

Industrial
Hydraulics

Electric Drives
and Controls

Linear Motion and
Assembly Technologies

Pneumatics

Service
Automation

Mobile
Hydraulics

Rexroth
Bosch Group

RE 29 069/02.03

Replaces: 12.99

4/3 and 4/4 high response directional control valves, direct operated, with electrical position feedback Type 4WRSEH

Nominal sizes 6 and 10

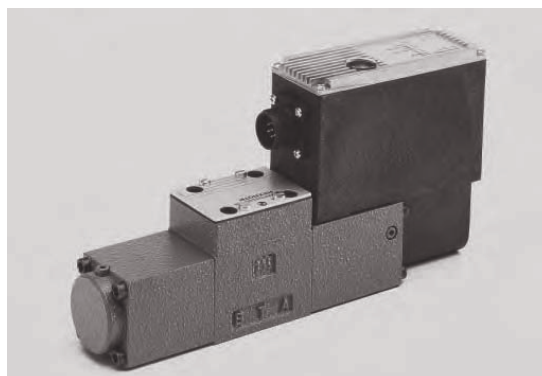
Series 3X

Maximum operating pressure 315 bar

Maximum flow 80 L/min (NS 6)

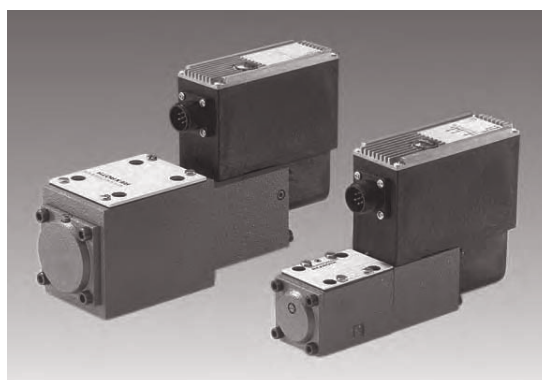
Maximum flow 180 L/min (NS 10)

H/A 5276/95



Type 4WRSEH 6 V...D-3X/... (4/3 high response directional control valve)

H/A 5544/96



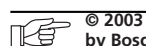
Types 4WRSEH 10 C.B...D-3X/... and 4WRSEH 6 C.B...D-3X/... (4/4 high response directional control valve)

Overview of contents

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Features

- Direct operated high response directional control valve for the control of the size and direction of a flow
- Valve spool and bush are of servo quality
- Suitable for closed loop, position, speed and pressure control
- Operated via high response solenoids
- With fail-safe position for the 4/4 high response directional control valve
- Electrical position feedback
- High response sensitivity and low hysteresis
- Integrated control electronics with interface A1 or F1
- For subplate mounting:
Porting pattern to DIN 24 340 form A, ISO 4401 and CETOP-RP 121 H
Subplates to catalogue sheets RE 45 052 and RE 45 054 (separate order), see pages 14 to 17

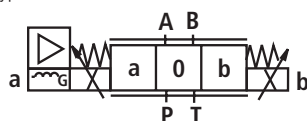


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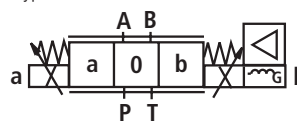
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Symbols

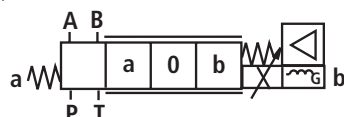
Type 4WRSEH.V...-3X/...



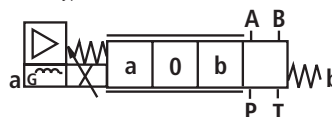
Type 4WRSEH.VC...-3X/...



Type 4WRSEH.C.B...-3X/...



Type 4WRSEH.C...-3X/...



Function, section

The 4/3 and 4/4 high response directional control valves are designed as direct operated units of subplate mounting design. They are operated by high response solenoids. The solenoids are controlled via the integrated control electronics.

Design:

The valve basically comprises of:

- Housing (1) with mounting surface
- Control spool (2) in bush (3) with compression springs (4 and 5)
- Solenoids (6 and 7)
- Position transducer (8)
- Integrated control electronics (9)
- Zero point adjustment accessible (10) via Pg9

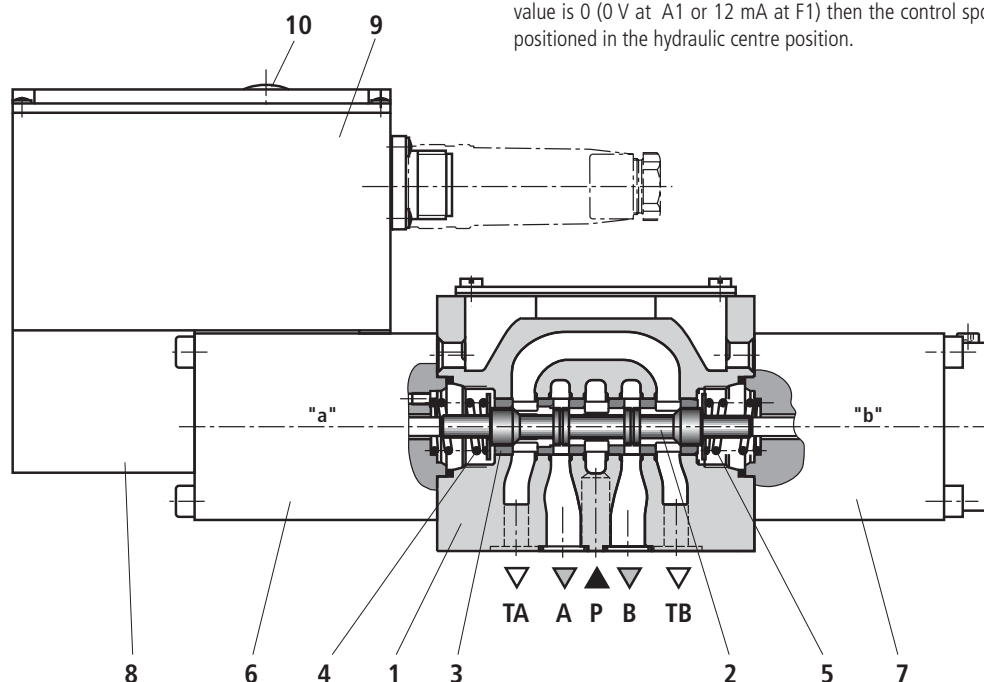
Functional description:

4/3-way version

- With solenoids (6 and 7), de-energised the control spool (2) is held in its mechanical centre position by the compression springs (4 and 5)
- Direct operation of the control spool (2) by the energisation of one of the high response solenoids
- E.g. control of solenoid "b" (7)
 - Moves the control spool (2) to the left in proportion to the electrical input signal
 - Connection from P to A and B to T via orifice type cross-sections with linear or inflected flow characteristics
- By de-energising the solenoid (7) → control spool (2) is returned to its centre position via the compression spring (4)

In the de-energised condition the control spool (2) is held in a mechanical centre position via the control springs. This does not relate to the hydraulic centre position!

By closing the electrical valve closed loop circuit and the command value is 0 (0 V at A1 or 12 mA at F1) then the control spool (2) is positioned in the hydraulic centre position.



Type 4WRSEH 10 V...-3X/...

Function, section

4/4-way version

The function of these valves is basically the same as the 4/3-way version. However, when the solenoid is de-energised the control spool is moved into a fail-safe position via a compression spring.

The 4/4 high response directional control valves are designed as direct operated units of subplate mounting design. They are operated by high response solenoids. The solenoids are controlled via the integrated control electronics.

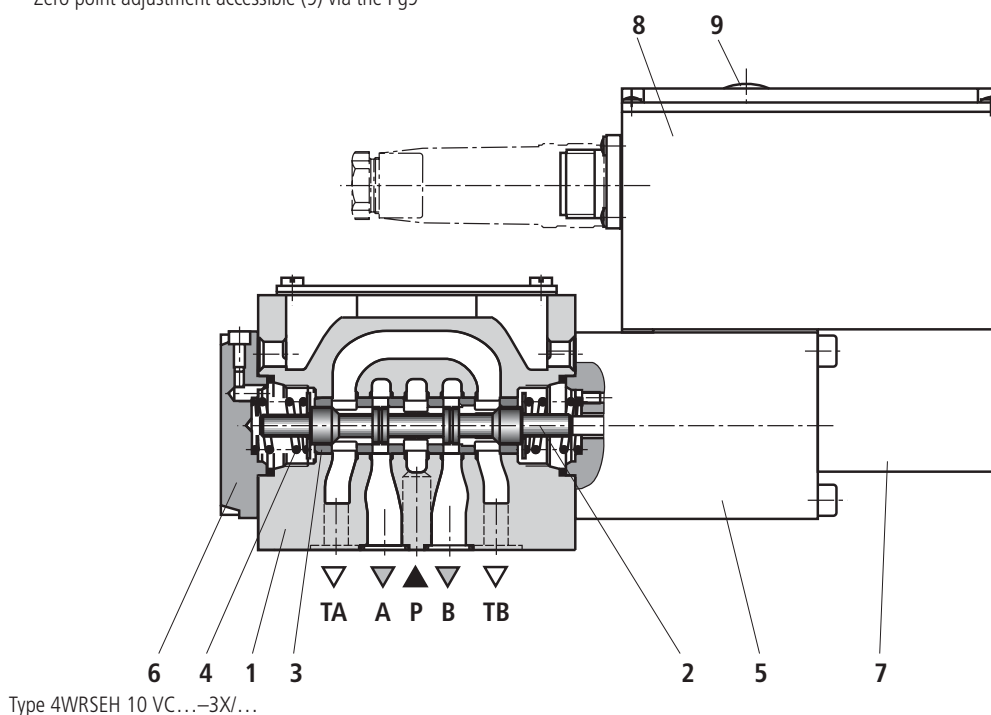
Design:

The valve basically comprises of:

- Housing (1) with mounting surface
- Control spool (2) in bush (3) with compression springs (4)
- Solenoid (5) and cover (6)
- Position transducer (7)
- Integrated control electronics (8)
- Zero point adjustment accessible (9) via the Pg9

Functional description:

- With the solenoid (5) de-energised, a fail-safe position for the control spool (2) via compression spring (4) results
 - Direct operation of the control spool (2) by the energisation of the high response solenoid (5)
- E.g. control of the solenoid
- Moves the control spool (2) in proportion to the electrical input signal
 - Connection from P to A and B to T via orifice type cross-sections with linear or inflected flow characteristics
- By de-energising the solenoid (5) → the control spool (2) is moved back into the fail-safe condition via the compression spring (4)



Technical data (for applications outside these applications, please consult us!)

General			NS 6	NS 10
Installation			Optional, preferably horizontal	
Storage temperature range		°C	– 20 to + 80	
Ambient temperature range		°C	– 20 to + 50	
Weight	Valve with 1 solenoid	kg	2.3	6.0
	Valve with 2 solenoids	kg	3.0	7.3

Hydraulic (measured at $p = 100$ bar, $v = 46$ mm²/s and $\vartheta = 40$ °C)

Operating pressure	Ports A, B, P	bar	up to 315				up to 315	
	Port T	bar	up to 315				up to 210	
Application limits C3, C4	Nominal flow	L/min	04	12	24	40	50	100
¹⁾ The details for C4 are	Application limit Δp with symbol C3	bar	315	315	315	160	250	150
only preliminary details!	Application limit Δp with symbol C4 ¹⁾	bar	315	315	200	100	150	100
Nominal flow $q_{V\text{ nom}} \pm 10\%$ at $\Delta p = 70$ bar Δp = valve pressure differential		L/min	4				50	
							12 100	
			24				–	
			50 (with V spool with flow „L“); 40 (with C and V spools with flow characteristic „P“)				–	
Max. permissible flow		L/min	80				180	
Pressure fluid			Mineral oil (HL, HLP) to DIN 51 524 and phosphate ester (HFD-R), further pressure fluids on request					
Degree of contamination			Maximum permissible degree of pressure fluid contamination to NAS 1638				A filter with a minimum retention rate of $\beta_x \geq 75$ is recommended	
			Class 7				x = 10	
Pressure fluid temperature range		°C	– 20 to + 80					
Viscosity range		mm ² /s	20 to 380, preferably 30 to 46					
Hysteresis		%	< 0.05					
Reversal span		%	< 0.03					
Response sensitivity		%	< 0.03					

Electrical

Valve protection to DIN 40 050		IP 65	
Voltage type		DC	
Signal type		analogue	
Zero point alignment		%	≤ 1
Zero point displacement with changes to:		NS 6	
		NS 10	
Pressure fluid temperature		%/10 K	< 0.15
Operating pressure		%/100 bar	< 0.1
			< 0.05
Electrical connection		With component plug to E DIN 43 563 AM6	
2) separate order, see page 6		Plug-in connector to E DIN 43 563-BF6-3/Pg11 2)	
Control electronics		VT 13070 (integrated into the valve, see page 7)	

 **Note:** For details regarding the **environmental simulation test** covering EMC (electro-magnetic compatibility), climate and mechanical loading see RE 29 069-U (declaration regarding environmental compatibility).

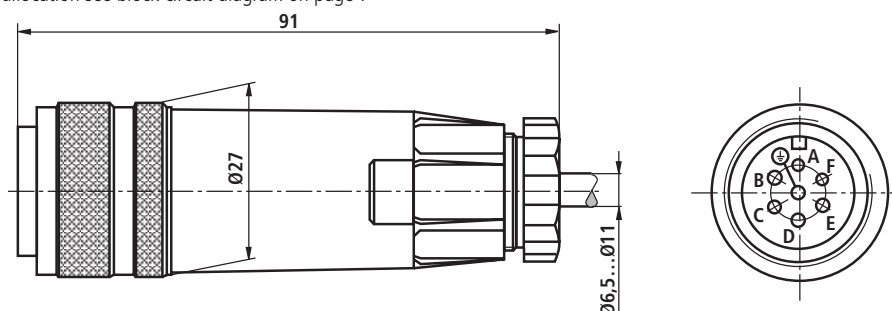
Electrical connections, plug-in connector

Plug-in connector

Plug-in connector to E DIN 43 563-BF6-3/Pg11

Separate order under material No. **00021267** (plastic version)

For pin allocation see block circuit diagram on page 7

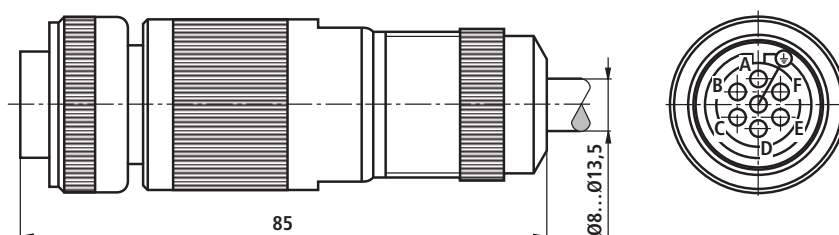


Plug-in connector

Plug-in connector to E DIN 43 563-BF6-3-Pg13.5

Separate order under material No. **000223890** (metal version)

For pin allocation see block circuit diagram on page 7



Component plug allocation

	Contact	Signal
Supply voltage	A	24 VDC ($u(t) = 19.4 \text{ V to } 35 \text{ V}$); $I_{\text{max}} = 2 \text{ A}$ (NS 6) $I_{\text{max}} = 2.8 \text{ A}$ (NS 10); impulse load = 4 A
	B	0 V
Ref. (actual value)	C	Ref. potential for actual value (contact F); A1: $R_e > 50 \text{ k}\Omega$ F1: $R_e < 10 \Omega$
Differential amplifier input (command value)	D	A1: $\pm 10 \text{ V}$ command value, $R_e > 50 \text{ k}\Omega$ or F1: 4...20 mA, $R_e > 100 \Omega$
	E	0 V ref. potential
Measurement output (act. value)	F	$\pm 10 \text{ V}$ actual value (limiting load 2 mA); or F1: 4...20 mA, max. load impedance 500 Ω
	PE	Connected with cooling body and valve housing

Actual value: Interface A1: A positive signal at F and the reference potential at C results in a flow from P to A.

Note for A1: Connect pin C on the control side (star form) with $\perp$.

Interface F1: 12...20 mA results in a flow from P to A.

Command value: A positive command value at D (interface A1) or 12...20 mA (interface F1) and the reference potential at E results in a flow from P to A and B to T.

A negative command value at D (interface A1) or 12...4 mA (interface F1) and the reference potential at E results in a flow from P to B and A to T.

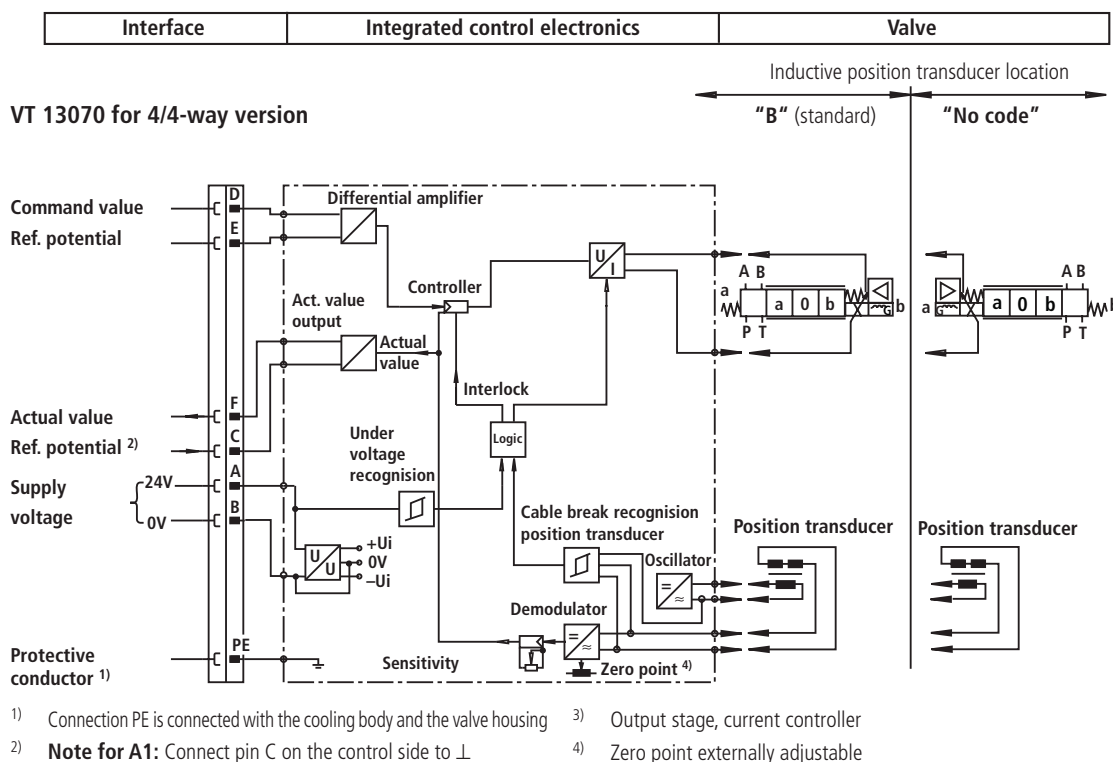
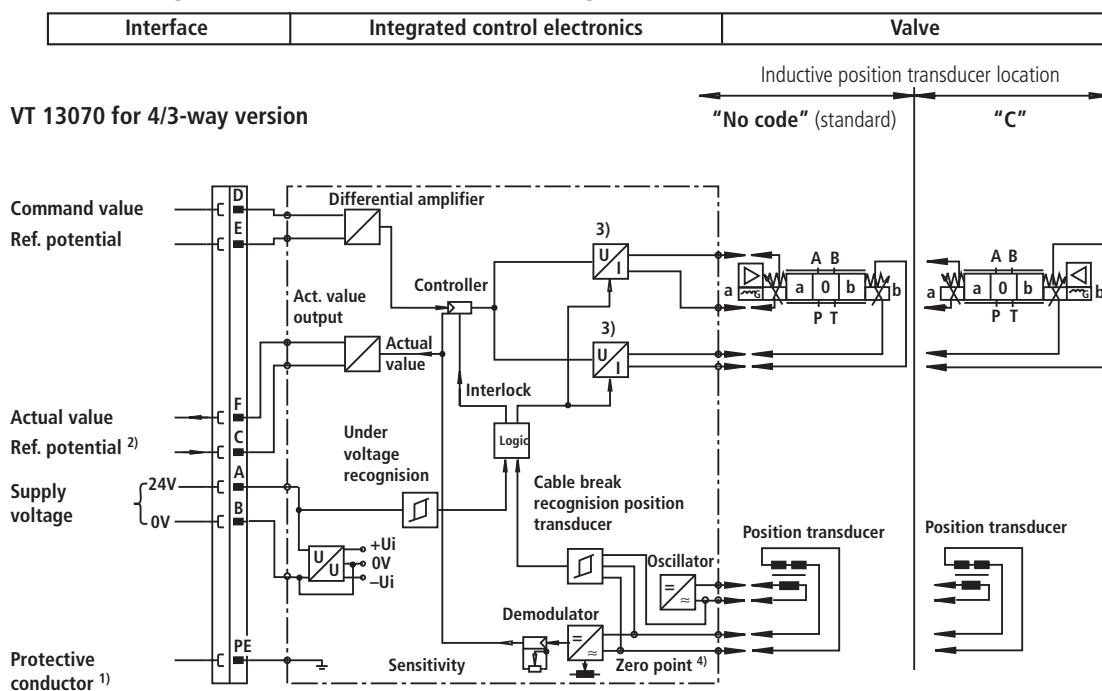
Connection cable: Recommended: – up to 25 m cable length type LiYCY 7 x 0.75 mm²
– up to 50 m cable length type LiYCY 7 x 1.0 mm²

Outside diameter 6.5 to 11 mm

Only connect the screen to $\perp$ on the supply side.

Integrated control electronics VT 13070

Block circuit diagram / connection allocation for the integrated control electronics



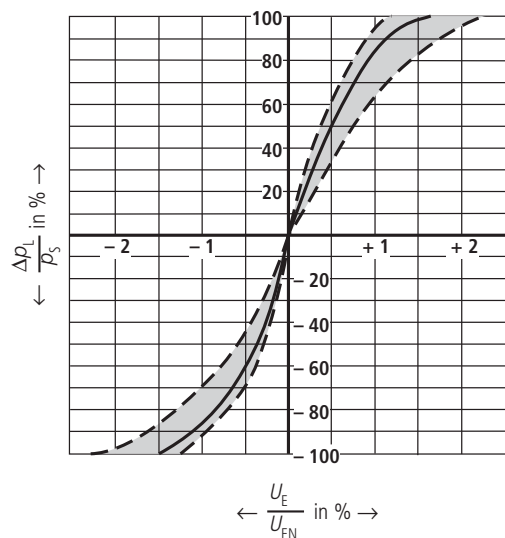
Note: Electrical signal (e.g. actual value) taken via valve electronics must not be used to switch off the machine safety functions!
(This is in accordance with the regulations to the European standard "Safety requirements of fluid technology systems and components – hydraulics", EN 982!)

Characteristic curves (measured at $\nu = 46 \text{ mm}^2/\text{s}$ and $\vartheta = 40 \text{ }^\circ\text{C}$)

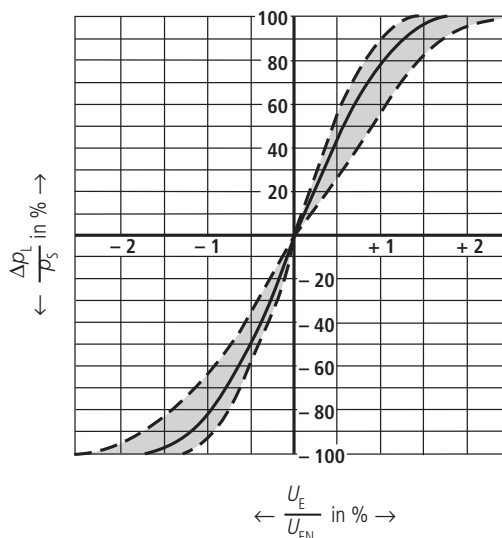
NS 6 and 10

Pressure-signal-characteristic curve $p_s = 100 \text{ bar}$

NS 6 Type 4WRSEH 6 ... L-3X/...

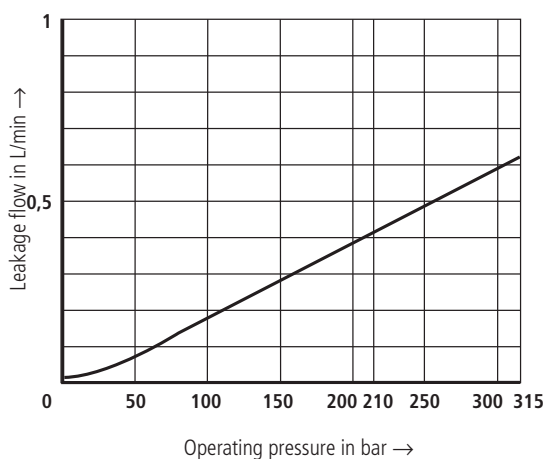


NS 10 Type 4WRSEH 10 ... L-3X/...

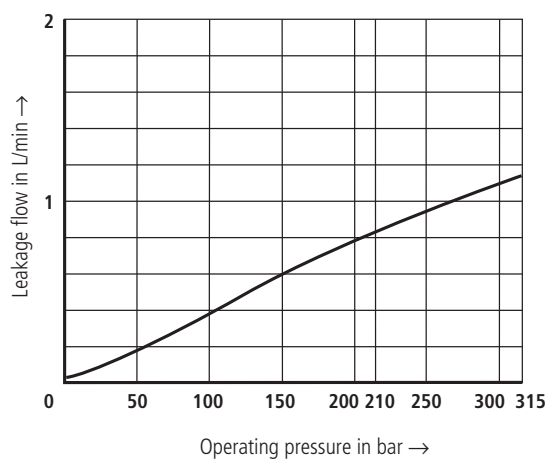


Leakage flow (typical)

NS 6 Type 4WRSEH 6 V50 L-3X/...

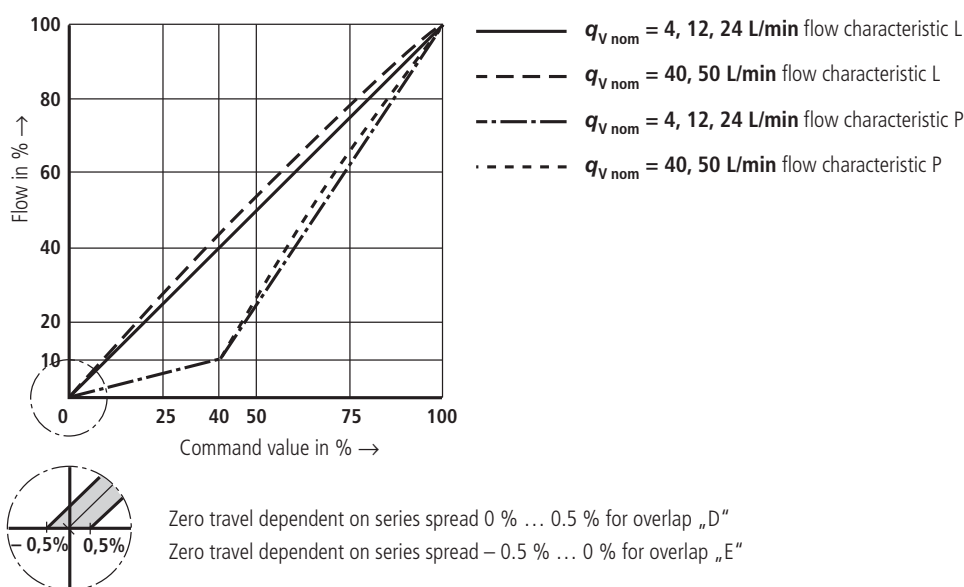


NS 10 Type 4WRSEH 10 V100 L-3X/...

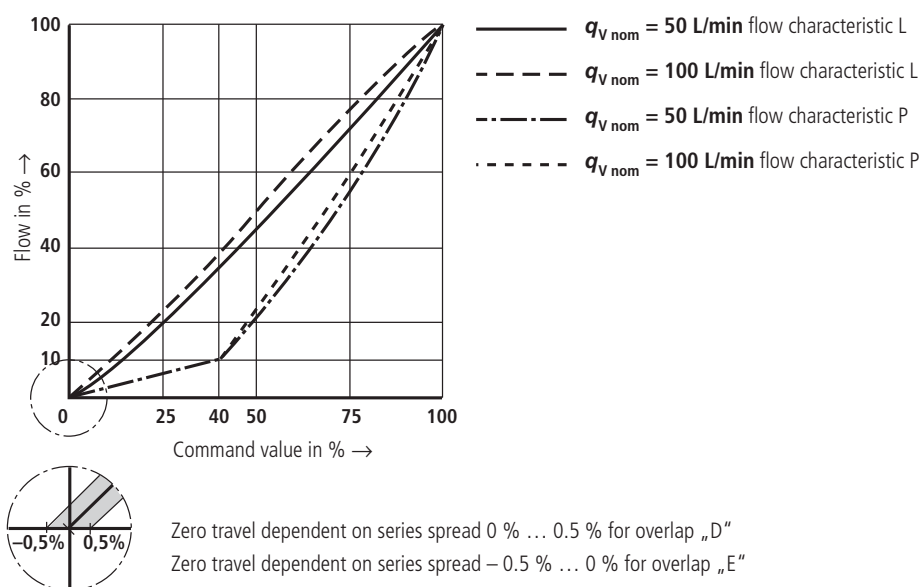


Characteristic curves (typical flow characteristic curve at 70 bar valve pressure differential or 35 bar per control land)

NS 6



NS 10

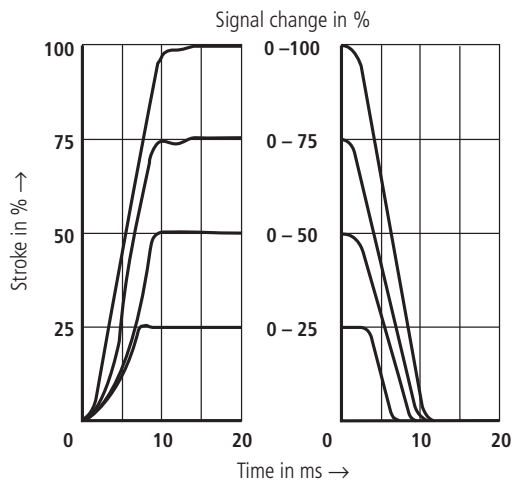


Characteristic curves (measured at: $p_s = 10 \text{ bar}$; $v = 46 \text{ mm}^2/\text{s}$; $\vartheta = 40^\circ \text{C}$)

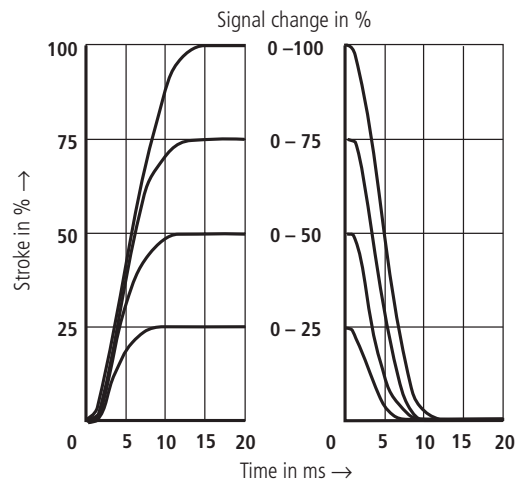
NS6

Transient function with a jump form of electrical input signal

4/3-way version

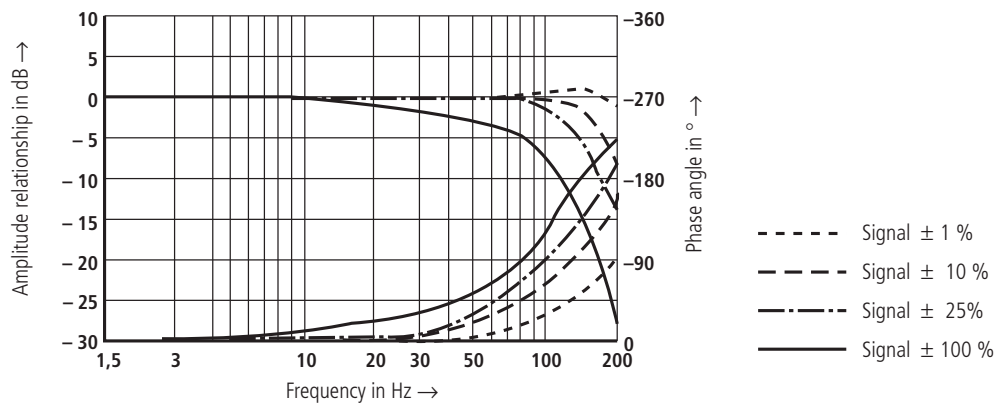


4/4-way version

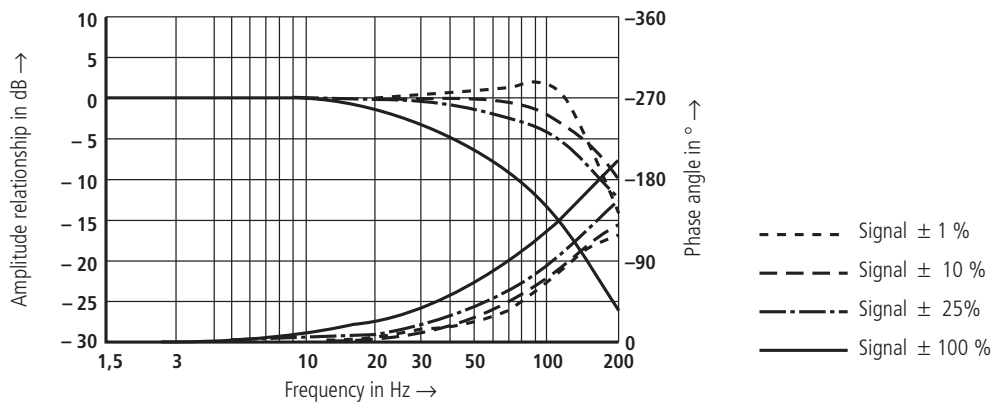


Frequency response characteristic curves

4/3-way version



4/4-way version

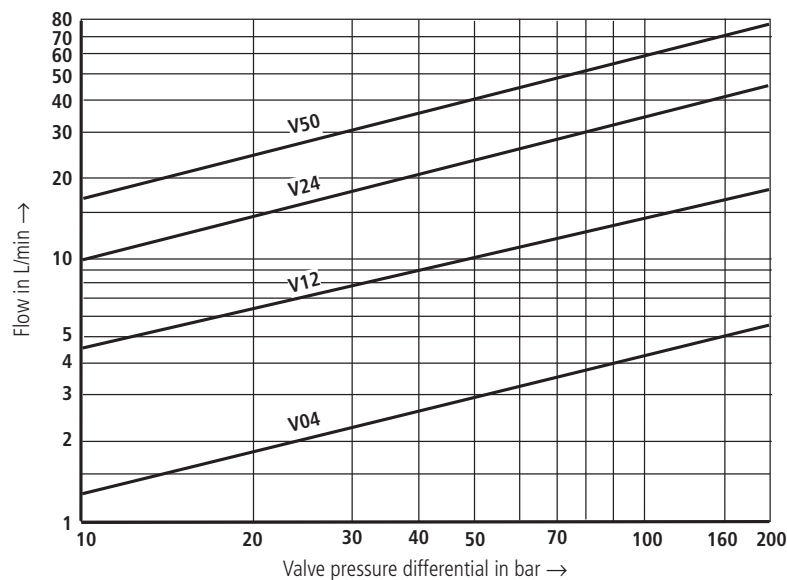


Characteristic curves (measured at: $p_s = 10$ bar; $v = 46$ mm²/s; $\vartheta = 40$ °C)

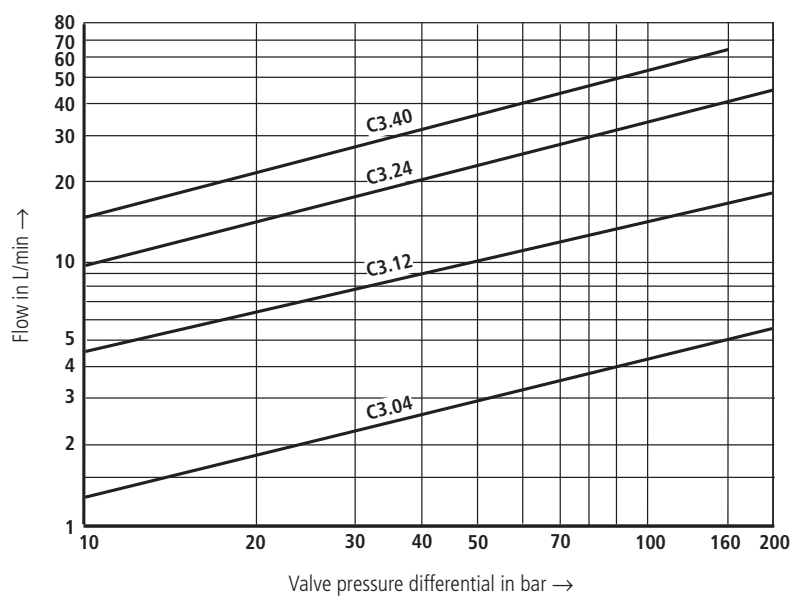
NS6

Flow-load function at the max. valve opening (tolerance $\pm 10\%$)

4/3-way version



4/4-way version

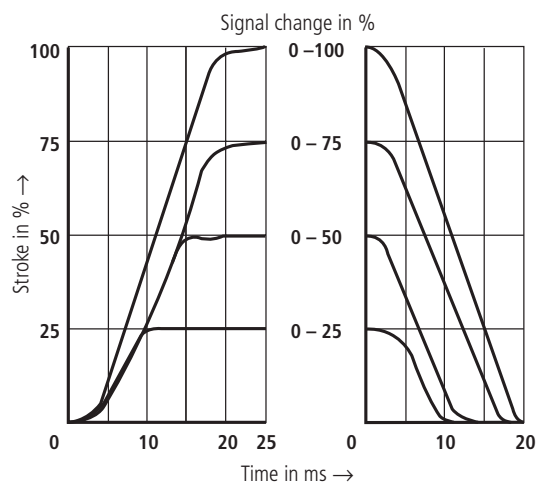


Characteristic curves (measured at: $p_s = 10 \text{ bar}$; $v = 46 \text{ mm}^2/\text{s}$; $\vartheta = 40^\circ \text{C}$)

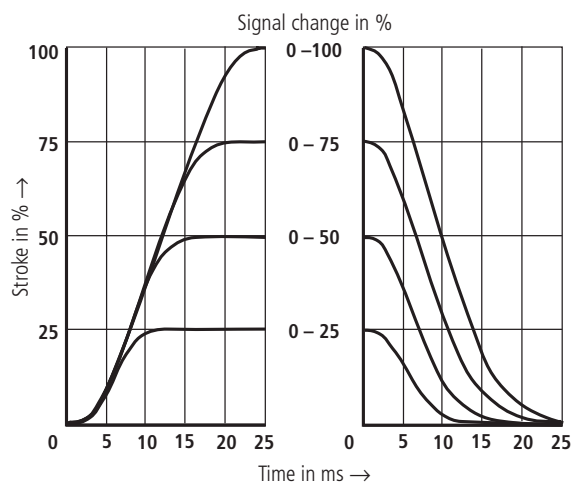
NS10

Transient function with a jump form of electrical input signal

4/3-way version

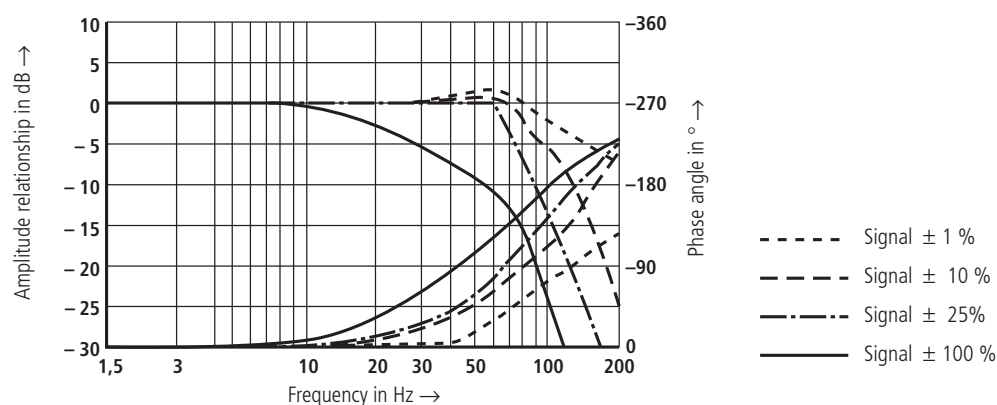


4/4-way version

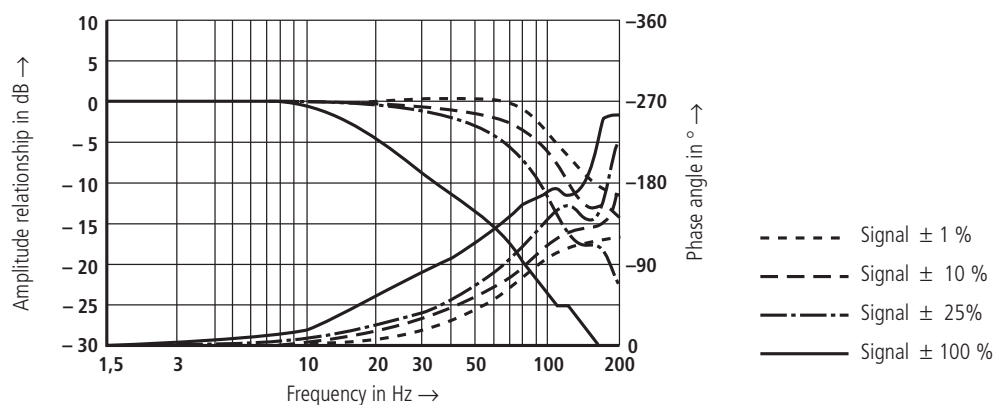


Frequency response characteristic curves

4/3-way version



4/4-way version

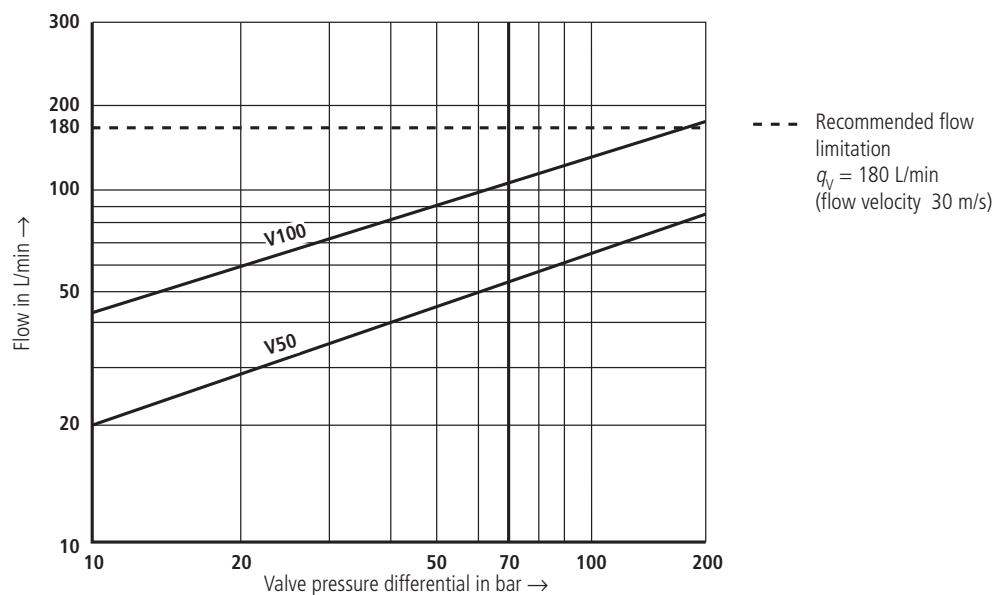


Characteristic curves (measured at: $p_s = 10$ bar; $v = 46$ mm²/s; $\vartheta = 40$ °C)

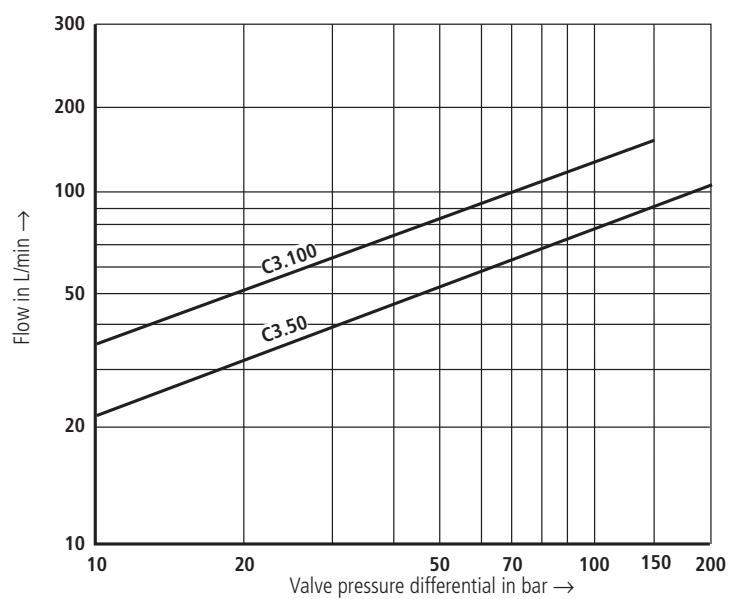
NS10

Flow-load function at the max. valve opening (tolerance $\pm 10\%$)

4/3-way version



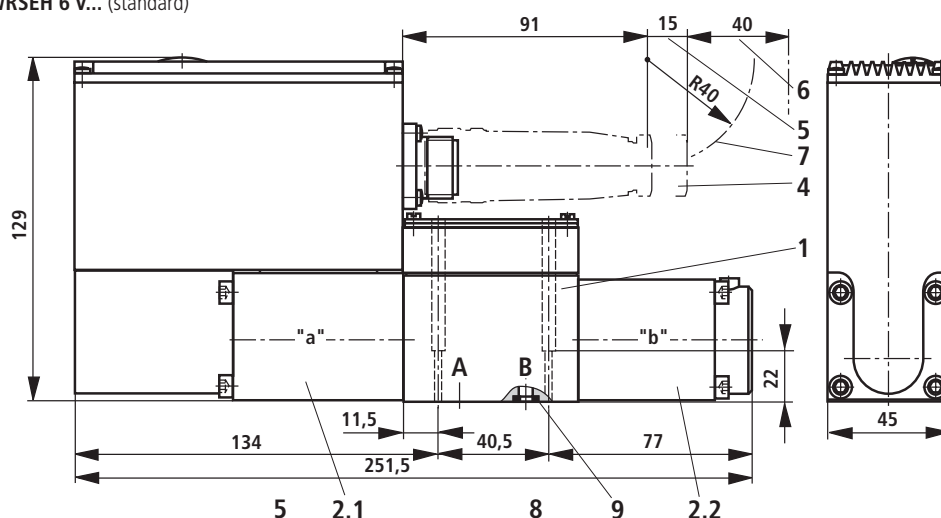
4/4-way version



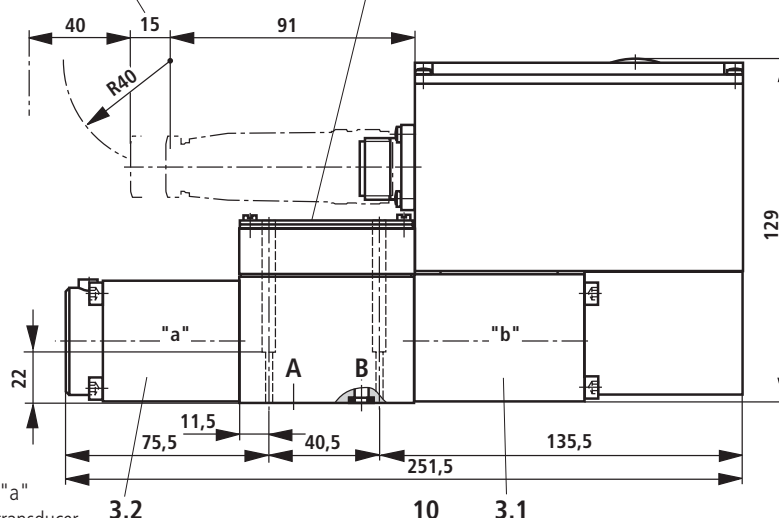
Unit dimensions: NS 6

(Dimensions in mm)

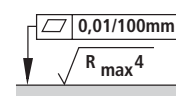
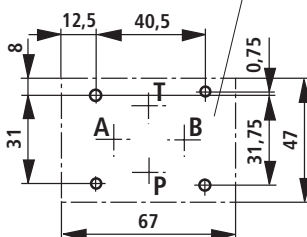
Type 4WRSEH 6 V... (standard)



Type 4WRSEH 6 VC..



- 1 Valve housing
- 2.1 High response solenoid "a" with inductive position transducer
- 2.2 High response solenoid "b"
- 3.1 High response solenoid "b" with inductive position transducer
- 3.2 High response solenoid "a"
- 4 Plug-in connector to E DIN 43 563 BF6-3/Pg11 (separate order, see page 6)
- 5 Space required to remove the plug-in connector
- 6 Space required for the cable bend radius when removing the plug-in connector
- 7 Cable bend radius
- 8 Name plate
- 9 R-ring 9.81 x 1.5 x 1.78 (ports A, B, P, T)
- 10 Machined valve mounting surface, position of ports to DIN 24 340 form A, ISO 4401 and CETOP-RP 121 H



Required surface finish of mating piece

Subplates to catalogue sheet RE 45 052 and valve fixing screws must be ordered separately.

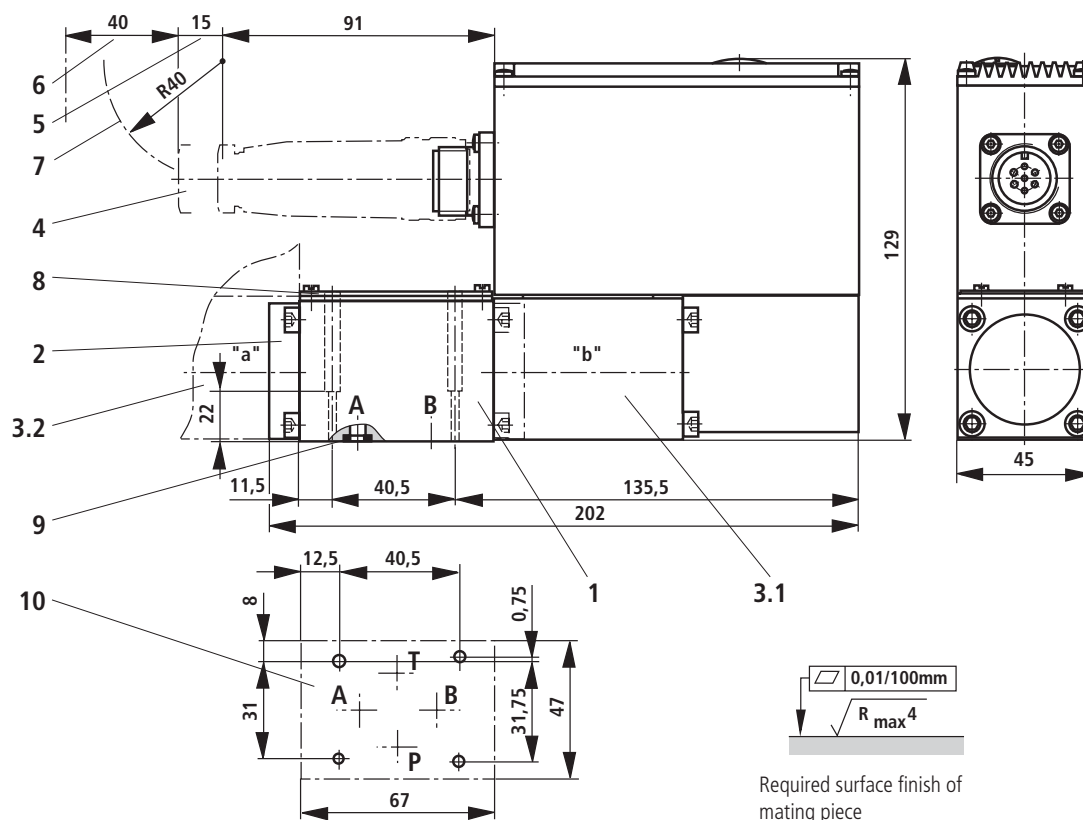
Subplates: G 341/01 (G 1/4)
G 342/01 (G 3/8)
G 502/01 (G 1/2)

Valve fixing screws:
4 off M5 x 30 DIN 912-10.9; $M_A = 7.1 \text{ Nm}$

Unit dimensions: NS 6

(Dimensions in mm)

Type 4WRSEH 6 C.B...



- 1 Valve housing
- 2 Cover
- 3.1 High response solenoid „b“ with inductive position transducer
- 3.2 High response solenoid „a“ with inductive position transducer
- 4 Plug-in connector to E DIN 43 563 BF6-3/Pg11 (separate order, see page 6)
- 5 Space required to remove the plug-in connector
- 6 Space required for the cable bend radius when removing the plug-in connector
- 7 Cable bend radius
- 8 Name plate
- 9 R-ring 9.81 x 1.5 x 1.78 (ports A, B, P, T)
- 10 Machined valve mounting surface, position of ports to DIN 24 340 form A, ISO 4401 and CETOP-RP 121 H

Subplates to catalogue sheet RE 45 052 and valve fixing screws must be ordered separately.

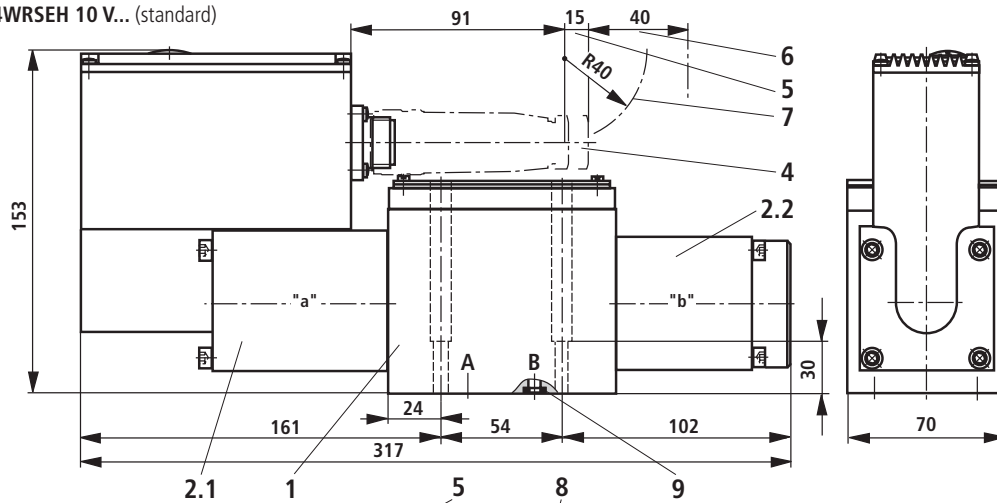
Subplates:
G 341/01 (G 1/4)
G 342/01 (G 3/8)
G 502/01 (G 1/2)

Valve fixing screws:
4 off M5 x 30 DIN 912-10.9; $M_A = 7.1 \text{ Nm}$

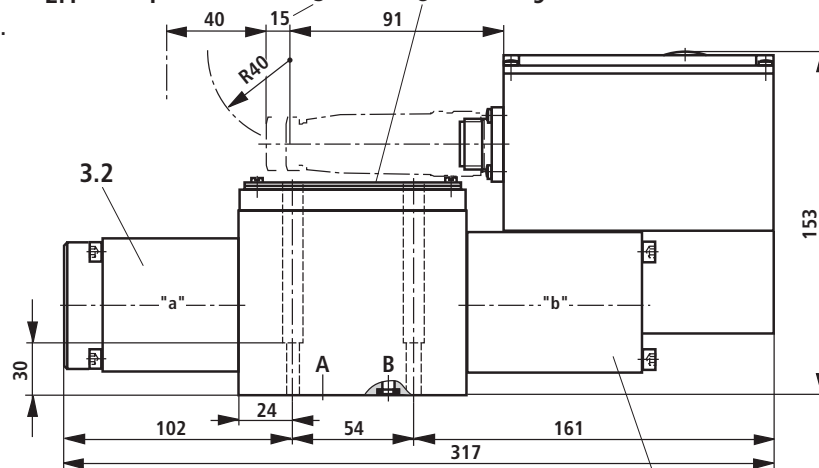
Unit dimensions: NS 10

(Dimensions in mm)

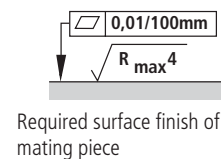
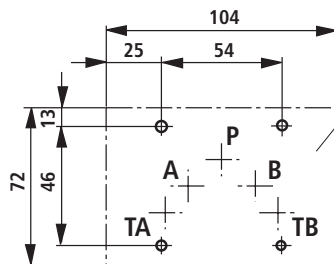
Type 4WRSEH 10 V... (standard)



Type 4WRSEH 10 .VC..



- 1 Valve housing
- 2.1 High response solenoid "a" with inductive position transducer
- 2.2 High response solenoid "b"
- 3.1 High response solenoid "b" with inductive position transducer
- 3.2 High response solenoid "a"
- 4 Plug-in connector to E DIN 43 563-BF6-3/Pg11 (separate order, see page 6)
- 5 Space required to remove the plug-in connector
- 6 Space required for the cable bend radius when removing the plug-in connector
- 7 Cable bend radius
- 8 Name plate
- 9 R-ring 13.0 x 1.6 x 2.0 (ports A, B, P, T)
- 10 Machined valve mounting surface, position of ports to DIN 24 340 form A, ISO 4401 and CETOP-RP 121 H



Subplates to catalogue sheet RE 45 054 and valve fixing screws must be ordered separately.

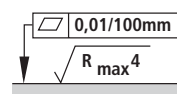
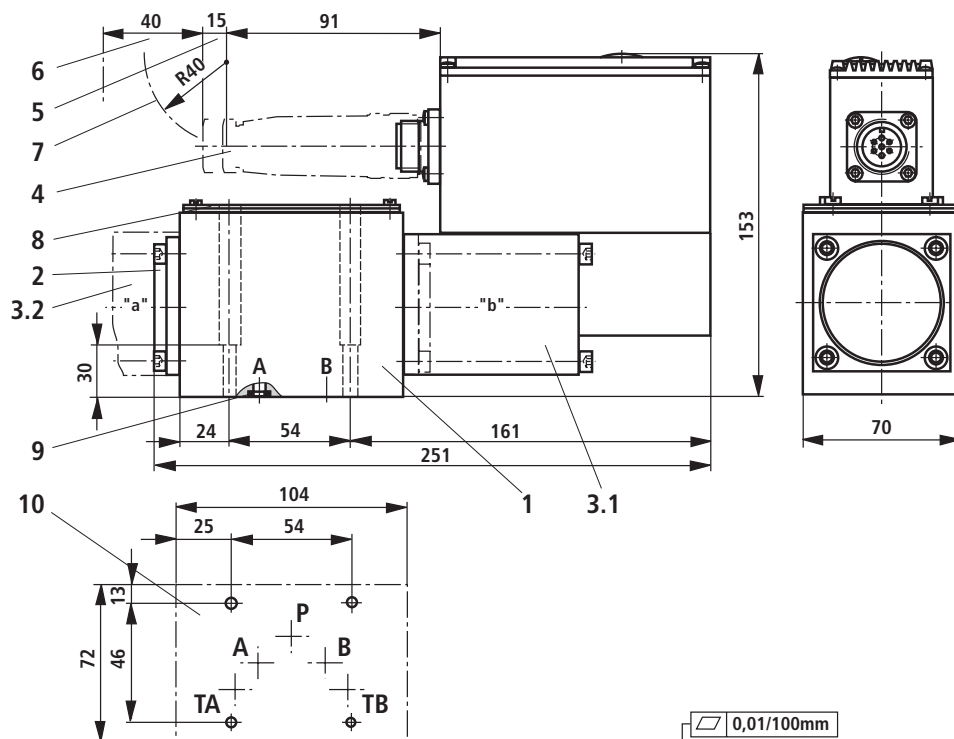
Subplates: G 66/01 (G 3/8); G 67/01 (G 1/2)
G 534/01 (G 3/4)

Valve fixing screws:
4 off M6 x 40 DIN 912-10.9; $M_A = 12.2 \text{ Nm}$

Unit dimensions: NS 10

(Dimensions in mm)

Type 4WRSEH 10 C.B...



Required surface finish of mating piece

- 1 Valve housing
- 2 Cover
- 3.1 High response solenoid „b“ with inductive position transducer
- 3.2 High response solenoid „a“ with inductive position transducer
- 4 Plug-in connector to E DIN 43 563-BF6-3/Pg11 (separate order, see page 6)
- 5 Space required to remove the plug-in connector
- 6 Space required for the cable bend radius when removing the plug-in connector
- 7 Cable bend radius
- 8 Name plate
- 9 R-ring 13.0 x 1.6 x 2.0 (ports A, B, P, T)
- 10 Machined valve mounting surface, position of ports to DIN 24 340 form A, ISO 4401 and CETOP-RP 121 H

Subplates to catalogue sheet RE 45 054 and valve fixing screws must be ordered separately.

Subplates: G 66/01 (G 3/8); G 67/01 (G 1/2)
G 534/01 (G 3/4)

Valve fixing screws:
4 off M6 x 40 DIN 912-10.9; $M_A = 12.2 \text{ Nm}$

Notes

The data specified above only serves to describe the product. No statements concerning a certain condition or suitability for a certain application can be derived from our information. The details stated do not release you from the responsibility for carrying out your own assessment and verification. It must be remembered that our products are subject to a natural process of wear and ageing.
