

Electric Drives and Controls

Linear Motion and Assembly Technologies

Rexroth

# Proportional pressure relief valve with on-board electronics (OBE) and position feedback

RE 29151/07.05 1/10

#### Type DBETBEX

Nominal size 6 Unit series 1X Maximum working pressure P 315 bar, T 250 bar Nominal flow rate  $Q_{\text{nom}}$  1I/min



#### List of contents

#### **Contents**

**Features** 

Ordering data

Preferred types, symbol

Function, sectional diagram

Technical data

On-board trigger electronics

Characteristic curve

Unit dimensions

#### **Features**

Page

2

2

3

10

4 to 6

7 and 8

- Directly operated valves with position feedback and on-board electronics for limiting system pressure
- Adjustable through the position of the armature against the compression spring
- Position-controlled, minimal hysteresis < 0.2 %, rapid response times, see Technical data
- Pressure limitation to a safe level even with faulty electronics (solenoid current  $I > I_{\text{max}}$ )
- For subplate attachment, mounting hole configuration to ISO 4401-03-02-0-94. Subplates as per catalog sheet RE 45053 (order separately)
- Plug-in connector to DIN 43563-AM6, see catalog sheet RE 08008 (order separately)
- Data for the on-board trigger electronics
  - Complies with CE, EMC directives EN 61000-6-2: 2002-08 and EN 61000-6-3: 2002-08

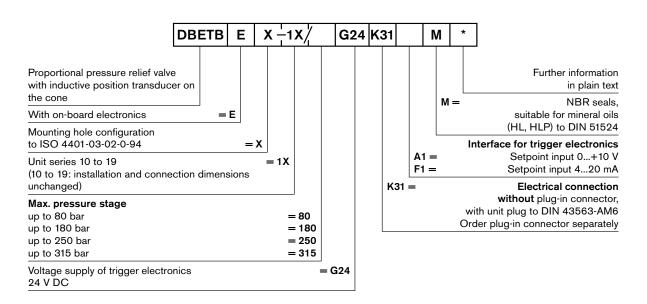
  - U<sub>B</sub> = 24 V<sub>nom</sub> DC
    Electrical connection 6P+PE
  - Signal actuation
  - Standard 0...+10 V (A1)
  - Version 4...20 mA (F1)
  - · Valve curve calibrated at the factory



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DBETBEX | RE 29151/07.05

# Ordering data



# Preferred types

TypeA1 (0+10 V)	Material Number	TypeF1 (420 mA)	Material Number
DBETBEX-1X/80G24K31A1M	0 811 402 072	DBETBEX-1X/80G24K31F1M	0 811 402 140
DBETBEX-1X/180G24K31A1M	0 811 402 071	DBETBEX-1X/180G24K31F1M	0 811 402 075
DBETBEX-1X/250G24K31A1M	0 811 402 073	DBETBEX-1X/315G24K31F1M	0 811 402 141
DBETBEX-1X/315G24K31A1M	0 811 402 070		

#### **Symbol**

For on-board electronics





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**3**/10

#### Function, sectional diagram

#### General

Type DBETBEX proportional pressure relief valves are remotecontrolled (pilot) valves in conical seat design. They are used to limit system pressure.

The valves are actuated by means of a proportional solenoid with on-board electronics.

With these valves, rapid response times with low hysteresis can be achieved.

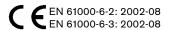
#### Basic principle

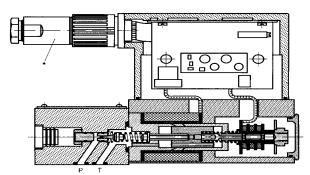
To adjust the system pressure, a setpoint is set in the trigger electronics. Based on this setpoint, the electronics control the position of the armature on the conical seat and on the compression spring.

The position control ensures extremely low hysteresis. The magnetic force determines the spring force until a new position is reached.

#### Pressure limitation for maximum safety

If a fault occurs in the electronics, so that the solenoid current  $(I_{\max})$  would exceed its specified level in an uncontrolled manner, the pressure cannot rise above the level determined by the maximum spring force.





Valve body

Proportional solenoid with position transducer

#### **Accessories**

Туре		Material Number	
(4 x) ₪ ISO 4762-M5x30-10.9	Cheese-head bolts		2 910 151 166
0000	Plug-in connectors 2P+PE,	KS	1 834 482 022
	see also RE 08008.	KS	1 834 482 026
		MS	1 834 482 023
		MS	1 834 482 024
		KS 90°	1 834 484 252

#### Testing and service equipment

Test box type VT-PE-TB3, see RE 30065 Measuring adapter 6P+PE type VT-PA-2, see RE 30068



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#### **Technical data**

General		
Construction		Poppet valve
Actuation		Proportional solenoid with position control and OBE
Connection type		Subplate, mounting hole configuration NG6 (ISO 4401-03-02-0-94)
Mounting position		Optional
mbient temperature range	°C	-20+50
Weight	kg	2.7
Vibration resistance, test condition		Max. 25 g, shaken in 3 dimensions (24 h)

Hydraulic (me	asured with H	LP 46,	$\vartheta_{\text{oil}} = 40 ^{\circ}\text{C} \pm 5 ^{\circ}\text{C}$	C)			
Pressure fluid			Hydraulic oil to DIN 51524535, other fluids after prior consultation				
Viscosity range	recommended	mm²/s	20100				
	max. permitted	mm <sup>2</sup> /s	10800				
Pressure fluid temperature range °C			-20+70				
Maximum permitted degree of contamination of pressure fluid Purity class to ISO 4406 (c)		Class 18/16/13 <sup>1)</sup>					
Direction of flow			See symbol				
Max. set pressure (at $Q = 1$ l/min) bar			80	180	250	315	
Minimum pressure (at $Q = 1 \text{ l/min}$ ) bar			3	4	5	8	
			Note: At $Q_{\text{max}} = 1.5$ l/min the pressure levels stated here increase				
$\begin{array}{ll} \text{Max. mechanical pressure} & \text{bar} \\ \text{limitation level, e.g. when solenoid} \\ \text{current } I {>} I_{\text{max}} \end{array}$		<85	<186	<258	<325		
Max. working pressure (at $Q = 1$ l/min) bar			Port P: 315				
Max. pressure bar		Port T: 250					

Static/Dynamic				
Hysteresis %	≦ 0.2			
Range of inversion %	≦ 0.1			
Manufacturing tolerance %	≦±5			
Response time 100% signal change ms	30			
10% signal change ms	10			
Thermal drift	<1 % at $\Delta T = 40$ °C			
Conformity	<b>C E</b> N 61000-6-2: 2002-08 EN 61000-6-3: 2002-08			

<sup>1)</sup> The purity classes stated for the components must be complied with in hydraulic systems. Effective filtration prevents problems and also extends the service life of components. For a selection of filters, see catalog sheets RE 50070, RE 50076 and RE 50081.



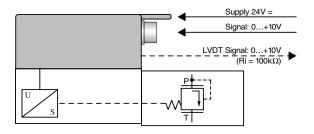
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**5**/10

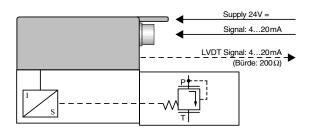
#### **Technical data**

Electrical, trigger electronics in	tegr	ated in valve
Cyclic duration factor	%	100
Degree of protection		IP 65 to DIN 40050 and IEC 14434/5
Connection		Plug-in connector 6P+PE, DIN 43563
Supply voltage Terminal A: Terminal B: 0 V		24 V DC Min. 21 V DC/max. 40 V DC Ripple max. 2 V DC
Power consumption		Solenoid ☐ 45 mm = 40 VA max.
External fuse		2.5 A <sub>F</sub>
Input, "standard" version Terminal D: $U_{\rm E}$ Terminal E:	A1	Differential amplifier, $R_{\rm i}$ = 100 k $\Omega$ 0+10 V 0 V
Input, "mA signal" version Terminal D: $I_{\rm D-E}$ Terminal E: $I_{\rm D-E}$	F1	Burden, $R_{\rm sh} = 200~\Omega$ 420 mA Current loop $I_{\rm D-E}$ feedback
Max. voltage to differential inputs over	0 V	$\begin{bmatrix} D \rightarrow B \\ E \rightarrow B \end{bmatrix}$ max. 18 V DC
Test signal, "standard" version Terminal F: $U_{\mathrm{Test}}$ Terminal C:	A1	LVDT 0+10 V Reference 0 V
Test signal, "mA signal" version Terminal F: $I_{\rm F-C}$ Terminal C: $I_{\rm F-C}$	F1	LVDT signal 420 mA at external load 200500 $\Omega$ max. 420 mA output Current loop $I_{\rm F-C}$ feedback
Safety earth conductor and shield		See pin assignment (installation in conformity with CE)
Recommended cable		See pin assignment up to 20 m 7 x 0.75 mm <sup>2</sup> up to 40 m 7 x 1 mm <sup>2</sup>
Calibration		Calibrated at the factory, see valve curve

#### Version A1: Standard



#### Version F1: mA signal

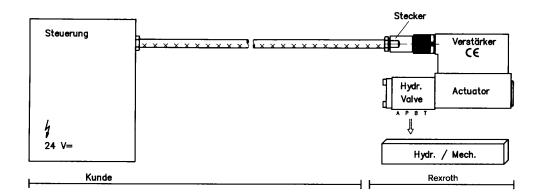




**6**/10 Bosch Rexroth AG | Hydraulics DBETBEX | RE 29151/07.05

#### Connection

For electrical data, see page 5 and Operating Instructions 1819929083



#### Technical notes for the cable

Version: - Multi-wire cable

- Extra-finely stranded wire to VDE 0295, Class 6

- Safety earth conductor, green/yellow

- Cu-braided shield

– e.g. Ölflex-FD 855 <u>C</u>P Type:

(from Lappkabel company)

No. of wires: - Determined by type of valve, plug type

and signal assignment - 0.75 mm<sup>2</sup> up to 20 m long

Cable Ø: - 1.0 mm<sup>2</sup> up to 40 m long

Outside Ø: - 9.4...11.8 mm - Pg11 - 12.7...13.5 mm - Pg16

## **Important**

Voltage supply 24 V DC nom,

if voltage drops below 18 V DC, rapid shutdown resembling

"Enable OFF" takes place internally.

In addition, with the "mA signal" version:

 $I_{\rm D-E} \ge 3 \; {\rm mA} - {\rm valve} \; {\rm is} \; {\rm active}$ 

 $I_{\rm D-E} \le 2$  mA – valve is deactivated.

Electrical signals emitted via the trigger electronics (e.g. actual values) must not be used to shut down safety-relevant machine

functions!

(See also European Standard, "Technical Safety Requirements for Fluid-Powered Systems and Components - Hydraulics",

EN 982.)

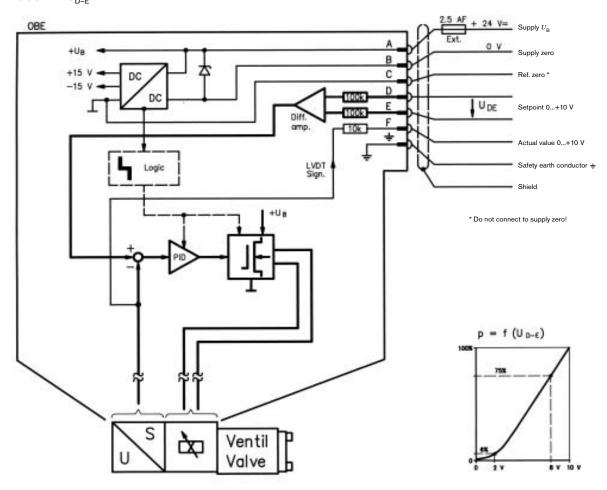


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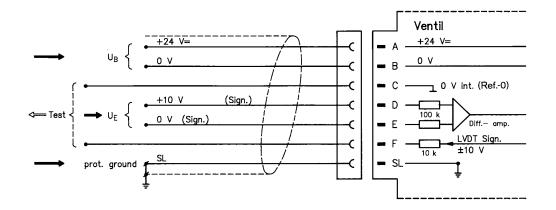
**7**/10

### On-board trigger electronics

# Circuit diagram/pin assignment Version A1: $U_{\rm D-E}$ 0...+10 V



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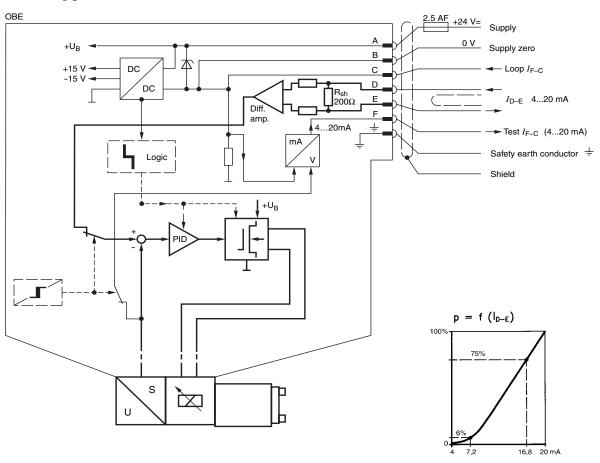


**8**/10 Bosch Rexroth AG | Hydraulics

### On-board trigger electronics

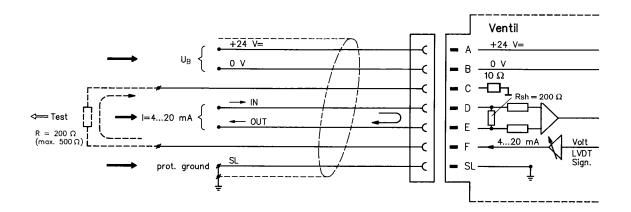
#### Circuit diagram/pin assignment

Version F1:  $I_{\rm D-E}$  4...20 mA



#### Pin assignment

Version F1:  $I_{\rm D-E}$  4...20 mA  $(R_{\rm sh}=200~{\rm k}\Omega)$ 



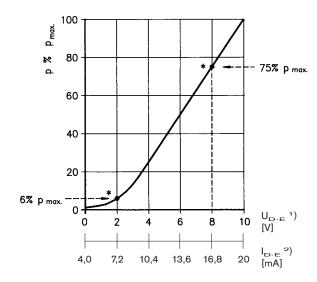


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**9**/10

# Characteristic curve (measured with HLP 46, $\vartheta_{oil} = 40 \,^{\circ}\text{C} \pm 5 \,^{\circ}\text{C}$ )

Pressure in port P as a function of the setpoint Nominal flow rate = 1 l/min



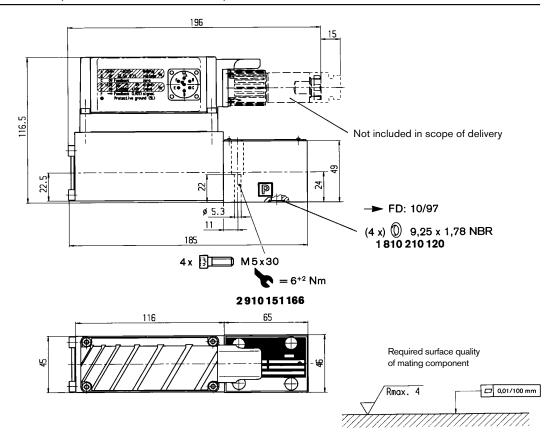
- \* Factory setting at Q = 1 I/min  $\pm 2\%$  manufacturing tolerance
- $^{\rm 1)}$  Version:  $U_{\rm D-E}$  = 0...+10 V
- $^{2)}$  Version:  $I_{D-E} = 4...20 \text{ mA}$



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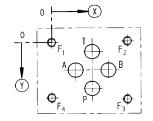
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#### Unit dimensions (nominal dimensions in mm)



**Mounting hole configuration: NG6** (ISO 4401-03-02-0-94) For subplates, see catalog sheet RE 45053

- 1) Deviates from standard
- <sup>2)</sup> Thread depth: Ferrous metal 1.5 x Ø Non-ferrous 2 x Ø



	Р	Α	Т	В	F <sub>1</sub>	F <sub>2</sub>	F <sub>3</sub>	F <sub>4</sub>
<b>(X)</b>	21.5	12.5	21.5	30.2	0	40.5	40.5	0
<u> </u>	25.9	15.5	5.1	15.5	0	-0.75	31.75	31
Ø	8 <sup>1)</sup>	8 <sup>1)</sup>	8 <sup>1)</sup>	8 <sup>1)</sup>	M5 <sup>2)</sup>	M5 <sup>2)</sup>	M5 <sup>2)</sup>	M5 <sup>2)</sup>