

**RE 29583-XD** 

Edition: 2020-11 Replaces: 04.17 RA88690535\_AA



# **Directional servo valve** with mechanical position feedback

# Type 4WS2EM ...XD



- ▶ Size 10
- ► Component series 5X
- ▶ Maximum operating pressure 315 bar
- Maximum flow 180 l/min



#### **ATEX units**

#### For potentially explosive atmospheres





- ▶ Area of application in accordance with the Explosion Protection Directive 2014/34/EU:
- II 2G Type of protection valve: Ex db IIB T4 Gb according to EN IEC 60079-0 / EN 60079-1 and

IEC 60079-0 / IEC 60079-1

Information on explosion protection:

### **Features**

- ▶ 4 or 3-way version
- For intended use in potentially explosive atmosphere
- Valve for position, force, pressure or velocity control
- ► Subplate mounting
- Porting pattern according to 4401-05-05-0-05
- ▶ Dry control motor, no contamination of the solenoid gaps by the hydraulic fluid
- Wear-free control spool return element
- ▶ Pressure chambers at the control sleeve with gap seal, therefore no wear of seal ring

### **Contents**

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**Notice:** The documentation version with which the product was supplied is valid.



# **Ordering code**

01	02	03		04		05	06	07	80	09	10	11	12	13	14
4WS2E	М	10	-	5X	/		В	11	XD			С		٧	

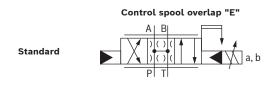
4W	VS2E   M   10   -   5X   /     B   11   XD       C     V					
01	Directional servo valve, 4-way version, 2-stage, electrically operated	4WS2E				
`ont	rol spool return					
02	, ·	М				
03	Size 10	10				
04	Component series 50 59 (50 59: unchanged installation and connection dimensions)	5X				
lom	inal flow					
05		5				
	10 l/min	10				
	20 l/min	20				
	30 l/min	30				
	45 l/min	45				
	60 l/min	60				
	75 l/min	75				
	90 l/min	90				
06		В				
06	6   Control sleeve exchangeable					
07	Valve for <b>external</b> control electronics; coil no. 11 (30 mA/85 $\Omega$ per coil)	11				
vol	osion protection					
08	Type of protection "db"	XD				
00	For details, see information on the explosion protection, page 7	, AD				
Pilot	oil supply					
09	External pilot oil supply, external pilot oil return	-				
	Internal pilot oil supply, external pilot oil return					
	Internal pilot oil supply, internal pilot oil return					
	External pilot oil supply, internal pilot oil return	Т				
nlet	pressure range					
10	10 210 bar	210				
	10 315 bar	315				
Elect	trical connection					
11	Cable connection	С				
Cont	rol spool overlap 1)					
12	0 0.5% negative	E				
	0 0.5% positive					
	3 5% positive	С				
ادما	material (observe compatibility of seals with hydraulic fluid used, see page 6)					
13		V				
Snec	ial versions					
14	Standard	no code				
	Without control (de-energized condition), channels $P \rightarrow B$ and $A \rightarrow T$ are open 10% of the nominal quant					
	Without control (de-energized condition), channels $P \rightarrow A$ and $B \rightarrow T$ are open 10% of the nominal quant					
	Trialoge Control (de energized Condition), Chaimeto F - A and D - 1 are open 10% of the nonlinat quality	102				

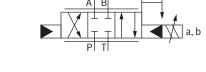
<sup>1)</sup> The control spool overlap is specified in % of the control spool stroke.



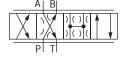
Directional servo valve | **4WS2EM ...XD** 3/16

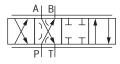
# **Symbols**





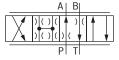


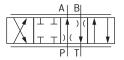




Control spool overlap "C" and "D"

Special version "-102"





M Notice:

Representation according to DIN ISO 1219-1.



## **Function, section**

Valves of type 4WS2EM are electrically operated, 2-stage directional servo valves. They are mainly used to control position, force, pressure or velocity.

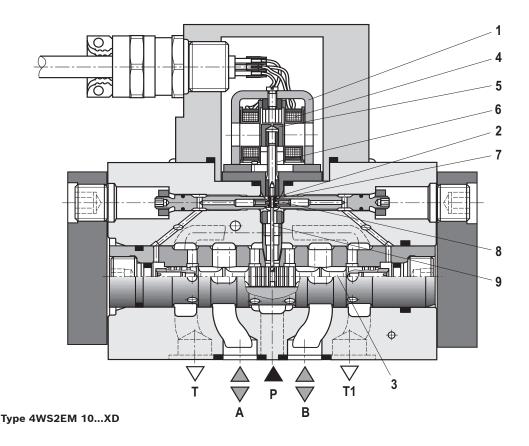
The valves basically comprise of an electro-mechanical converter (torque motor) (1), a hydraulic amplifier (nozzle flapper plate principle) (2) and a control spool (3) in a sleeve (2ndstage) which is connected with the torque motor via a mechanical feedback.

An electrical input signal at the coils (4) of the torque motor generates a force by means of a permanent magnet which acts on the armature (5), and in connection with a torque tube (6) results in a torque. This causes the flapper plate (7) which is connected to the torque tube (6) via a bolt to move from the central position between the two control nozzles (8), and a pressure differential is created across the front sides of the control spool (3). This pressure differential results in the control spool (3) changing its position, which results in the pressure port being connected to one actuator port and, at the same time, the other actuator port being connected to the return flow port.

The control spool (3) is connected to the flapper plate or the torque motor by means of a bending spring (mechanical feedback) (9). The position of the control spool (3) is changed until the feedback torque across the bending spring and the electro-magnetic torque of the torque motor are balanced and the pressure differential at the nozzle flapper plate system becomes zero. The stroke of the control spool (3) and consequently the flow of the servo valve are controlled proportionally to the electrical input signal. It must be noted that the flow

External control electronics (servo amplifier) serve the actuation of the valve, amplifying an analog input signal (command value) so that with the output signal, the servo valve is actuated in a flow-controlled form.

depends on the valve pressure drop.





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# **Technical data**

(for applications outside these values, please consult us!)

General		
Installation position		Any - ensure that during start-up of the system, the valve is supplied with sufficient pressure (≥ 10 bar)
Ambient temperature range	°C	-30 +80
Storage temperature range	°C	+5 +40
Maximum storage time	Years	1
Weight	kg	3.97
Surface protection		Nitro-carburated

Hydraulic										
Operating pressure range	▶ Pilot control valve									
	- Pilot oil supply	bar	10 2	10 or 10	315					
Maximum operating	► Main valve,									
pressure	- Port A, B, P	bar	315							
Maximum return flow ► Port T										
pressure	- Pilot oil return internal	bar	bar Pressure peaks < 100, static < 10							
	- Pilot oil return external	bar	315							
	► Port Y	bar	Pressui	re peaks	< 100,	static <	10			
Hydraulic fluid			See tak	ole page	6					
Hydraulic fluid temperatur	e range	°C	-20	+80, pre	ferably ·	+40 +	50			
Viscosity range		mm²/s	15 3	80; pref	erably 3	0 45				
Maximum admissible degr cleanliness class according	ee of contamination of the hydrau g to ISO 4406 (c)	lic fluid,	Class 1	8/16/13	3 1)					
Zero flow <b>q</b> <sub>V,L</sub>	-	l/min	see characteristic curve on page 9							
Nominal flow $\mathbf{q}_{\text{V nom}}$			5	10	20	30	45	60	75	90
Maximum control spool st position (in case of error)		%	6 120 170 120 150							
Feedback system			mechanical							
Hysteresis (dither-optimize	ed)	%	6 ≤ 1.5							
Range of inversion (dither-	optimized)	%	6 ≤ 0.3							
Response sensitivity (dithe	er-optimized)	%	% ≤ 0.2							
Pressure amplification with 1% control spool stroke change % of $p_P$ (from the hydraulic zero point)			pp ≥ 30 ≥ 60 ≥ 8					≥ 80		
Zero adjustment flow %				ng-term	≤ 5					
across the entire operating pressure range					_					
Zero shift upon change of:										
► Hydraulic fluic	≤ 1									
► Ambient temp	erature	% / 20 °C	≤ 1							
► Operating pres	ssure 80 120% of <b>p</b> <sub>P</sub>	% / 100 bar	≤ 2							
► Return flow pr	ressure 0 10% of <b>p</b> P	% / bar	≤ 1							

<sup>1)</sup> The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and simultaneously increases the life cycle of the components.

Available filters can be found at www.boschrexroth.com/filter.

 $m{q}_{
m V,L}$  = zero flow in l/min  $m{q}_{
m V\,nom}$  = nominal flow in l/min

 $p_{\rm P}$  = operating pressure in bar



# Technical data

(for applications outside these values, please consult us!)

Hydraulic fluid		Classification	Suitable sealing materials	Standards	Data sheet
Mineral oils	'	HL, HLP, HLPD, HVLP, HVLPD	NBR, FKM	DIN 51524	90220
Bio-degradable	► Insoluble in water	HETG	FKM	100 15000	
		HEES	FKM	ISO 15380	90221
	► Soluble in water	HEPG	FKM	ISO 15380	

# Important information on hydraulic fluids:

- ► For further information and data on the use of other hydraulic fluids, please refer to the data sheets above or contact us.
- ► There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.).
- ► The ignition temperature of the hydraulic fluid used must be at least 150 °C.

Electric			
Protection class according	to EN 60529		IP65
Type of signal			analog
Rated current per coil mA		30	
Resistance per coil		Ω	85
Inductivity with 60 Hz and 100% rated current	► Serial connection	Н	1.0
	► Parallel connection	Н	0.25

# Notice:

In case of control using non-Rexroth amplifiers, we recommend a superimposed dither signal.

External control electronics		
Servo amplifier in euro-card format		Type VT-SR2-1X/.60 according to data sheet 29980
Servo amplifier in modular design	analog	Type VT 11021 according to data sheet 29743

# If Important notice:

The external servo amplifier and the safety barrier must be operated outside the potentially explosive atmospheres.



Directional servo valve | 4WS2EM ...XD 7/16

#### **Technical data**

(for applications outside these values, please consult us!)

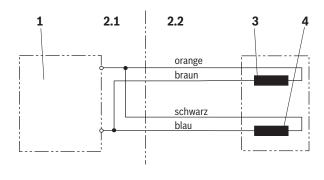
Information on explosion protection					
Area of application according to Directive 2014/34/EU	II 2G				
Type of protection according to EN IEC 60079-0 / EN 60079-1 and IEC 60079-0 / IEC 60079-1	Ex db IIB T4 Gb				
IECEx Certificate of Conformity	IECEx BVS 13.0120 X				
EU type examination certificate	BVS 09 ATEX E 116 X				
Maximum current per coil	mA 100				

## **Special application conditions for safe application:**

For ensuring the type of protection d "flameproof enclosure", the occurrence of explosive atmospheres in the hydraulic area of the valve must be securely avoided. This may be ensured by applying a sufficiently high pilot pressure ( $\geq$  10 bar in channel P and/or X) before applying an electrical signal at the coils or the electronics.

#### **Electrical connection**

### **Example: Parallel connection**



- 1 Control electronics
- 2.1 Non-explosive area
- 2.2 Explosive area
- 3 Valve, coil A
- 4 Valve, coil B

Connection line					
Line type		non-exchangeable, four-wire connection line			
Line cross-section	mm <sup>2</sup>	0.75 finely stranded			
Line diameter	mm	5.9 ±0.3			
Length	m	3			

The electrical connection can be designed as parallel or serial connection. For reasons of operational safety and the resulting lower coil inductivity, we recommend the parallel connection.

### ► Parallel connection:

Connect the "orange" cable connector with "black" and "brown" with "blue".

### ► Serial connection:

Connect the "brown" cable connector with "black".

The electrical control at "orange" (+) and "blue" (-) provides for the direction of flow P  $\rightarrow$  A and B  $\rightarrow$  T. Reverse electrical control provides for direction of flow P  $\rightarrow$  B and A  $\rightarrow$  T.

# Notes:

- ► The free end of the connection cable must be connected as follows according to the construction provisions:
  - outside the potentially explosive area or
  - within the potentially explosive area in terminal boxes of an acknowledged type of protection
- ► Only use finely stranded conductors if they have pressed-on wire end ferrules.

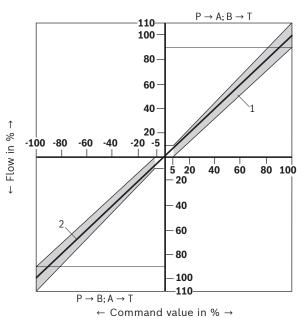


## **Characteristic curves**

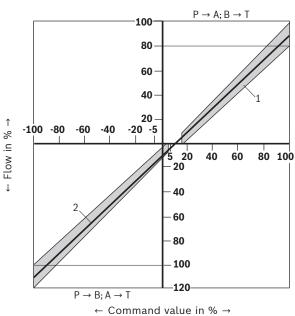
(measured with HLP 32, 9oil = 40 °C ± 5 °C)

Tolerance field of the flow/signal function at constant valve pressure differential  $\Delta p$ 

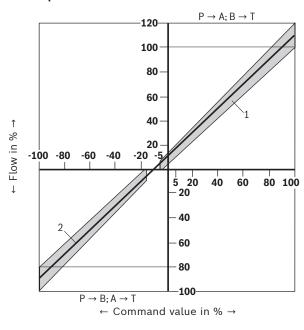
#### Standard



# Special version "-100"



### Special version "-102"



- 1 Tolerance field
- 2 Typical flow curve



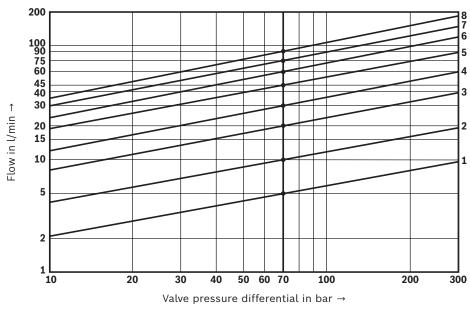
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# **Characteristic curves**

(measured with HLP 32, 3<sub>oil</sub> = 40 °C ± 5 °C)

# Flow/load function

(tolerance ±10%) with 100% command value signal



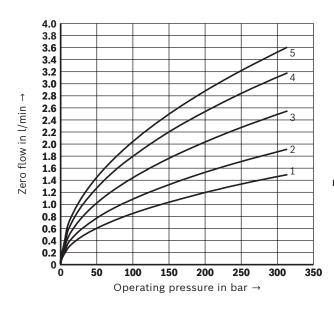
Version	Characteristic curve
"5"	1
"10"	2
"20"	3
"30"	4
"45"	5
"60"	6
"75"	7
"90"	8

### M Notes:

- ► Flow values in the maximum command value range (see "Tolerance field of the flow/signal function")
- ►  $\Delta p = p_P p_L p_T$   $\Delta p$  valve pressure differential  $p_P$  inlet pressure  $p_I$  load pressure

 $p_T$  return flow pressure

Zero flow (with control spool overlap "E", measured without dither signal)



# Nominal flow

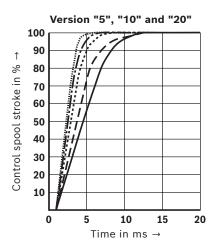
- **1** 5 l/min
- **2** 10 l/min
- **3** 20, 30, 45 l/min
- **4** 60, 75 l/min
- **5** 90 l/min

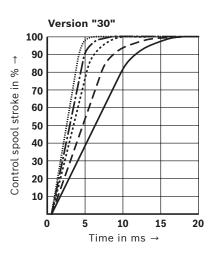


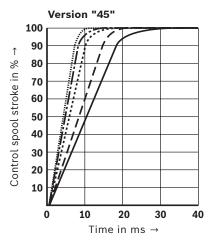
## **Characteristic curves**

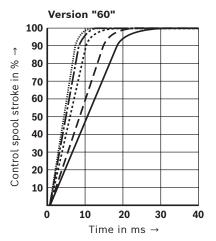
(measured with HLP 32,  $\theta_{oil}$  = 40 °C ± 5 °C)

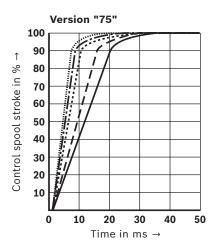
Transition function with pressure rating 315 bar, step response without flow

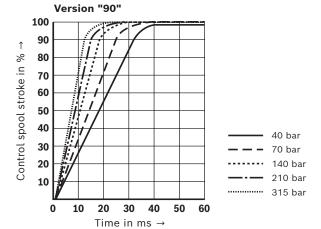












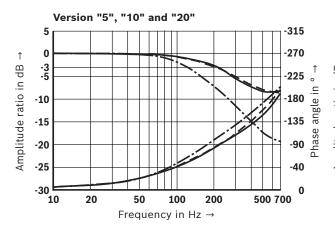


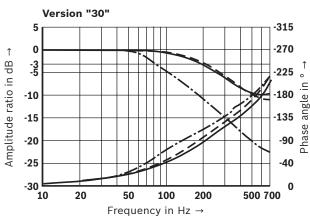
Directional servo valve | 4WS2EM ...XD 11/16

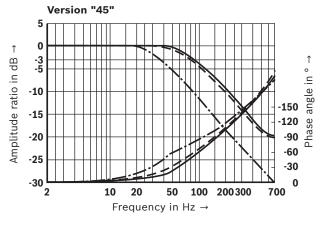
## **Characteristic curves**

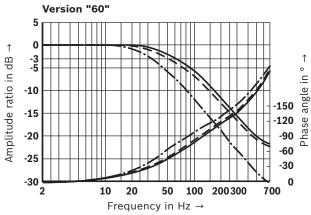
(measured with HLP 32, 9oil = 40 °C ± 5 °C)

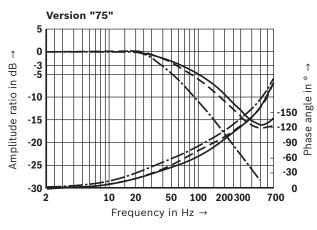
Frequency response with pressure rating 315 bar, stroke frequency without flow

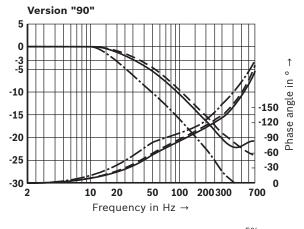












5% --- 25% --- 100%

RE 29583-XD, edition: 2020-11, Bosch Rexroth AG

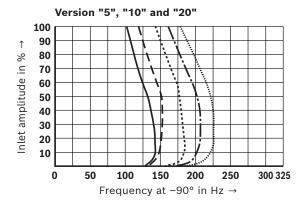
Amplitude ratio in dB

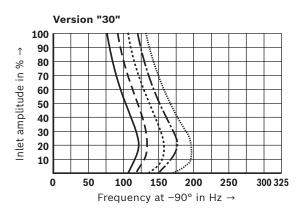


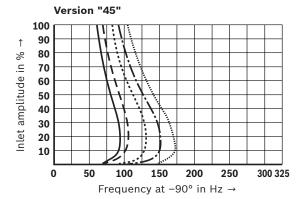
### **Characteristic curves**

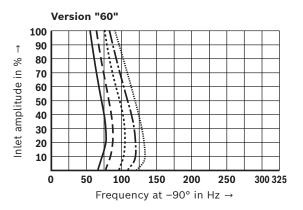
(measured with HLP 32,  $\theta_{oil}$  = 40 °C ± 5 °C)

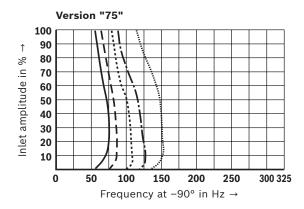
Frequency response with pressure rating 315 bar, stroke frequency without flow

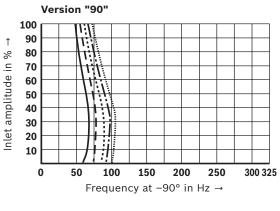














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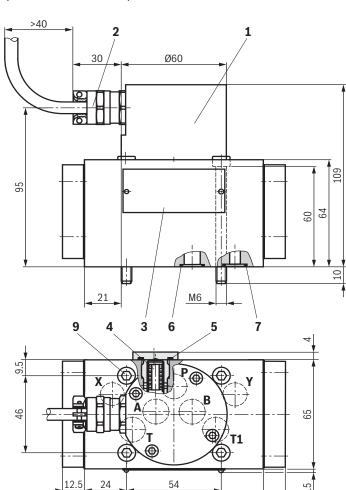
**\_\_\_\_ 0,01/100** 

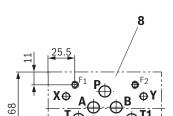
Required surface quality of the valve contact surface

Rzmax 4

#### **Dimensions**

(dimensions in mm)





- **1** Cap
- 2 Cable gland with 3 m cable
- 3 Name plate
- 4 Exchangeable filter element, material no.: R961001950

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- $\mathbf{5}$  Profile seal for filter screw M16 x 1.5 (part of item 4)
- 6 Identical seal rings for ports P, A, B, T and T1
- 7 Identical seal rings for ports X and Y; Ports X and Y are also pressurized in case of "internal" pilot oil supply and return
- 8 Machined valve contact surface; Porting pattern according to ISO 4401-05-05-0-05; Port T1 is optional and is recommended for reducing the pressure drop from B → T with rated flows > 45 l/min.

9 Valve mounting screws (included in the scope of delivery) Only use valve mounting screws with the subsequently listed thread diameters and strength properties. Observe the screw-in depth.

105

4 hexagon socket head cap screws ISO 4762 · M6 x 70 · 10.9 (Friction coefficient  $\mu_{\text{total}}$  = 0.09 ... 0.14) Tightening torque  $M_A$  = 12.5 Nm ± 1.5 Nm

**Subplates** (separate order) with porting pattern according to ISO 4401-05-05-0-05, see data sheet 45100.

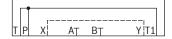
# Notes:

- ► The dimensions are nominal dimensions which are subject to tolerances.
- ➤ Subplates are no components in the sense of Directive 2014/34/EU and can be used after the manufacturer of the overall system has conducted an assessment of the risk of ignition. The "G...J3" versions are free from aluminum and/or magnesium and galvanized.



**Flushing plate** with porting pattern according to ISO 4401-05-05-0-05 (dimensions in mm)

# Symbol



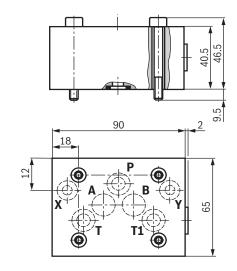
# Ordering code and further information

- ▶ Material number **R901541299**
- ▶ Weight 2.0 kg
- ▶ Identical seal rings for ports P, A, B, T and T1
- ▶ Identical seal rings for ports X and Y
- ► Mounting screws (included in the scope of delivery)
  For reasons of stability, exclusively the following mounting screws
  are to be used:

4 hexagon socket head cap screws ISO 4762 - M6 x 50 - 10.9

(friction coefficient  $\mu_{\text{total}} = 0.09 \dots 0.14$ );

Tightening torque  $M_A$  = 12.5 $\pm$ 1.5 Nm



# Motice:

Before assembly and operation, please observe the information in the  $29583\text{-}\mathrm{XD}\text{-}\mathrm{B}$  operating instructions.



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# **Further information**

Analog amplifier module type VT 11021
 Analog amplifier type VT-SR2-1X/.60
 Subplates
 Hydraulic fluids on mineral oil basis
 Environmentally compatible hydraulic fluids
 Use of non-electrical hydraulic components in an explosive environment (ATEX)
 Data sheet 29743
 Data sheet 29980
 Data sheet 45100
 Data sheet 90220
 Data sheet 90221
 Data sheet 07011

▶ Selection of filters

► Information on available spare parts