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Issue 9-17 E WS 5.450

Workholding Systems MC-P Z Balance, Position Flexible mechanically operated, jaw widths 60, 100 and 125 mm



Application

Besides 5-axis machining and concentric clamping, the position flexible workholding system MC-P Balance offers the solution for individual or series clamping of bars, rails, profiles, guide rails or housings. The compensating function avoids tensioning and deformation on the workpiece.

Also workpieces that are fixed by internal contours or positioning elements can be clamped concentrically. For this purpose, customer-specific dowel holes or tapped holes can be provided in the guide bars of the MC-P Balance in which the workpiece supports or stops can be fixed.

Accessories

- Clamping jaws and jaw inserts, accessories for mounting, positioning and operation see data sheet WS 5.450Z
- Rapid change block Quintus see data sheet WS 5.6150

Application example



Clamping of aluminium bars with workholding system MC-P 100 Z Balance.

Advantages

Patented segment design

- Clamping without deformation of workpieces by position flexible clamping point
- Clamping system also suitable for concentric clamping
- Compact design
- High precision and accuracy of the manufactured workpieces by high rigidity
- Sturdy design and good swarf protection
- Large iaw openings
- Extensive range of jaws
- Clamping of raw and finished parts without retrofitting
- Easy to maintain

Description

Workholding systems of the MC-P Z Balance series excel by a very compact design and their patented segment design.

Due to the position flexible function, deformation of the workpiece during clamping can be avoided.

The patented segment design ensures a high degree of precision and stability. The guiding clearance is reduced to nearly zero.

All essential components are made of hardened steel.

The workholding systems MC-P 100/125 Z Balance are already prepared for the use on zero point clamping systems. For this purpose, there are location threads for retractable nipples at the bottom side of the housing. For workholding systems MC-P Z Balance

a wide range of clamping jaws is available (see data sheet WS 5.450Z).

Customised versions

MC-P Z Balance workholding systems can also be delivered as customised versions. For example with other lengths or with individual mounting holes. Please contact us.

Consultation

Our experts will be pleased to advise you also on site, and work with you to find the optimum clamping solution.

Extensive information such as drawings and CAD models are available on request.

Technical data

Clamping principle: Operation:

Compensation stroke:

MC-P 60 ZB

Jaw width: Clamping force: Clamping stroke: Max. jaw opening:

15 kN at 50 Nm 30 mm 6-150 mm

25 kN at 80 Nm

position flexible

with a torque wrench

mechanically

± 2 mm

60 mm

100 mm

50 mm

6-204 mm

MC-P 100 ZB

Jaw width: Clamping force: Clamping stroke: Max. jaw opening:

MC-P 125 ZB

Clamping force:

Jaw width:

125 mm 35 kN at 200 Nm Clamping stroke: 101 mm 6-400 mm Max. jaw opening:

Function

The workholding systems MC-P Z Balance have a floating clamping point (with released locking). After operation of the clamping spindle, first the two clamping slides concentrically approach a location-fixed workpiece position. When both clamping jaws are in contact with the workpiece, the desired clamping force is applied by means of a torque wrench. Until this moment the clamping point is still floating. If the desired clamping force is reached, the clamping point which was floating up to this moment will be safely fixed by the locking spindle.

The adaptation of the clamping point to the location-fixed workpiece position will prevent a deformation of the workpiece

Subject to modifications



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Technical data Dimensions MC-P 60 ZB View from below Accessory: Clamping jaw (Fig. shows reversible step jaw 945836901) SW 12 M8x10 30 Str 100 ±0,01 فعرن 170 MC-P 100 ZB Accessory: Clamping jaw (Fig. shows reversible step jaw 945856901)-7 d1: Location hole for retractable nipple of a zero point clamping system SW 14 S1 200 ±0,01 M10x15 50 Stro ¢ 6 Ċ \odot Ф g-25 15 ⊚ ٢ 21 260 100 80 80 80 MC-P 125 ZB Accessory: Clamping jaw (Fig. shows reversible step jaw 945866901) d1: Location hole for retractable nipple of a zero point clamping system S1 SW 17 200 ±0,01 M 12x18 101 Stroke ÷ 6 θ Ð ¢ 160 150 80 HILM \odot 36 ¢ ф Φ Φ φ 465 4,5 125 83 164 83 All dimensions in [mm] MC-P 60 ZB MC-P 100 ZB MC-P 125 ZB Type **Clamping principle** position flexible position flexible position flexible Operation mechanical mechanical mechanical Clamping force / torque [kN/Nm] 15/5025/8035/200 Stroke, position flexible ± 2 ± 2 ± 2 [mm] S* 6-150 18-204 18-400 [mm] **S1**' [mm] 6-192 6-388 25+0.01x5/M10x14 25+0.01x5/M10x18 d1 [mm] _ 10F7 d2 [mm] _ _ d3 M10x11 [mm] **g** on both sides [mm] M8x10 M8x14 M12x18 Weight without clamping jaws [kg] 4.6 17.5 52.3 945830701 945850701 945860701 Part no. without clamping jaws

* depending on the used clamping jaw

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