

Electric Drives
and Controls

Hydraulics

Linear Motion and
Assembly Technologies

Pneumatics

Service

Rexroth
Bosch Group

Electric amplifiers

RE 30043/02.12

1/6

Replaces: 11.02

Type VT-VRRA1-527-2X/V0/K40-AGC-2STV

Component series 2X

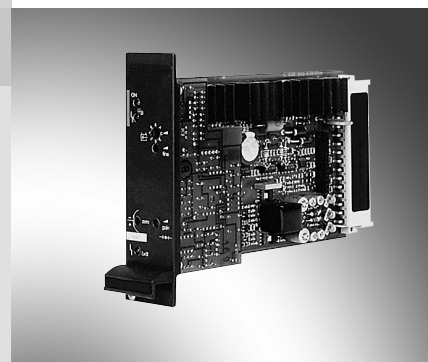


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Features

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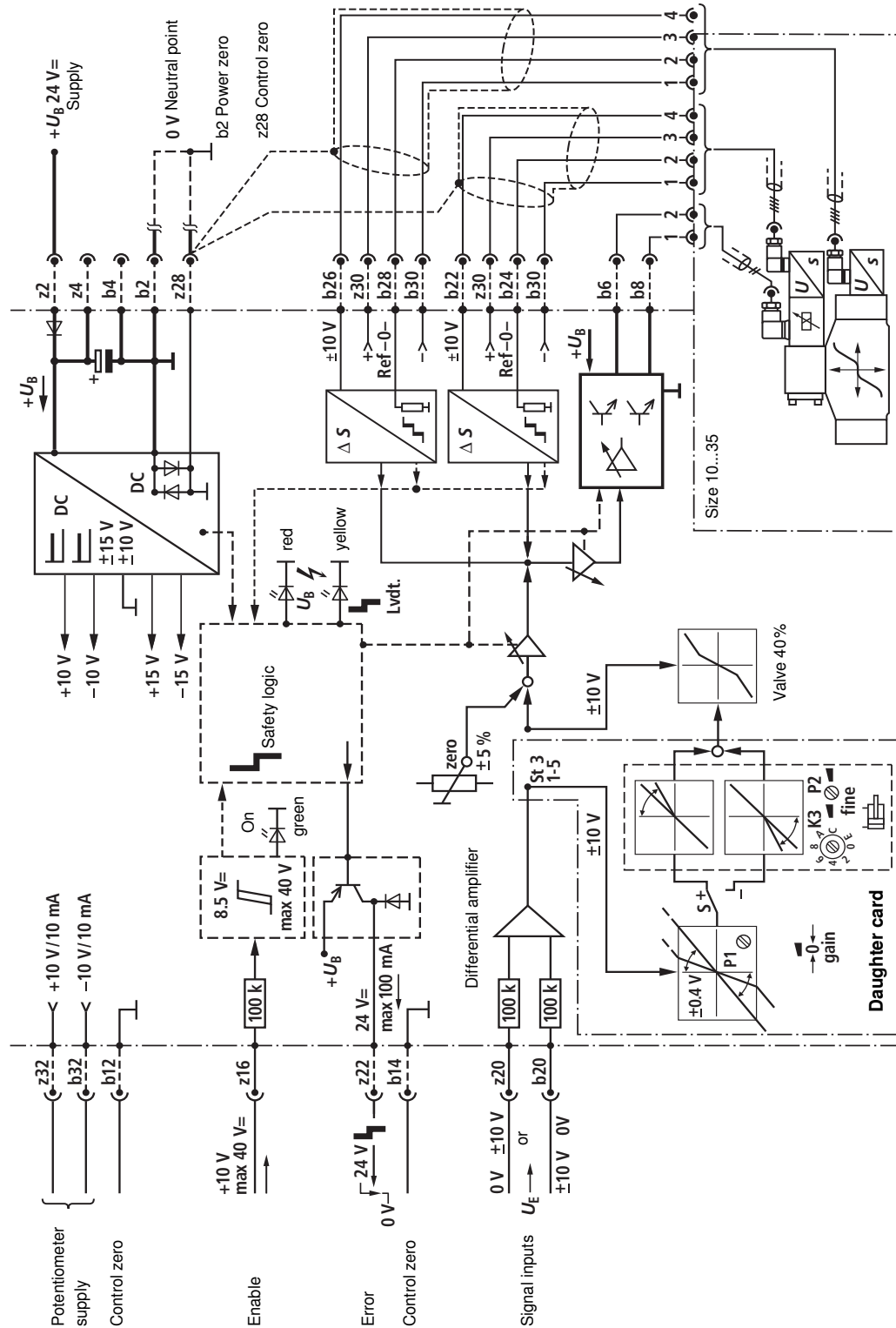
Notice:

The photo shows an example configuration.
The delivered product differs from the figure.

Ordering code, accessories

VT- V R R A 1 - 527 - 2X/V0/K40-AGC-2STV									
Hydraulic component									
For valves with electrical feedback			= R						
Valve type									
Directional control valve			= R						
Control									
Analog			= A						

Block diagram with pin assignment



Technical data (For applications outside these parameters, please consult us!)

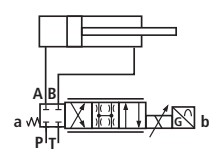
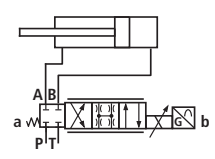
Supply voltage U_B at z2 – b2		Nominal 24 V =, Battery voltage 21...40 V, Rectified alternating voltage $U_{eff} = 21...28$ V (one-phase, full-wave rectifier)
Smoothing capacitor, separately at z2 – b2		Recommendation: Capacitor module VT 11110 (see data sheet 30750) (only necessary if the ripple of $U_B > 10\%$)
Valve solenoid, max.	A/VA	2.7/40 (pilot control valve size 6)
Current consumption, max.	A	1.7 The current consumption may increase with min. U_B and extreme cable length to the control solenoid
Power consumption (typical)	W	37
Input signal (command value)		b20: 0...±10 V z20: 0...±10 V } Differential amplifier ($R_i = 100$ kΩ)
Signal source		Potentiometer 10 kΩ Supply with ±10 V from b32, z32 (10 mA) or external signal source
Enable output stage		At z16, $U = 8.5...40$ V, $R_i = 100$ kΩ, LED (green) on front plate lights up
Position transducer Supply		b30: –15 V z30: +15 V
Pilot control valve	Actual value signal	b22: 0...±10 V
	Actual value reference	b24
Main stage	Actual value signal	b26: 0...±10 V
	Actual value reference	b28
Solenoid output b6 – b8		Clocked current controller
	I_{max}	2.7 A
Cable lengths between amplifier and valve		Solenoid cable: to 20 m 1.5 mm ² 20 to 60 m 2.5 mm ² Position transducer: 4 x 0.5 mm ² (shielded)
Special features		Cable break protection for actual value cable, Position control with PID behavior, Pulsed output stage, Fast energization and fast deletion for short actuating times, Short-circuit-proof outputs, Linearization of the inflected flow characteristic curve
Adjustment		Zero point via trimming potentiometer ±5 % Area adjustment of single rod cylinders, Gain in the small signal range
LED displays		green: Enable yellow: Cable break actual value red: Undervoltage (U_B too low)
Error message		
– Cable break actual value		
– U_B too low		
– ±15 V stabilization		z22: Open collector output to + U_B max. 100 mA; no error: + U_B
Circuit board format	mm	(100 x 160 x approx. 35) / (W x L x H) Europe format with front plate 7 TE
Plug-in connection		Connector DIN 41612 – F32
Ambient temperature	°C	0...+70
Storage temperature range	°C	–20...+70
Weight	m	0.39 kg

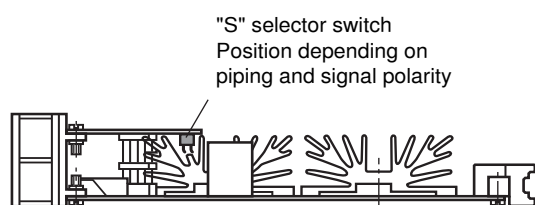
Notice:

Power zero b2 and control zero b12 or b14 or z28 must be separately led to the central ground (neutral point).

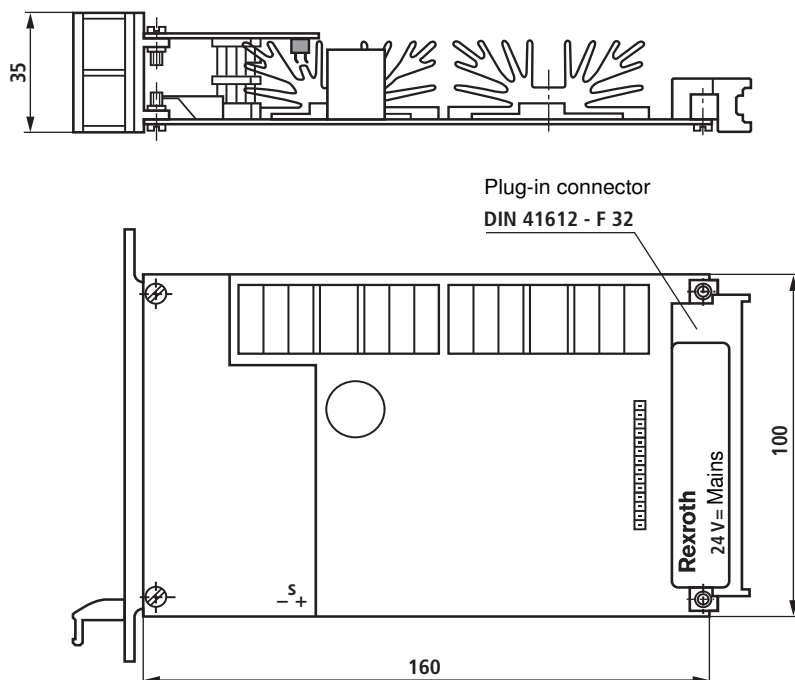
Commissioning

1. Setting the electric and hydraulic zero point using the "zero" potentiometer.
 With closed control loop, the following error displayed by the CNC is then controlled to 0.
2. Adjustment single rod cylinder
 - "S" selector switch setting on daughter card
 - Comparison with direction-dependant command value attenuator with step switch K3 (coarse), with potentiometer P2 (fine).
3. Optimization of the gain in the small signal range with potentiometer P1.

Valve \leftrightarrow Cylinder	Selector switch
	"S" –
	"S" +



Unit dimensions (dimensions in mm)



Project planning / maintenance instructions / additional information

- The amplifier card may only be unplugged and plugged when de-energized.
- The distance to aerial lines, radios and radar systems must be sufficient (> 1 m).
- Do not lay solenoid and signal lines near power cables.
- For signal lines and solenoid conductors, we recommend using shielded cables.
The cable shield must be connected to the control cabinet extensively and as short as possible.
- The valve solenoid must not be connected to free-wheeling diodes or other protective circuits.
- The cable lengths and cross-sections specified on page 4 must be complied with.