electrical, integrated | electronics (OBE) | | | | | |
|---------------------------------|---|-----|---|--|--|--|
| Supply voltage 4) | ► Nominal value | VDC | 24 | | | |
| | ► Minimum | VDC | 18 | | | |
| | ► Maximum | VDC | 36 | | | |
| | ► Maximum residual ripple | Vpp | 2.5 (comply with the absolute supply voltage limit values) | | | |
| Current consumption | ► Maximum ⁵⁾ | А | 2.5 | | | |
| | ► Impulse current | А | 4 | | | |
| Maximum power cons | umption | W | 40 | | | |
| Relative duty cycle | | % | 100 (continuous operation) | | | |
| Fuse protection, exter | nal | Α | 4, time-lag | | | |
| Functional ground and screening | | | see connector pin assignment (CE-compliant installation) page 12 | | | |
| Booting time | | s | <15 | | | |
| Switching input | ► Quantity | | 1 | | | |
| Enable XH1 | ► Low level | V | -3 5 | | | |
| | ► High level | V | 15 U B | | | |
| | ► Maximum current consumption at high level | mA | <1 | | | |
| Switching output | ► Quantity | | 1 | | | |
| Enable acknowledgment XH1 | ► Low level | V | 0 3 | | | |
| acknowledgment An i | ► High level | V | 15 U _B | | | |
| | ► Current carrying capacity | mA | 50 (short-circuit-proof) | | | |
| | ► Inductive load admissible | | no | | | |
| Analog sensors X2N | ► Quantity | | 3 (version "5") | | | |
| | ► Supply voltage | V | 24 | | | |
| | ► Maximum supply current | mA | 50 | | | |
| | ► Voltage inputs | | | | | |
| | - Measurement range | V | 0 10 | | | |
| | - Input resistance | kΩ | 100 +10% | | | |

⁴⁾ Voltage limit values must be observed directly at the connector of the valve (observe line length and cable cross-section!)

⁵⁾ The maximum current consumption will increase when using the sensor inputs or the switching output according to the external load



Representation in the system network (version "5")

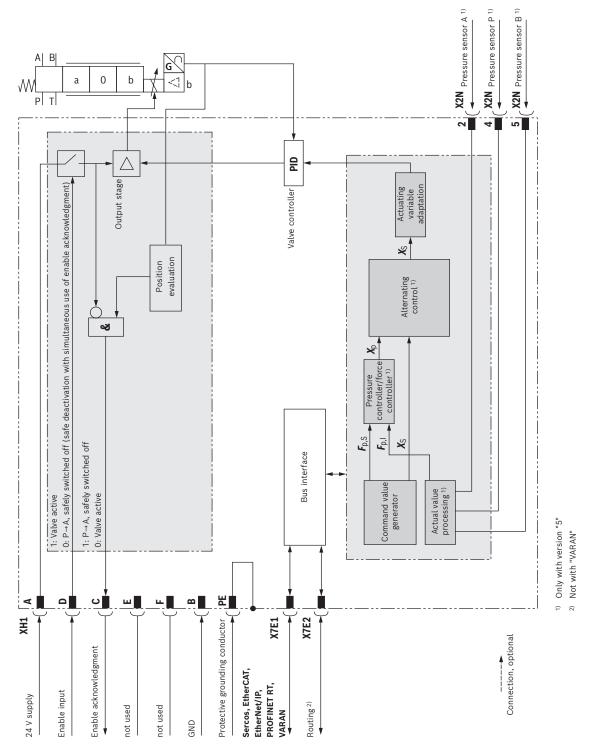


1) Not with "VARAN"



Directional control valve | 4WRPFH 11/20

Block diagram/controller function block

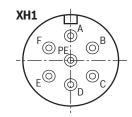




Electrical connections, assignment

Connector pin assignment XH1, 6-pole + PE according to DIN 43563

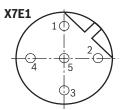
| Pin | Assignment of interface D9 |
|-----|---|
| Α | 24 VDC supply voltage 1) |
| В | GND |
| С | Enable acknowledgment 24 VDC (I_{max} 50 mA) ²⁾ (high \geq 15 V; low < 2 V) |
| D | Enable input 24 VDC (high ≥ 15 V; low < 2 V) |
| Ε | not used |
| F | not used |
| PE | Functional ground (connected directly to metal housing) |



- 1) A load increases the current consumption on pin A
- 2) Enable acknowledgment is issued only if the valve has safely switched off according to EN 13849-1, see operating instructions 29391-B.

Connector pin assignment for Ethernet interface "X7E1" and "X7E2" (coding D), M12, 4-pole, socket

| Pin | Assignment |
|-----|------------|
| 1 | TxD + |
| 2 | RxD + |
| 3 | TxD - |
| 4 | RxD - |
| 5 | not used |



Analog configurable sensor interface, port "X2N" (coding A), M12, 5-pole, socket

| Pin | Assignment |
|-----|--------------------------------|
| 1 | +24 V voltage output |
| 2 | Analog sensor input 2 (0 10 V) |
| 3 | GND |
| 4 | Analog sensor input 4 (0 10 V) |
| 5 | Analog sensor input 3 (0 10 V) |



Only with version "5"

Motice:

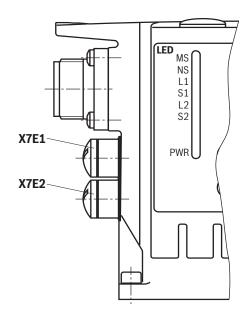
- ► Reference potential for all signals: GND
- We recommend connecting the shields on both sides via the metal housings of the plug-in connectors.
 Using connector pins will affect the effectiveness of the shielding effect. Internal screens are not required.



Directional control valve | 4WRPFH 13/20

LED displays

| LED | Interface | Sercos | EtherNET/IP | EtherCAT | PROFINET RT | VARAN |
|-----|--------------------|---------------------|---------------------------|---------------------------|---------------------------|---------------------------|
| MS | | Module status | Module status | Module status | Module status | Module status |
| NS | Electronics module | S | Network status and others |
| L1 | X7E1 | Link and others | Link and others | Link/activity | Link and others | Link and others |
| S1 | | Activity and others | Activity and others | not used | Activity and others | Active and others |
| L2 | X7E2 | Link and others | Link and others | Link/activity | Link and others | not used |
| S2 | X/E2 | Activity and others | Activity and others | not used | Activity and others | not used |
| PWR | XH1 | Power | Power | Power | Power | Power |



Displays of the status LEDs

| Power LED (LED PWR) | Display status |
|-------------------------------|--|
| Off | No voltage supply |
| Green | Operation |
| Module status LED (LED MS) | Display status |
| Off | No voltage supply |
| Green-red, flashing | Initialization |
| Green, flashing | Drive ready for operation |
| Green | Drive active |
| Orange, flashing | Warning |
| Red, flashing | Error |
| Green, rapidly flashing | Firmware must be loaded |
| Link LED (LED L1) | Display status |
| Permanently lit | Cable plugged in, connection established |
| Activity LED (LED S1) | Display status |
| Flashing | Data sent/received |

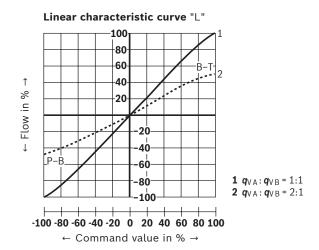
Motice:

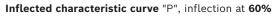
- ► For the connection to the M12 sockets, we recommend using self-locking mating connectors
- ▶ The MS module status LED relates to the electronics module
- ▶ The NS network status LED indicates the status of the control communication, see application description 30338-FK ► LEDs L1, S1, L2 and S2 relate to inter-
- faces "X7E1" and "X7E2"
- ▶ For a detailed description of the diagnosis LEDs, please refer to the functional description Rexroth HydraulicDrive HDx.
- ▶ Function is only available after start-up of the electronics.

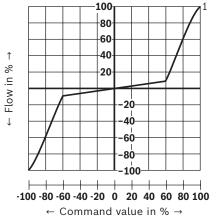


Characteristic curves: Flow characteristic (measured with HLP46, 9_{oil} = 40 ±5 °C)

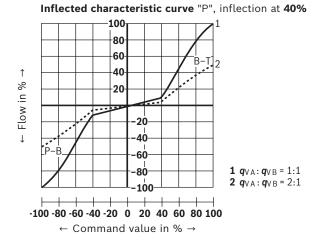
Flow/signal function







1 qvA: qvB = 1:1



| | Fail-safe positi | ion | | |
|---|----------------------------|--|------------|--|
| A B i_ | T PLOUT A GO | Leakage flow at 100 bar | P→A P→B | 50 cm ³ /min 70 cm ³ /min |
| WT I | <u> </u> | Flow at 4p = 35 bar | A→T B→T | 10 20 l/min 7 20 l/min |
| A B G C C C C C C C C C C C C C C C C C C | | Leakage flow at 100 bar | P→A P→B | 50 cm ³ /min 70 cm ³ /min |
| | | | A→T B→T | 70 cm³/min 50 cm³/min |
| Fail-safe | p = 0 bar → 7 ms | Enable "off" or internal shut-of | | |
| raitsale | p = 100 bar → 10 ms | $U_B \le 18 \text{ V or } I \le 2 \text{ mA (with 4 20 mA signal, cable break detection:}$ | | |

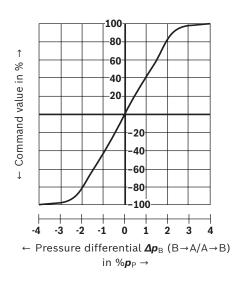


Directional control valve | 4WRPFH 15/20

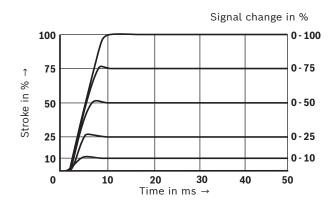
Characteristic curves

(measured with HLP46, ϑ_{oil} = 40 ±5 °C)

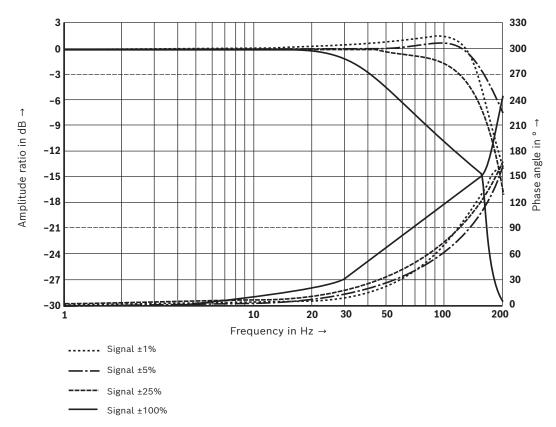
Pressure/signal characteristic curve



Transition function with stepped electric input signals

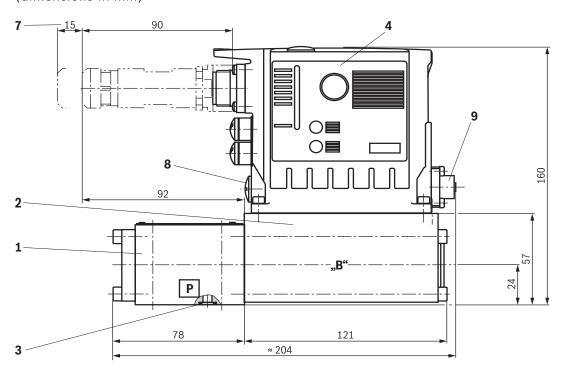


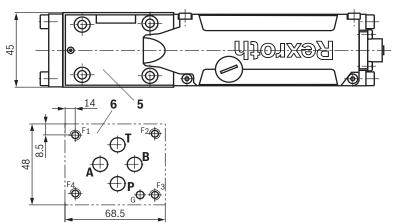
Frequency response

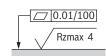




Dimensions: Versions "00..D90" and "00..D95" (dimensions in mm)







Required surface quality of the valve contact surface

- Valve mounting screws see page 18.
- Motice:

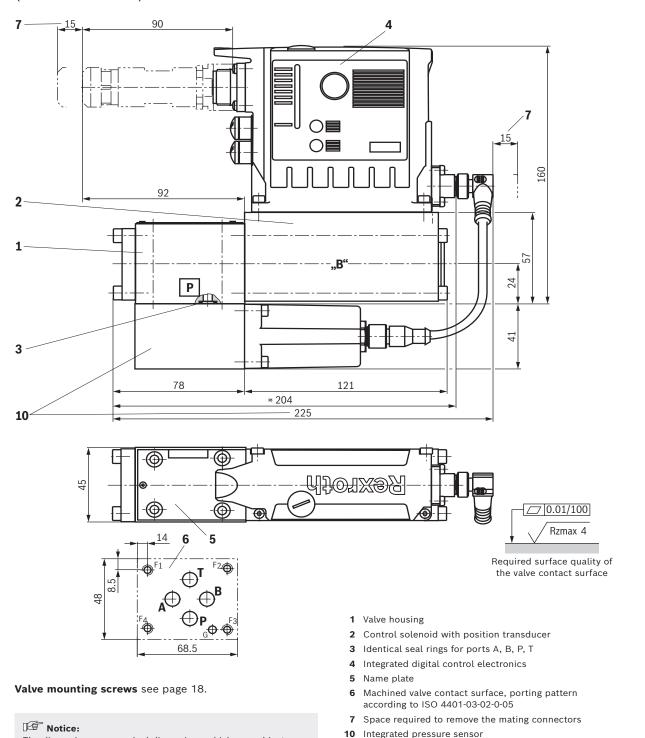
The dimensions are nominal dimensions which are subject to tolerances.

- 1 Valve housing
- 2 Control solenoid with position transducer
- 3 Identical seal rings for ports A, B, P, T
- 4 Integrated digital control electronics
- 5 Name plate
- **6** Machined valve contact surface, porting pattern according to ISO 4401-03-02-0-05
- 7 Space required to remove the mating connectors
- 8 Plug screw PG, version "00..D90" only
- **9** Version "00..D95" only



Directional control valve | 4WRPFH 17/20

Dimensions: Versions "GA..D90", "GB..D90" and "GC..D90" (dimensions in mm)



RE 29395, edition: 2022-03, Bosch Rexroth AG

The dimensions are nominal dimensions which are subject



Dimensions

Valve mounting screws (separate order)

| Version | Hexagon socket head cap screws | Material number |
|---------------------------------|--|-----------------|
| "00D90", "00D95" | 4 hexagon socket head cap screws ISO 4762 - M5 x 30 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B Friction coefficient μ_{total} = 0.09 0.14; tightening torque M_{A} = 6+2 Nm | R913048086 |
| "GAD90", "GBD90", "GCD90" | 4 hexagon socket head cap screws ISO 4762 - M5 x 70 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B Friction coefficient $\mu_{\rm total}$ = 0.09 0.14; tightening torque $M_{\rm A}$ = 8.9 Nm ±10% | R913043762 |

Motice:

The tightening torque of the hexagon socket head cap screws refers to the maximum operating pressure.

Accessories (separate order)

Protective cap

| Protective cap M12 | Version | Material number |
|--------------------|---------|-----------------|
| | | R901075563 |
| | | |

Parameterization

| The following is required for the | Material number/download | |
|-----------------------------------|---|---|
| 1 Commissioning software | IndraWorks, Indraworks D, Indraworks DS | www.boschrexroth.com/IFB |
| 2 Connection cable, 3 m | Shielded, M12 on RJ45, length can be freely selected (= xx.x) | R911172135 (additional indication of type designation RKB0044/xx.x) |



Directional control valve | 4WRPFH 19/20

Accessories (separate order)

Mating connectors and cable sets

| Port | Designation | Version | Short designation | Material number | Data sheet |
|-------------------|--|--|-------------------|--------------------------|---------------|
| XH1 | Mating connector; | Straight, metal | 7PZ31M | R900223890 | 08006 |
| | for valves with round connector, | Straight, plastic | 7PZ31K | R900021267 |] |
| | 6-pole + PE | Angled, plastic | - | R900217845 | - |
| | Cable sets; | Plastic, 3.0 m | 7P Z31 BF6 | R901420483 | 08006 |
| | for valves with round connector, | Plastic, 5.0 m | | R901420491 | |
| | 6-pole + PE | Plastic, 10.0 m |] | R901420496 | |
| | | Plastic, 20.0 m | _ | R901448068 | - |
| X7E1, X7E2 | Cable set; shielded, 4-pole, D coding | Straight connector M12, on straight connector M12, line cross-section 0.25 mm², CAT 5e, length freely selectable (= xx.x) | _ | R911172111 1) | - |
| | Cable set; shielded, 4-pole | Straight connector M12, on straight connector RJ45, line cross-section 0.25 mm², CAT 5e, length freely selectable (= xx.x) | _ | R911172135 ²⁾ | - |
| X2N ³⁾ | Cable set; shielded, 5-pole, for connecting Rexroth pressure sensors, type HM20, A coding | PUR/PVC, straight connector M12, on straight socket M12, line cross-section 0.34 mm², 0.6 m | - | R901111709 | - |
| | | PUR/PVC, straight connector M12, on straight socket M12, line cross-section 0.34 mm², 1.0 m | - | R901111712 | - |
| | | PUR/PVC, straight connector M12, on straight socket M12, line cross-section 0.34 mm², 2.0 m | - | R901111713 | - |
| | Cable set; shielded, 5-pole, A coding | Straight connector M12, on free line end, line cross-section 0.34 mm², 1.5 m | - | R901111752 | - |
| | | Straight connector M12, on free line end, line cross-section 0.34 mm², 3.0 m | _ | R901111754 | - |
| | | Straight connector M12, on free line end, line cross-section 0.34 mm², 5.0 m | - | R901111756 | - |
| | | Straight connector M12, on free line end, line cross-section 0.34 mm², 10.0 m | _ | R913005147 | - |

- 1) Additional indication of type designation RKB0040/xx.x
- 2) Additional indication of type designation RKB0044/xx.x
- $^{\rm 3)}\,$ Only with connection of an external sensor, type HM20 $\,$

Motice:

- ► Tighten the M12 connector with a manual torque wrench by 1 Nm.
- ► Self-locking M12 cables must be used.
- ▶ It must be ensured that cables are secured without radial force.
- ▶ All cables connected to "XH1", "X7E1" and "X7E2" must be bundled in a wire harness after 20 cm the latest. The wire harness must be fixed after further 20 ... 30 cm. Make sure that there is no relative motion between the fixation and the valve.
- ▶ Before the fixation point, there must not be any cable loops.
- ► In general, the information on installation provided by the cable manufacturers must be observed.
- Respectively, the cable of "X2N" (if used) is also fixed as described above.
- \blacktriangleright For further information, see operating instructions 29391-B



Project planning and maintenance instructions

- ► The supply voltage must be permanently connected; otherwise, bus communication is not possible.
- If electro-magnetic interference is to be expected, take appropriate measures for ensuring the function (depending on the application, e.g. shielding, filtration).

► High-response/proportional valve with Multi-Ethernet interface

- ► The devices have been tested in the plant and are supplied with default settings.
- Only complete devices can be repaired.
 Repaired devices are returned with default settings.
 User-specific settings will not be applied.
 The machine end-user will have to retransfer the corresponding user parameters.

Further information

| \blacktriangleright | Operation fieldbus electronics (xx = software version): | | |
|-----------------------|---|------------------|--|
| | - Functional description Rexroth HydraulicDrive HDx-20 | - 30338-FK | |
| | - Parameter description Rexroth HydraulicDrive HDS-16, HDx-17 HDx-20 | - 30330-PA | |
| | - Description of diagnosis Rexroth HydraulicDrive HDS-16, HDx-17 HDx-20 | - 30330-WA | |
| • | Subplates | Data sheet 45100 | |

- ► Subplates
 ► Hydraulic fluids on mineral oil basis
 ► Environmentally compatible hydraulic fluids
 ► Flame-resistant, water-free hydraulic fluids
 ► Hexagon socket head cap screws, metric/UNC
 ► Data sheet 90221
 ► Data sheet 90222
 ► Data sheet 9036
- Hydraulic valves for industrial applications
 Directional control valves, direct operated, with electrical position feedback
 Data sheet 29035
- and integrated electronics (OBE)

 ▶ Directional control valve with integrated digital axis controller (IAC-R)

 Data sheet 2919
- ► Directional control valve with integrated digital axis controller (IAC-R)
 and clock-synchronized PROFIBUS DP/V2 (PROFIdrive profile)
- CE Declaration of Conformity

and field bus interface

- ► General product information on hydraulic products
- ► Installation, commissioning and maintenance of servo valves and high-response valves
- ► Assembly, commissioning and maintenance of hydraulic systems
- ▶ Commissioning software and documentation on the Internet
- ▶ Information on available spare parts

Data sheet 45100
Data sheet 90220
Data sheet 90221
Data sheet 90222
Data sheet 08936
Operating instructions 07600-B
Data sheet 29035

Data sheet 29191

Data sheet 29291

Operating instructions 29391-B

upon request Data sheet 07008 Data sheet 07700

Data sheet 07900