

RE 92703/2023-07-11 Replaces: 2020-12-07

and RE-A 92703/2021-01-20



Axial piston variable pump A10VO series 52 and 53



- ▶ For machines with medium pressure requirements
- ▶ Sizes 10 to 100
- Nominal pressure 250 bar (3600 psi)
- ► Maximum pressure 315 bar (4550 psi)
- ▶ Open circuit

Contents

Features

- Variable pump with axial piston rotary group in swashplate design for hydrostatic drives in open circuit.
- ▶ Flow is proportional to drive speed and displacement.
- ► The flow can be infinitely varied by adjusting the swashplate angle.
- ► Stable bearing for long service life
- ► High permissible drive speed
- ► Favorable power-to-weight ratio compact dimensions
- ► Low noise
- Excellent suction characteristics
- Electro-hydraulic pressure control
- ▶ Power control
- ► Electro-proportional swivel angle control
- ▶ Short control times

Type code series 52	2
Hydraulic fluids	7
Working pressure range	9
Technical data	10
DR – Pressure controller	14
DRG - Pressure controller, remotely controlled	15
DRF (DFR) / DRS (DFR1) / DRSC	16
LA Pressure, flow and power controller	18
LA – Variations	19
ED – Electro-hydraulic pressure control	20
ER – Electro-hydraulic pressure control	22
EP - Electro-proportional control	23
EK – Electro-proportional control with	
controller cut-off	24
EP(K).DF / EP(K).DS / EP(K) - with	
pressure flow controller	25
$\ensuremath{EP.ED}$ / $\ensuremath{EK.ED}$ – with electro-hydraulic pressure control	26
EC4 – Electro-hydraulic control valve	27
Dimensions, size 10 to 100	29
Dimensions, through drive	72
Overview of mounting options	76
Combination pumps A10VO + A10VO	77
Connector for solenoids	78
Swivel angle sensor	79
Installation instructions	80
Project planning notes	84
Safety instructions	85



2 **A10VO series 52 and 53** | Axial piston variable pump Type code series 52

Type code series 52

C)1	02	03	04		05	06		07	08	09		10		11	_	12
A 1	0V	0			/	52			V								
xial	piston	unit										10	28	45	60	85	
01	Swash	nplate desi	gn, variable	, nominal pres	sure 25	0 bar (3600	psi), max	imum pressu	ure 315 bar	(4550 psi)		•	•	•	•	•	A10
pera	ting m	ode															
02	Pump,	, open circ	uit														0
ize (NG)																
03	Geom	etric displa	acement, se	e table of valu	es on p	age 10						10	28	45	60	85	j
Contr	ol devi	ce															
04		ure contr	oller	Hydraulic								•	•	•	•	•	DR
	Wi	ith flow c	ontroller	Hydraulic	X-	T open						•	•	•	•	•	DFI
					X-	T plugged	٧	Vith flushin	g function			•	•	•	•	•	DFR
							V	Vithout flus	hing funct	ion		-	•	•	•	•	DRS
	Wi	ith pressu	re cut-off	Hydraulic	R	emote cont	rolled					•	•	•	•	•	DR
				Electric	N	egative con	trol	U = 1	2 V			-	•	•	•	•	ED7
								U = 2	4 V			-	•	•	•	•	ED7
				Electric	Р	ositive cont	rol	U = 1	2 V			-	•	•	•	•	ER7
								U = 2	4 V			-	•	•	•	•	ER7
	Electr	ro-hydrau	lic control	valve	P	ositive cont	rol	U = 1	2 V to 24	V		-	•	-	-	-	EC
Series	;											10	28	45	60	85	
05	Series	5, index 2	2									•	•	•	•	•	52
Direct	ion of	rotation										10	28	45	60	85	
06		d on drive	shaft					Clockwise				•	•	•	•	•	R
								ounter-clock	wise			•	•	•	•	•	L
Soalin	g mate	rial										10	28	45	60	85	
07			on rubber)									T •	•	•	•	•	v
															!		
08	shaft	ed shaft		Standard s	haft							10	28	45	60	85	s
00	ISO 30			Similar to s		S" however	for high	er torque				<u>-</u>	•	•	•	•	R
	150 50	0101		Reduced di					n drive			•	•	•	•	•	U.
				Like shaft "						table for m	nounting		<u> </u>	Ť	<u> </u>	_	H
				with throug		J	' '	,	3			-	•	•	•	•	w
	Parall	lel keyed	shaft DIN (6885 not for	throug	h-drive						● ¹⁾	-	-	-	-	Р
	Parall	lel keyed	shaft ISO 3	3019-1 not fo	r thro	ugh-drive						● ²⁾	•	•	•	•	К
	Taper	ed keyed	shaft and	UNF threaded	d bolt	not for thro	ough-driv	е		-		-	•	•	•	•	С
/loun	ting fla	inge															
09			3019-2 (IS	0)				2-ho	ole			•	-	-	-	_	А
	Based	d on ISO	3019-1 (SA	Æ)				2-ho	le			•	•	•	•	•	С
	1		•					4-ho	ole			-	_	-	•	_	D

¹⁾ With mounting flange A and C; order item 09 and port plate 14

 $_{\rm 2)}$ Only with mounting flange C; order item 09 and port plate 64

3



Axial piston variable pump | **A10VO series 52 and 53**Type code series 52

	01	02	03	04		05	06		07	08	09	-	10		11		12
A	10V	0			/	52		_	V								
/ork	ing port	t										10	28	45	60	85	
10	1	lange por		Fastening	g thread n	netric rear		lot for thro	ugh drive			-	•	•	•	•	11
	accore metri	ding to IS c	O 6162	Fastening		netric late	rally F	or through	drive			-	•	•	•	•	12
				Fastening offset 90°	•	netric later	-	lot for thro ounter-cloc	,		or	-	-	•	-	-	13
	Threaded port rear Not for through drive metric SAE flange ports Fastening thread UNC rear Not for through drive							•2)	-	-	-	-	14				
according to ISO 6162 Fastening thread LINC latera						N	lot for thro	ugh drive			-	•	•	•	•	61	
	according to ISO 6162 UNC Threaded port			Fastening opposite	•	INC lateral	lly F	or through	drive			-	•	•	•	•	62
	opposite						•3)	•	•	-	-	64					
hrou	ıgh driv	e (for mou	nting optio	ns, see page	76)												
11	Flange	e ISO 301	9-1	Hub for splined shaft ¹⁾													
	Diame	eter		Diameter								10	28	45	60	85	
	Withou	ut through	drive									•	•	•	•	•	NO
	82-2 ((A)		5/8 in	9T 16/3	2DP						-	•	•	•	•	K0
				3/4 in	11T 16/	32DP						-	•	•	•	•	K5:
	101-2	(B)		7/8 in	13T 16/	32DP						-	•	•	•	•	К6
				1 in	15T 16/	32DP						-	-	•	•	•	ко
	127-4 (C) 1 1/4 in 14T 12/24DP							-	-	-	•	•	K1				
1 1/2 in 17T 12/24DP									-	-	-	-	•	K1			
	127-2	(C)		1 1/4 in	14T12/2	24DP						-	-	-	-	•	ко
	1			1 1/2 in	17T 12/							+					К2

• = Available o = On request - = Not available

12 Without connector (without solenoid, only for hydraulic controls, without signs)

DEUTSCH – molded connector, 2-pin – without suppressor diode (for electric controls)

Notice

- ► Observe the general project planning notes on page 84 and the project planning notes regarding each control device.
- In addition to the type code, please specify the relevant technical data.

¹⁾ In accordance with ANSI B92.1a

²⁾ Only with mounting flange A; order item 09

 $_{\mbox{\scriptsize 3)}}$ Only with mounting flange C; order item 09



A10VO series 52 and 53 | Axial piston variable pump Type code series 53

Type code series 53

)1	02	03	04		05	06		07	08	09	9		10		11		12
A 1	IOV	0			/	53		-	V						Π		Т	
Axial	pisto	n unit			•						18	28	45	63	72	85	100	
01	Swas (4550		sign, variak	ole, nomin	al pressure	e 250 bar	(3600 psi)), maxir	num pressur	e 315 bar	•	•	•	•	•	•	•	A10V
Oper	ating r	mode																
02	Pump	o, open cir	cuit															0
Size	(NG)																	
03	Geon	netric disp	lacement,	see table	of values o	on page 1	0				18	28	45	63	72	85	100]
Cont	rol de	vice			_						,							•
04	Press	ure contro	oller	Hydrauli							•	•	•	•	•	•	•	DR
	W	ith flow co	ontroller	Hydrauli		X-T ope	n				•	•	•	•	•	•	•	DRF
						X-T plug	ged	With	flushing fun	ction	•	•	•	•	•	•	•	DRS
								With	out flushing	function	•	•	•	•	•	•	•	DRSC
	W	ith pressu	re cut-off	Hydrauli	С	Remote	controlled	ł			•	•	•	•	•	•	•	DRG
				Electric		Negativ	e control		U = 12 V		•	•	•	•	•	•	•	ED71
									U = 24 V		•	•	•	•	•	•	•	ED72
				Electric		Positive	control		U = 12 V		•	•	•	•	•	•	•	ER71
									U = 24 V		•	•	•	•	•	•	•	ER72
	Elect	ro-hydraul	ic control	valve		Positive	control		<i>U</i> = 12 V to	24 V	-	-	-	o ¹⁾	-	-	-	EC4
		er controlle ure cut-of		Hydrauli	С	Beginni control	ng of	from	10 to 35 ba (145 to 510		•	•	•	•	•	•	•	LA5D
									36 to 70 ba (520 to 101		•	•	•	•	•	•	•	LA6D
									71 to 105 b (1030 to 15		•	•	•	•	•	•	•	LA7D
									106 to 140 (1535 to 20		•	•	•	•	•	•	•	LA8D
									141 to 230 (2045 to 33		•	•	•	•	•	•	•	LA9D
	Re	emote con	trolled	Hydrauli	С	Beginni control	ng of		See LA.D	-	•	•	•	•	•	•	•	LA.DG
		ow contro ugged,	l X-T	Hydrauli flushing		Beginni control	ng of		See LA.D		•	•	•	•	•	•	•	LA.DS
		'			c without	Beginni control	ng of		See LA.D		•	•	•	•	•	•	•	LA.DC

Notice

▶ Observe the project planning notes regarding each control device

¹⁾ Only available with mounting flange C (order item 09)



Axial piston variable pump | **A10VO series 52 and 53** 5 Type code series 53

01	02	03	04		05	06		07	08	09	10	11	12
A10V	0			/	53		-	V					

04	Electro-proportional cor	itrol	Positive control		18	28	45	63	72	85	100	
	With pressure contro	l		U = 12 V	•	•	•	•	•	•	•	EP1D
				U = 24 V	•	•	•	•	•	•	•	EP2D
	With pressure and flo	ow control	X-T open	U = 12 V	•	•	•	•	•	•	•	EP1DI
	(load-sensing)			U = 24 V	•	•	•	•	•	•	•	EP2DI
	With pressure and flo	ow control	X-T plugged	U = 12 V	•	•	•	•	•	•	•	EP1DS
	(load-sensing)			U = 24 V	•	•	•	•	•	•	•	EP2D
	With electro-hydrauli	c pressure control		U = 12 V	•	•	•	•	•	•	•	EP1EI
				U = 24 V	•	•	•	•	•	•	•	EP2E
	Electro-proportional cor	itrol	Positive control									
	With pressure contro	l		U = 12 V	•	•	•	•	•	•	•	EK1D
				U = 24 V	•	•	•	•	•	•	•	EK2D
	Pressure and flow co	ntrol with controller	X-T open	U = 12 V	•	•	•	•	•	•	•	EK1DI
	cut-off (load sensing))		U = 24 V	•	•	•	•	•	•	•	EK2DI
	Pressure and flow co	ntrol with controller	X-T plugged	U = 12 V	•	•	•	•	•	•	•	EK1D
	cut-off (load sensing))		U = 24 V	•	•	•	•	•	•	•	EK2D
	Electro-hydraulic pre	ssure control with		U = 12 V	•	•	•	•	•	•	•	EK1EI
	controller cut-off			U = 24 V	•	•	•	•	•	•	•	EK2EI
Serie	s				18	28	45	63	72	85	100	
05	Series 5, index 3				•	•	•	•	•	•	•	53
)iror	tion of rotation				18	28	45	63	72	05	100	
06	Viewed on drive shaft			Clockwise	•	- 26	•	•	•	•	•	R
00	viewed on drive shart			Counter-clockwise	•	•		•	•	•	•	L
	ng material				18	28	45	63	72		100	
07	FKM (fluorocarbon rubb	er)			•	•	•	•	•	•	•	V
)rive	shaft				18	28	45	63	72	85	100	
80	Splined shaft	Standard shaft			•	•	•	•	•	•	•	s
	ISO3019-1	Similar to shaft "S	" however for highe	r torque	•	•	•	•	•	•	•	R
		Reduced diameter,	limited suitability	for through drive	•	•	•	•	•	•	•	U
		Like shaft "U" but	for higher torque, o	nly conditionally suitable for		•			•	•		w
		mounting with thre	ough-drive. For mou	inting options, see page 76		Ľ	Ľ	Ľ	_	_	_	
	Parallel keyed shaft ISO	3019-1 not for throug	gh-drive		•	•	•	•	•	•	•	K
/lour	nting flange				18	28	45	63	72	85	100	
09	Based on ISO 3019-1 (S	AE)		2-hole	•	•	•	•	•	•	•	С
				4-hole	T -	_	-	•	•	•	•	D



6 **A10VO series 52 and 53** | Axial piston variable pump Type code series 53

(01	02	03	04		05	06		07	08	09	9	-	10		11		12
A ¹	10V	0			/	53		-	V									
Vork	ing po	ort									18	28	45	63	72	85	100	
10		lange por		Fastenin	g thread r	netric rea	r	Not for	through d	rive	•	•	•	•	•	•	•	11
	metri	-	0 6162	Fastenin	_	netric late	rally	For thro	ough drive		•	•	•	•	•	•	•	12
	SAE flange ports	Fastening thread metric laterally Not for through driv offset 90° available for counte clockwise rotation of						nter-	-	-	•	-	_	-	-	13		
				Fastenin	g thread (JNC rear		Not for	through d	rive	•	•	•	•	•	•	•	61
	UNC	ding to IS	0 6162	Fastenin opposite	_	JNC latera	lly	For thro	ough drive		•	•	•	•	•	•	•	62
hrou	ugh dri	ive (for m	ounting o	ptions, see	page 76)													
11	Flang	e ISO 30	19-1	Hub for	splined sh	naft ¹⁾												
	Diam	eter		Diamete	r						18	28	45	63	72	85	100	
	Witho	out throug	gh drive								•	•	•	•	•	•	•	N0
	82-2	(A)		5/8 in	9T 16/3	32DP					•	•	•	•	•	•	•	K0
				3/4 in	11T 16/	/32DP												K5

11	Flange ISO 3019-1	Hub for splined shaft ¹⁾								
	Diameter	Diameter	18	28	45	63	72	85	100	
	Without through drive		•	•	•	•	•	•	•	N00
	82-2 (A)	5/8 in 9T 16/32DP	•	•	•	•	•	•	•	K01
		3/4 in 11T 16/32DP	•	•	•	•	•	•	•	K52
	101-2 (B)	7/8 in 13T 16/32DP	-	•	•	•	•	•	•	K68
		l in 15T 16/32DP	-	-	•	•	•	•	•	K04
	127-4 (C)	I 1/4 in 14T 12/24DP	-	-	-	•	•	•	•	K15
		I 1/2 in 17T 12/24DP	-	-	-	-	-	•	•	K16
	127-2 (C)	I 1/4 in 14T12/24DP	-	-	-	-	-	•	•	K07
		I 1/2 in 17T 12/24DP	-	_	_	-	_	•	•	K24
	•									

Con	nector for solenoids	18	28	45	63	72	85	100	
12	Without connector (without solenoid, only for hydraulic controls, without signs)	•	•	•	•	•	•	•	
	DEUTSCH – molded connector, 2-pin – without suppressor diode (for electric controls)	•	•	•	•	•	•	•	Р

• = Available • = On request - = Not available

Notice

- ▶ Note the project planning notes on page 84.
- ► In addition to the type code, please specify the relevant technical data when placing your order.

1) In accordance with ANSI B92.1a



Axial piston variable pump | **A10VO series 52 and 53** Hydraulic fluids

7

Hydraulic fluids

The A10VO variable pump is designed for operation with HLP mineral oil according to DIN 51524.

Application instructions and requirements for hydraulic fluid selection, behavior during operation as well as disposal and environmental protection should be taken from the following data sheets before the start of project planning:

- ▶ 90220: Hydraulic fluids based on mineral oils and related hydrocarbons
- ▶ 90221: Environmentally acceptable hydraulic fluids

Selection of hydraulic fluid

Bosch Rexroth evaluates hydraulic fluids on the basis of the Fluid Rating according to the technical data sheet 90235. Hydraulic fluids with positive evaluation in the Fluid Rating are provided in the following technical data sheet:

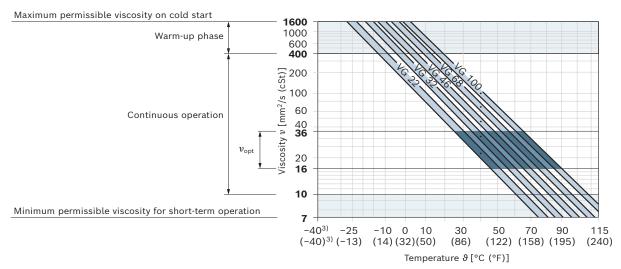
▶ 90245: Bosch Rexroth fluid rating list for Rexroth hydraulic components (pumps and motors)

The hydraulic fluid should be selected so that the operating viscosity in the operating temperature range is within the optimum range (v_{opt} ; see selection diagram).

Viscosity and temperature of hydraulic fluids

	Viscosity	Shaft seal	Temperature ²⁾	Comment
Cold start	ν _{max} ≤ 1600 mm ² /s (cSt)	FKM	ϑ _{St} ≥ −25 °C (−13 °F)	$t \le 3$ min, without load ($p \le 50$ bar (725 psi)), $n \le 1000$ rpm Permissible temperature difference between the axial piston unit and hydraulic fluid in the system max. 25 K (45 °F)
Warm-up phase	$v = 1600 \dots 400 \text{ mm}^2/\text{s (cSt)}$			$t \le 15 \text{min}, p \le 0.7 \times p_{\text{nom}} \text{ and } n \le 0.5 \times n_{\text{nom}}$
Continuous operation	$v = 400 \dots 10 \text{ mm}^2/\text{s (cSt)}^{1)}$	FKM	9 ≤ +110 °C(+230 °F)	Measured at port $\mathbf{L}_{\mathbf{x}}$
	$v_{\rm opt}$ = 36 16 mm ² /s (cSt)			Optimal operating viscosity and efficiency range
Short-term operation	v_{min} = 10 7 mm ² /s (cSt)	FKM		$t \le 3 \text{ min, } p \le 0.3 \times p_{\text{nom}}, \text{ measured at port } \mathbf{L_x}$

▼ Selection diagram



¹⁾ This corresponds, for example on the VG 46, to a temperature range of +4 °C to +85 °C (+39 °F to +113 °F) (see selection diagram)

²⁾ If the temperature at extreme operating parameters cannot be adhered to, please contact us.

³⁾ For applications in the low-temperature range, please contact us.



8 **A10VO series 52 and 53** | Axial piston variable pump Hydraulic fluids

Filtration of the hydraulic fluid

Finer filtration improves the cleanliness level of the hydraulic fluid, which increases the service life of the axial piston unit.

A cleanliness level of at least 20/18/15 is to be maintained according to ISO 4406

At a hydraulic fluid viscosity of less than 10 mm²/s (cSt) (e.g. due to high temperatures during short-term operation) at the drain port, a cleanliness level of at least 19/17/14 under ISO 4406 is required.

Examples of temperatures of hydraulic fluids at a viscosity of 10 $\,\mathrm{mm^2/s}$ (cSt):

- ▶ 73 °C (163 °F) at HLP 32
- ▶ 85 °C (185 °F) at HLP 46



Axial piston variable pump | **A10VO series 52 and 53**Working pressure range

9

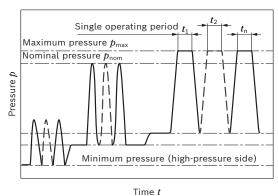
Working pressure range

Pressure at working port B		Definition
Nominal pressure p_{nom}	250 bar (3600 psi)	The nominal pressure corresponds to the maximum design pressure.
Maximum pressure p_{max}	315 bar (4550 psi)	The maximum pressure corresponds to the maximum working pressure within
Single operating period	2.5 ms	a single operating period. The sum of single operating periods must not exceed
Total operating period	300 h	the total operating period.
Minimum pressure $p_{B \text{ abs}}$ (high-pressure side)	10 bar (145 psi)	Minimum pressure on the high-pressure side (B) which is required in order to prevent damage to the axial piston unit.
Rate of pressure change $R_{ m A\ max}$	16000 bar/s (232000psi/s)	Maximum permissible speed of pressure build-up and reduction during a pressure change across the entire pressure range.
Pressure at suction port S (inle	et)	
Minimum Standard pressure $p_{\text{S min}}$	0.8 bar (12 psi) absolute	Minimum pressure at suction port ${\bf S}$ (inlet) which is required to prevent damage to the axial piston unit. The minimum pressure depends on the rotational speed and displacement of the axial piston unit.
Maximum pressure $p_{\text{S max}}$	5 bar (75 psi) absolute	
Case pressure at port L, L ₁ , L ₂		
Maximum pressure $p_{ m L\ max}$	2 bar (30 psi)	Maximum 0.5 bar (7.5 psi) higher than inlet pressure at port S , but not higher than $p_{\rm L\ max}$. The case pressure must always exceed the ambient pressure. A case drain line to the reservoir is required.
Pilot pressure port X with exte	rnal high pressure	
Maximum pressure p_{max}	315 bar (4550 psi)	When designing all control lines with external high pressure, the values for the rate of pressure change, maximum single operating period and total operating period applicable to port B must not be exceeded.

Notice

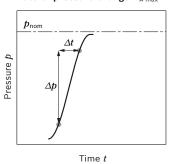
Working pressure range applies when using hydraulic fluids based on mineral oils. Please contact us for values for other hydraulic fluids.

▼ Pressure definition



Total operating period = $t_1 + t_2 + ... + t_n$

▼ Rate of pressure change $R_{\text{A max}}$



RE 92703/2023-07-11, Bosch Rexroth AG



10 A10VO series 52 and 53 | Axial piston variable pump Technical data

Technical data

Size		NG		10	18	28	45	60	63	72	85	100
Geometric dis	splacement,	$V_{ m g\ max}$	cm ³	10.5	18	28	45	60	63	72	85	100
per revolution	ı		inch ³	0.64	1.10	1.75	2.75	3.66	3.84	4.39	5.18	6.10
Maximum	at $V_{ m g\ max}$	n_{nom}	rpm	3600	3300	3000	2600 ⁵⁾	2700	2600	2600	2500	2300
rotational speed ¹⁾	at $V_{\rm g}$ < $V_{\rm g \ max}^{2)}$	$n_{max\ perm}$	rpm	4320	3960	3600	3120	3140	3140	3140	3000	2500
Flow	at n_{nom} and $V_{g\;max}$	$q_{\scriptscriptstyle ee}$	l/min	37	59	84	117	162	163	187	212	230
			gpm	9.7	15.6	22	31	42	43	49.4	55	60
	at $n_{\rm E}$ = 1500 rpm	$q_{\scriptscriptstyle \sf VE}$	l/min	15	27	42	68	90	95	108	128	150
			gpm	4	7.1	11.1	18	24	25.1	28.5	34	39
Power	at $n_{ m nom}$, $V_{ m g\; max}$ and	P	kW	16	25	35	49	65	68	77	89	96
	Δp = 250 bar		HP	22	34	47	65	88	90	103	119	130
	at n_E = 1500 rpm	P_E	kW	7	11	18	28	37	39	45	53	62
			HP	9.4	15	24	38	50	52	60	71	84
Torque	at $V_{ m g\ max}$ and	M	Nm	42	71	111	179	238	250	286	338	398
	Δp = 250 bar		lb-ft	31	52	82	132	175	184	211	247	293
	at $V_{ m g\; max}$ and	M	Nm	17	29	45	72	95	100	114	135	159
	Δp = 100 bar		lb-ft	13	21	33	53	70	74	84	102	117
Rotary	S	с	kNm/rad	9.2	11.0	22.3	37.5	65.5	65.5	65.5	143.0	143.0
tiffness of	R		lb-ft/rad	6760	8082	16400	27560	48100	48100	48100	105100	10510
drive shaft		с	kNm/rad	-	14800	26300	41000	69400	69400	69400	152900	15290
			lb-ft/rad	-	10870	19400	30240	51200	51200	51200	112773	11277
	U	с	kNm/rad	6.8	8.0	16.7	30.0	49.2	49.2	49.2	102.9	102.9
			lb-ft/rad	5020	5870	12317	22130	36290	36290	36290	75900	75900
	W	с	kNm/rad	-	-	19.9	34.4	54.0	54.0	54.0	117.9	117.9
			lb-ft/rad	-	-	14678	25270	39830	39830	39830	86960	86960
	P	с	kNm/rad	10.7	-	-	-	-	-	-	-	-
			lb-ft/rad	7892	-	-	-	-	-	-	-	-
	K	c	kNm/rad	10.8	13.3	26.8	43.9	73.9	73.9	73.9	163.4	163.4
			lb-ft/rad	7965	9810	19770	32380	54506	54506	54506	120518	12051
	С	с	kNm/rad	-	-	4)	4)	4)	-	-	4)	-
			lb-ft/rad	-	-	4)	4)	4)	-	-	4)	-
Moment of in	ertia of the	$J_{\sf TW}$	kgm ²	0.0006	0.0009	0.0017	0.003	0.0056	0.0056	0.0056	0,012	0,012
rotary group			lb-ft²	0.0142	0.2207	0.0403	0.0783	0.1329	0.1329	0.1329	0.2848	0.284
Maximum ang	gular acceleration ³⁾	α	rad/s²	8000	6800	5500	4000	3300	3300	3300	2700	2700
Case volume		V	l	0.2	0.25	0.3	0.5	0.8	8.0	0.8	1	1
			gal	0.05	0.06	0.08	0.13	0.21	0.21	0.21	0.26	0.26
-	ut through drive	m	kg	8	11.5	15	18	22	22	22	36	36
(approx.)			lbs	17	25	33	40	48.5	48.5	48.5	79	79
Weight with t	hrough drive		kg	-	13	18	24	28	28	28	45	45
(approx.)			lbs	-	28.6	40	53	62	62	62	99	99

¹⁾ The values are applicable:

[–] at absolute pressure $p_{\rm abs}$ = 1 bar (15 psi) at suction port **S**

[–] for the optimum viscosity range from v_{opt} = 36 to 16 mm²/s (cSt)

⁻ with hydraulic fluid based on mineral oils

²⁾ See diagram on page 11 at speed increase up to $n_{
m max\; adm.}$

³⁾ The data are valid for values between the minimum required and maximum permissible rotational speed. Valid for external excitation (e.g. diesel engine 2 to 8 times the rotary frequency; cardan shaft 2 times the rotary frequency). The limit value is only valid for a single pump. The load capacity of the connection parts must be considered.

⁴⁾ On request

⁵⁾ Higher rotational speeds on request.

11



Axial piston variable pump | **A10VO series 52 and 53** Technical data

Determin	nation	of t	he characteristics			
Flow	$q_{\scriptscriptstyle ee}$	=	$\frac{V_{\rm g} \times n \times \eta_{\rm v}}{1000}$			[l/min]
Torque	M	=	$\frac{V_{\rm g} \times \Delta p}{20 \times \pi \times \eta_{\rm hm}}$			[Nm]
Power	P	=	2 π × M × n 60000	=	$\frac{q_{\rm v} \times \Delta p}{600 \times \eta_{\rm t}}$	[kW]

Determin	nation	of the chara	acteristics		
Flow	$q_{\scriptscriptstyle ee}$	=	$\frac{n \times \eta_{\text{v}}}{31}$		[gpm]
Torque	M	=	$\times \Delta p$ $ au \times \eta_{\text{hm}}$		[lb-ft]
Power	P	=	<u>M × n</u> 000 =	$\frac{q_{v} \times \Delta p}{1714 \times \eta_{t}}$	[HP]



 $V_{\rm g}$ Displacement per revolution [cm³ (inch³)]

 Δp Differential pressure [bar (psi)]

n Rotational speed [rpm]

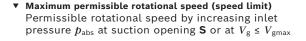
 η_{v} Volumetric efficiency

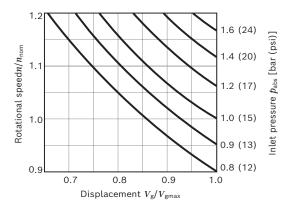
 $\eta_{
m hm}$ Hydraulic-mechanical efficiency

 $\eta_{\rm t}$ Total efficiency ($\eta_{\rm t} = \eta_{\rm v} \times \eta_{\rm hm}$)

Notice

- Theoretical values, without efficiency and tolerances; values rounded
- ▶ Operation above the maximum values or below the minimum values may result in a loss of function, a reduced service life or in the destruction of the axial piston unit. Bosch Rexroth recommends checking the load by means of test or calculation/simulation and comparison with the permissible values.







12 **A10VO series 52 and 53** | Axial piston variable pump Technical data

Permissible radial and axial loading of the drive shaft

Size		NG		10	18	28	45	60/63	72	85	100
Maximum radial force at a/2	Fq	$F_{q\;max}$	N	250	350	1200	1500	1700	1500	2000	2000
	a/2a/2		lbf	56	78	270	337	382	337	450	450
Maximum axial force	F +	± $F_{\rm ax\ max}$	N	400	700	1000	1500	2000	1500	3000	3000
	Fax +		lbf	90	157	225	337	450	337	675	675

Notice

► The values given are maximum values and do not apply to continuous operation. All loads of the drive shaft reduce the bearing service life.

Permissible inlet and through-drive torques

Size				10	18	28	45	60/63	72	85	100
Torque at V_{gmax} and		M_{max}	Nm	42	71	111	179	250	321	338	398
$\Delta p = 250 \text{ bar } (3600 \text{ psi})^{1)}$			lb-ft	31	52	82	132	184	211	247	293
Max. input torque on driv	e shaft ²⁾										
	S	$M_{E\;max}$	Nm	126	124	198	319	630	630	1157	1157
			lb-ft	93	91	146	235	464	464	853	853
		Ø	in	3/4	3/4	7/8	1	1 1/4	1 1/4	1 1/2	1 1/2
	R	$M_{E\;max}$	Nm	-	160	250	400	650	650	1215	1215
		l	lb-ft	-	118	184	295	479	479	895	895
		Ø	in	-	3/4	7/8	1	1 1/4	1 1/4	1 1/2	1 1/2
	U	$M_{E\;max}$	Nm	60	59	105	188	306	306	628	628
			lb-ft	44	43	77	139	226	226	463	463
		Ø	in	5/8	5/8	3/4	7/8	1	1	1 1/4	1 1/4
	W	$M_{E\;max}$	Nm	-	-	140	220	396	383	650	650
			lb-ft	-	-	103	162	292	282	479	479
		Ø	in	-	-	3/4	7/8	1	1	1 1/4	1 1/4
	Р	$M_{E\;max}$	Nm	90	-	-	-	-	-	-	-
		Ø	lb-ft	66	-	-	-	-	-	-	-
			mm	18	-	-	-	-	-	-	-
			in	0.71	-	_	-	-	-	-	-
	K	$M_{E\;max}$	Nm	106	104	145	212	441	441	750	750
			lb-ft	78	76	107	156	325	325	553	553
		Ø	in	3/4	3/4	7/8	1	1 1/4	1 1/4	1 1/2	1 1/2
	С	$M_{E\;max}$	Nm	-	-	145	212	441	-	750	-
				-	-	107	156	325	-	553	-
Maximum through-drive to	orque										
	S	$M_{D\;max}$	Nm	-	108	160	319	484	484	698	698
			lb-ft	-	80	118	235	357	357	515	515
	R	$M_{D\;max}$	Nm	-	120	176	365	484	484	698	-
			lb-ft	-	89	130	270	357	357	515	-
	U	$M_{D\;max}$	Nm	-	59	105	188	306	306	628	628
			lb-ft	-	43	77	139	226	226	463	463
	W	$M_{D\;max}$	Nm	-	-	140	220	396	383	650	650
			lb-ft	-	-	103	162	292	282	479	479
	K	$M_{D\;max}$	Nm	-	104	145	212	441	441	_	750
			lb-ft	-	76	107	156	325	325	-	553

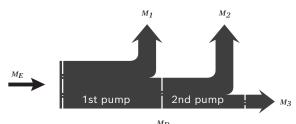
¹⁾ Efficiency not considered

²⁾ For drive shafts with no radial force



Axial piston variable pump | **A10VO series 52 and 53** 13 Technical data

▼ Distribution of torques



Torque at 1st pump	M_1	
Torque at 2nd pump	M_2	
Torque at 3rd pump	M_3	
Input torque	<i>M</i> _E =	$M_1 + M_2 + M_3$
	<i>M</i> _E <	$M_{E\;max}$
Through-drive torque	M_{D} =	$M_2 + M_3$
	<i>M</i> _D <	$M_{D\;max}$



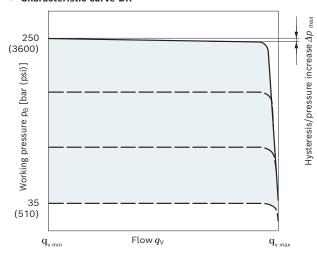
14 A10VO series 52 and 53 | Axial piston variable pump DR – Pressure controller

DR - Pressure controller

The pressure controller limits the maximum pressure at the pump outlet within the control range of the variable pump. The variable pump only supplies as much hydraulic fluid as is required by the consumers. If the working pressure exceeds the pressure command value at the pressure valve, the pump will regulate to a smaller displacement to reduce the control differential.

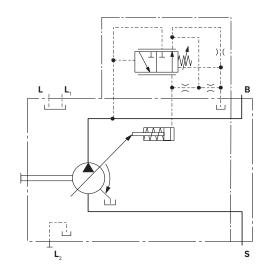
- ▶ Basic position in depressurized state: $V_{\rm g\ max}$.
- Setting range¹⁾ for pressure control 35 to 250 bar (510 to 3600 psi).
 Standard is 250 bar (3600 psi).

▼ Characteristic curve DR



Characteristic curve valid at n_1 = 1500 rpm and θ_{fluid} = 50 °C (120° F).

▼ Circuit diagram DR



Controller data

Size		10	18	28	45	60	72	85	100
						63			
Pressure increase	Δp [bar]	6	6	6	6	8	8	12	14
	Δp [psi]	90	90	90	90	115	115	175	200
Hysteresis	Δp [bar]	Max	imum	4					
	Δp [psi]	Max	imum	60					
Pilot fluid	[l/min]	Max	imum	appr	ox. 3				
consumption	[gpm]	Max	imum	appr	ox. 0.	8			

In order to prevent damage to the pump and the system, the permissible setting range must not be exceeded.
 The range of possible settings at the valve is higher.

15



Axial piston variable pump | **A10VO series 52 and 53**DRG – Pressure controller, remotely controlled

DRG - Pressure controller, remotely controlled

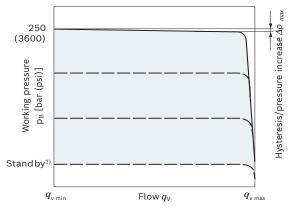
For the remote controlled pressure controller, the LS pressure relief is performed using a separately arranged pressure relief valve. Therefore, any pressure control value under the pressure set on the pressure controller can be regulated. Pressure controller DR see page 14. A pressure relief valve is externally piped up to port **X** for remote control. This relief valve is not included in the scope of delivery of the DRG control. When there is differential pressure of 20 bar (290 psi) Δp , the quantity of control fluid at the port is **X** approx. 1.5 l/min (0.4 gpm). If another setting is required (range from 14 to 22 bar (200 to 320 psi)) please state in plain text. As a separate pressure relief valve (1) we recommend:

- ► A direct operated, hydraulic or electric proportional one, suitable for the control fluid mentioned above. The maximum line length should not exceed 2 m (6.6 ft).
- ▶ Basic position in depressurized state: $V_{\rm g\ max}$.
- ► Setting range¹⁾ for pressure control 35 to 250 bar (510 to 3600 psi) (**3**).

 Standard is 250 bar (3600 psi).
- Setting range for differential pressure 14 to 22 bar (200 to 320 psi) (2)
 Standard is 20 bar (290 psi).

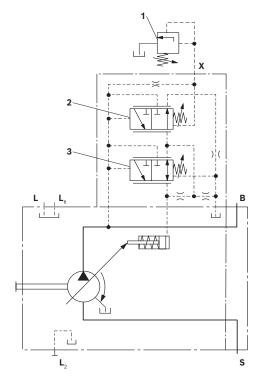
Unloading port **X** to the reservoir results in a zero stroke pressure (standby) which is approx. 1 to 2 bar (15 to 30 psi) higher than the defined differential pressure Δp , however system influences are not taken into account.

▼ Characteristic curve DRG



Characteristic curve valid at n_1 = 1500 rpm and ϑ_{fluid} = 50 °C (120 °F).

▼ Circuit diagram DRG



- **1** The separate pressure relief valve and the line are not included in the scope of delivery.
- 2 Remote controlled pressure cut-off (G)
- 3 Pressure controller (DR)

Controller data

Size		10	18	28	45	60 63	72	85	100
Pressure	Δp [bar]	6	6	6	6	8	8	12	14
increase	Δp [psi]	87	87	87	87	115	115	175	200
Hysteresis	Δp [bar]	Maximum 4							
	Δp [psi]	Max	imum	60					
Pilot fluid	[l/min]	Max	imum	appr	ox. 3				
consumption	[gpm]	Max	imum	appr	ox. 0.	8			

In order to prevent damage to the pump and the system, the permissible setting range must not be exceeded.
 The range of possible settings at the valve is higher.

Zero stroke pressure from pressure setting Δp on controller (2)

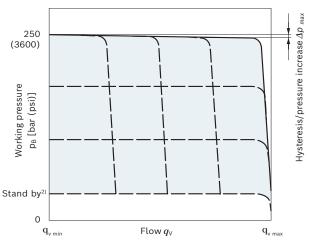


16 **A10VO series 52 and 53** | Axial piston variable pump DRF (DFR) / DRS (DFR1) / DRSC- Pressure and flow controller

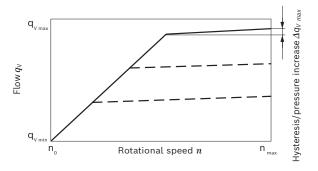
DRF (DFR) / DRS (DFR1) / DRSC- Pressure and flow controller

In addition to the pressure controller function (see page 14), an adjustable orifice (e.g. directional valve) is used to adjust the differential pressure upstream and downstream of the orifice. This is used to control the pump flow. The pump flow is equal to the actual hydraulic fluid quantity required by the consumer. With all controller combinations, the $V_{\rm g}$ reduction has priority.

- lacktriangle Basic position in depressurized state: $V_{\rm g\ max}$.
- ► Setting range¹⁾ to 250 bar (3600 psi)
- ▶ DR pressure controller data see page 14
- ▼ Characteristic curve DRF (DFR) / DRS (DFR1) / DRSC



▼ Characteristic curve at variable rotational speed



Characteristic curves valid at n_1 = 1500 rpm and ϑ_{fluid} = 50 °C (120 °F).

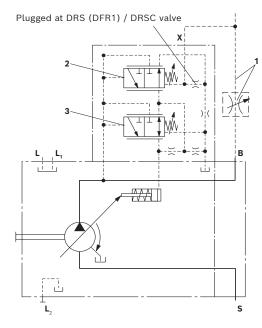
- 1) In order to prevent damage to the pump and the system, the permissible setting range must not be exceeded. The range of possible settings at the valve is higher.
- $_{2)}$ Zero stroke pressure from differential pressure setting Δp on controller (2)

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Possible connections at port **B** (not included in the scope of delivery)

LS mobile control blocks	Data sheets				
M4-12	64276				
M4-15	64283				
LUDV mobile control blocks					
M7-22	64295				

▼ Circuit diagram DRF (DFR)



- 1 The metering orifice (control block) and the line is not included in the scope of delivery.
- 2 Flow controller (FR).
- 3 Pressure controller (DR)

Notice

The DRS (DFR1) and DRSC versions have no unloading from \mathbf{X} to the reservoir.

The LS must thus be unloaded in the system.

Because of the flushing function sufficient unloading of the flow controller in DRS (DFR1) control valve \mathbf{X} -line must also be provided.

If this unloading of the ${\bf X}$ line cannot be ensured, the DRF control valve must be used.

For further information see page 17



Axial piston variable pump | **A10VO series 52 and 53**DRF (DFR) / DRS (DFR1) / DRSC- Pressure and flow controller

Differential pressure Δp :

 Standard setting: 14 bar (200 psi) If another setting is required, please state in clear text.

▶ Setting range: 14 bar to 22 bar (200 to 320 psi) Unloading port \mathbf{X} to the reservoir results in a zero stroke pressure (standby) which is approx. 1 to 2 bar (15 to 30 psi) higher than the defined differential pressure Δp , however system influences are not taken into account.

Controller data

- ▶ DR pressure controller data, see page 14
- ► Maximum flow deviation measured at drive speed n = 1500 rpm.

Size		10	18	28	45	60 63	72	85	100
Flow deviation	$\Delta q_{ m vmax}$ [l/min]	0.5	0.9	1.0	1.8	2.5	2.5	3.1	3.1
	$\Delta q_{ m vmax}$ [gpm]	0.13	0.24	0.26	0.48	0.66	0.66	0.83	0.83
Hysteresis	Δp [bar]	Maximum 4	1						
	Δp [psi]	Maximum 6	60						
Pilot fluid consumption	[l/min]	Maximum approx. 3 to 4.5 (DRF (DFR)) Maximum approx. 3 ((DFR1) / DRSC)							
	[gpm]			o 1.2 (DRF ((DFR1) / DR					



18 **A10VO series 52 and 53** | Axial piston variable pump LA... – Pressure, flow and power controller

LA... - Pressure, flow and power controller

Pressure controller equipped as DR(G), see page 14 (15). Equipment of the flow controller like DRS (DFR1), see page 16.

In order to achieve a constant drive torque with varying working pressures, the swivel angle and with it the volume flow from the axial piston pump is varied so that the product of flow and pressure remains constant. Flow control is possible below the power control curve. When ordering

please state the power characteristics to be set at the factory in plain text, e.g. 20 kW (27 HP) at 1500 rpm.

Controller data

- ▶ Pressure controller DR see page 14.
- ▶ Pressure and flow controller DR see page 16.
- ► Pilot fluid consumption max. approx. 5.5 l/min (1.45 gpm).

Beginning of control	Torque M [Nm	(lb-ft)] for size	9		,			Code
[bar (psi)	18	28	45	63	72	85	100	
10 to 35	3.8 - 12.1	6 – 19	10 - 30	15 – 43	17 - 49.2	20 - 57	24 - 68	LA5
(145 to 510)	(2.80 - 8.92)	(4.4 - 14)	(7.4 - 22.1)	(11 – 32)	(12.5 - 36.3)	(15 – 42)	(18 – 49.5)	
36 to 70	12.2 - 23.3	19.1 – 36	30.1 – 59	43.1 – 83	49.3 - 94.9	57.1 – 112	68.1 – 132	LA6
(520 to 1015)	8.92 / 17.2	(14 - 26.5)	(22.2 – 43.5)	(32 – 61)	(36.4 - 69.9)	(42 - 83)	(49.5 - 97.1)	
71 to 105	23.4 - 33.7	36.1 – 52	59.1 – 84	83.1 - 119	95.0 - 136.0	112.1 – 160	132.1 – 189	LA7
(1030 to 1520)	(17.2 -24.9)	(26.6 - 38.4)	(43.6 - 62)	(61 – 88)	(70 - 100.3)	(83 – 118)	(97.1 - 139.4)	
106 to 140	33.8 – 45	52.1 - 70	84.1 - 112	119.1 – 157	136.1 – 179.4	160.1 – 212	189.1 – 249	LA8
(1535 to 2030)	(24.9 -33.2)	(38.4 - 51.6)	(62 – 83)	(88 – 116)	(100.4 - 132.3)	(118 – 156)	(139.4 - 183.6)	
141 – 230	45.1 – 74.8	70.1 – 117	112.1 – 189	157.1 – 264	179.5 – 301.7	212.1 – 357	249.1 – 419	LA9
(2045 to 3335)	(33.2 - 55.2)	(51.7 - 86.3)	(83 – 139)	(116 – 195)	(132.4 - 222.5)	(156 – 263)	(183.3 - 309)	

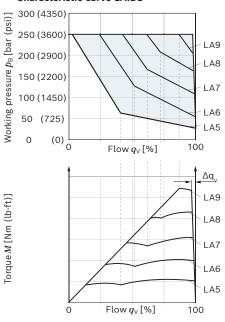
Conversion of the torque values in power [kW (HP)]

$$P = \frac{M}{6.4 (3.5)}$$
 [kW (HP)] (At 1500 rpm)

$$P = \frac{2\pi \times M \times n}{60000 (33000)}$$

- [kW (HP)] (For rotational speeds see table on page 10)

▼ Characteristic curve LA.DS



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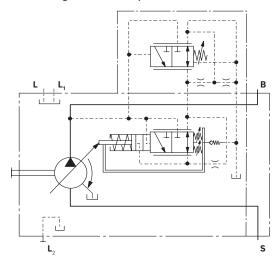
► Combination options with LA.. see page 19)



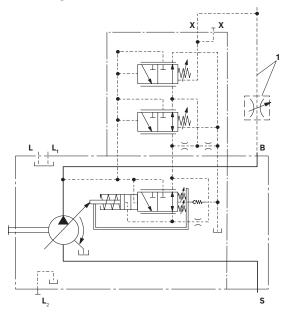
Axial piston variable pump | **A10VO series 52 and 53** 19 LA... – Variations

LA... - Variations

▼ Circuit diagram LA.D with pressure cut-off

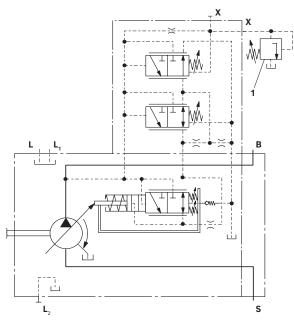


▼ Circuit diagram LA.DS



1 The metering orifice (control block) and the line is not included in the scope of delivery.

▼ Circuit diagram LA.DG with pressure cut-off, remote controlled



1 The pressure relief valve and the line are not included in the scope of delivery.



20 A10VO series 52 and 53 | Axial piston variable pump ED – Electro-hydraulic pressure control

ED - Electro-hydraulic pressure control

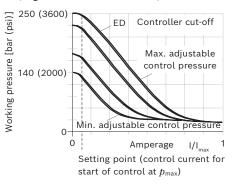
The ED valve is set to a certain pressure by a specified variable solenoid current.

When changing the consumer (load pressure), this causes an increase or decrease in the pump swivel angle (flow) in order to maintain the electrically set pressure level.

The pump thus only delivers as much hydraulic fluid as the consumers can take. The desired pressure level can be set steplessly by varying the solenoid current.

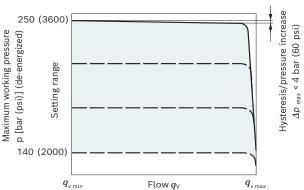
As the solenoid current signal drops towards zero, the pressure will be limited to $p_{\rm max}$ by an adjustable hydraulic pressure cut-off (secure fail safe function in case of power failure, e.g. for fan speed control). The swivel time characteristic of the ED control was optimized for the use as a fan drive system. When ordering, specify the type of application in plain text.

▼ Current-pressure characteristic ED (negative characteristic curve)



► Hysteresis static < 25 bar (365 psi).

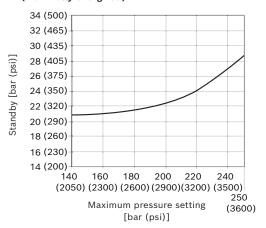
▼ Flow-pressure characteristic curve



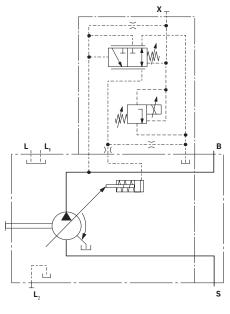
► Characteristic curves valid at n_1 = 1500 rpm and ϑ_{fluid} = 50 °C (120 °F).

- ▶ Pilot fluid consumption: 3 to 4.5 l/min (0.8 to 1.2 gpm).
- For standby standard setting, see the following diagram, other values on request

▼ Influence of the pressure setting on standby (maximally energized)



▼ Circuit diagram ED71/ED72





Axial piston variable pump | **A10VO series 52 and 53** 21 ED – Electro-hydraulic pressure control

Technical data, solenoids	ED71	ED72					
Voltage	12 V (±20%)	24 V (±20%)					
	12 V (±2076)	24 V (±2070)					
Control current							
Start of control at p_{\max}	100 mA	50 mA					
End of control at $p_{ \mathrm{min}}$	1200 mA	600 mA					
Current limit	1.54 A	0.77 A					
Nominal resistance	5.5 Ω	22.7 Ω					
(at 20 °C (68 °F))							
Dither frequency	100 Hz	100 Hz					
Recommended amplitude	120 mA	60 mA					
Duty cycle	100%	100%					
Type of protection: see conne	ector version page	15					
Operating temperature range at valve -20 °C to +115 °C							
(-4 °F to +239 °F)							

The following electronic control units are available for control:

BODAS Controllers	Data sheet
RC5-6, series 40	95207
RC18-12, series 40	95208
RC27-18, series 40	95208

Notice!

With **ED71**, de-energized operating condition (jump from 100 to 0 mA) results in a pressure increase of the maximum pressure of 4 to 5 bar (60 to 75 psi). With **ED72**, de-energized operating condition (jump from 50 to 0 mA) results in a pressure increase of the maximum pressure of 4 to 5 bar (60 to 75 psi).



22 **A10VO series 52 and 53** | Axial piston variable pump ER – Electro-hydraulic pressure control

ER - Electro-hydraulic pressure control

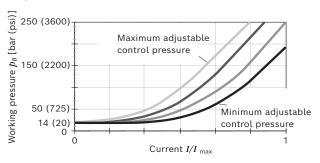
The ER valve is set to a certain pressure by a specified variable solenoid current.

When a change is made at the consumer (load pressure), the position of the control spool will shift.

This causes an increase or decrease in the pump swivel angle (flow) in order to maintain the electrically set pressure level. The pump thus only delivers as much hydraulic fluid as the consumers can take. The desired pressure level can be set steplessly by varying the solenoid current. As the solenoid current signal drops towards zero, the pressure will be limited to p_{\min} (stand by).

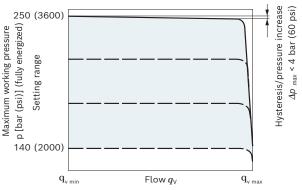
Observe project planning notes.

▼ Current-pressure characteristic curve ER (positive characteristic curve)



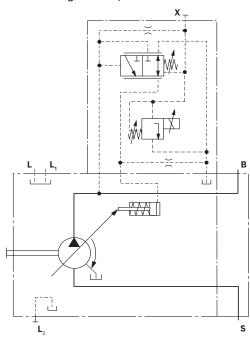
 Hysteresis static current-pressure characteristic curve < 25 bar (365 psi).

▼ Flow-pressure characteristic curve



- Characteristic curves valid at n_1 = 1500 rpm and θ_{fluid} = 50 °C (120 °F).
- ▶ Pilot fluid consumption: 3 to 4.5 l/min (0.8 to 1.2 gpm).
- Standby standard 14 bar (200 psi). Other values on request.
- ► Influence of pressure setting on standby ± 2 bar (±30 psi).

▼ Circuit diagram ER71/ER72



Technical data, solenoids	ER71	ER72
Voltage	12 V (±20%)	24 V (±20%)
Control current		
Start of control at p_{min}	100 mA	50 mA
End of control at p_{max}	1200 mA	600 mA
Current limit	1.54 A	0.77 A
Nominal resistance (at 20 °C (68 °F))	5.5 Ω	22.7 Ω
Dither frequency	100 Hz	100 Hz
Recommended amplitude	120 mA	60 mA
Duty cycle	100%	100%
Type of protection: see connector vers	sion page 78	
Operating temperature range at valve (4 °F to +239 °F)	20 °C to +115	°C

Project planning note!

Excessive current levels (I > 1200 mA at 12 V or I > 600 mA at 24 V) to the ER solenoid can result in undesired pressure increases which can lead to pump or system damage. Therefore:

- ▶ Use I_{max} current limiter solenoids.
- An intermediate plate pressure controller can be used to protect the pump in the event of overflow.

An accessory kit with intermediate plate pressure controller can be ordered from Bosch Rexroth under part number R902490825.

23



Axial piston variable pump | **A10VO series 52 and 53**EP – Electro-proportional control

EP - Electro-proportional control

Electro proportional control makes a continuous and reproducible setting of the pump displacement possible directly via the cradle. The control force of the control piston is applied by a proportional solenoid. The control is proportional to the current (for start of control, see table right).

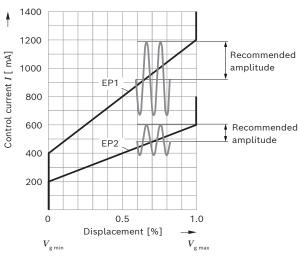
In a depressurized state, the pump is swiveled to its initial position ($V_{\rm g\ max}$) by an adjusting spring. If the working pressure exceeds a limit value of approx. 4 bar (60 psi), the pump starts to swivel from $V_{\rm g\ max}$ to $V_{\rm g\ min}$ without control by the solenoid (control current < start of control). With a minimum swivel angle $V_{\rm g\ min}$ and de-energized EP solenoids, a minimum pressure of 10 bar (145 psi) must be maintained.

A PWM signal is used to control the solenoid.

EP.D: The pressure control regulates the pump displacement back to $V_{\rm g\;min}$ after the set pressure command value has been reached.

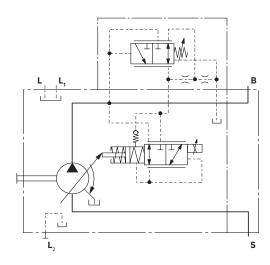
A minimum working pressure of 14 bar (200 psi) is needed for safe and reproducible control. The required control fluid is taken from the high pressure.

▼ Characteristic curve EP1/2



 Hysteresis static current-displacement characteristic curve < 5 %.

▼ Circuit diagram EP.D



Technical data, solenoids	EP1	EP2
Voltage	12 V (±20%)	24 V (±20%)
Control current		
Start of control at V_{gmin}	400 mA	200 mA
End of control at $V_{ m g\ max}$	1200 mA	600 mA
Dither frequency	100 Hz	100 Hz
Recommended amplitude	120 mA	60 mA
Current limit	1.54 A	0.77 A
Nominal resistance (at 20 °C (68 °F))	5.5 Ω	22.7 Ω
Duty cycle	100%	100%
Type of protection: see connector ver	sion page 78	

Operating temperature range at valve –20 °C to +115 °C (–4 °F to +239 °F)

Notice!

We recommend the valve with flushing function for the EP.D control variant. Please contact us.

The following electronic control units are available for control:

BODAS Controllers	Data sheet
RC5-6, series 40	95207
RC18-12, series 40	95208
RC27-18, series 40	95208



24 A10VO series 52 and 53 | Axial piston variable pump EK – Electro-proportional control with controller cut-off

EK - Electro-proportional control with controller cut-off

Variant EK... is based completely on the variant EP... (see page 23).

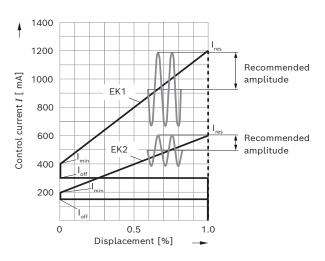
In addition to the electro-proportional control function, a controller cut-off is integrated in the electric characteristic curve. The pump then swivels to $V_{\rm g\ max}$ if the pilot signal is lost (e.g. cable break) and then works with the DRF settings if necessary (see page 16). The controller cut-off is only intended for short-term use and not for permanent use if the pilot signal is lost. If the pilot signal is lost, the pump swivel times will be increased by the EK valve. A PWM signal is used to control the solenoid.

Notice!

A minimum working pressure of 50 bar (725 psi) is needed for safe and reproducible electro-proportional control with controller cut-off. For lower pressures, a pilot signal of > 500 mA (EK2) or > 1000 mA (EK1) is required in order to avoid undesired controller cut-off. The required control fluid is taken from the high pressure.

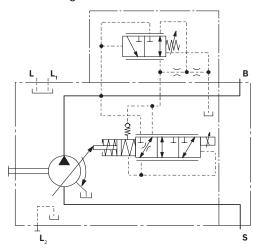
In $V_{\rm g\ max}$ position, the spring force of the return spring is maximum. To overcome the force of this spring, the solenoid must be subjected to excessive current (I_{res}).

▼ Characteristic curve EK1/2



- Hysteresis static current-displacement characteristic curve < 5 %.
- For changes in current, ramp times of > 200 ms must be observed.

▼ Circuit diagram EK.D



Technical data, solenoids	EK1	EK2
Voltage	12 V (±20%)	24 V (±20%)
Control current		
Start of control at $V_{ m g\ min}$	400 mA	200 mA
End of control at $V_{ m g\ max}$	1200 mA	600 mA
Dither frequency	100 Hz	100 Hz
Recommended amplitude	120 mA	60 mA
Current limit	1.54 A	0.77 A
Nominal resistance (at 20 °C (68 °F))	5.5 Ω	22.7 Ω
Duty cycle	100%	100%

Type of protection: see connector version page 78

Operating temperature range at valve -20 °C to +115 °C

(-4 °F to +239 °F)

	EK1	EK2	
I _{min} [mA]	400	200	
I _{max} [mA]	1200	600	
I _{off} [mA]	< 300	< 150	
I _{res} [mA]	> 1200	> 600	

Notice

We recommend the valve with flushing function for the EK.D control variant. Please contact us.

The following electronic control units are available for control:

BODAS Controllers	Data sheet
RC5-6, series 40	95207
RC18-12, series 40	95208
RC27-18, series 40	95208



Axial piston variable pump | A10VO series 52 and 53 EP(K).DF / EP(K).DS / EP(K) – with pressure flow controller

EP(K).DF / EP(K).DS / EP(K) - with pressure flow controller

A hydraulic pressure flow control is superimposed on the electro-proportional control.

The pressure control regulates the pump displacement infinitely varied back to $V_{\rm g\,min}$ after the set pressure command value has been reached.

This function is super-imposed on the EP or EK control, i.e. the control-current dependent EP or EK function is executed below the pressure command value.

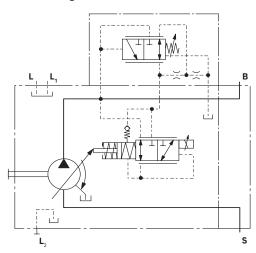
For the setting range of the pressure flow controller, see page 14 to 16.

With all controller combinations, the $V_{\rm g}$ reduction has priority.

With flow control, the pump flow can be influenced in addition to pressure control. The pump flow is thus equal to the actual amount of hydraulic fluid required by the consumer. This is achieved using the differential pressure at the consumer (e.g. orifice).

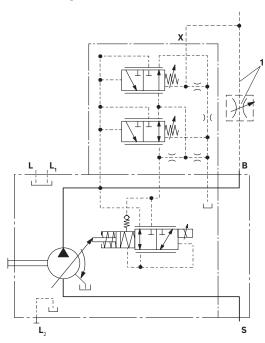
The EP.DS or EK.DS version has no connection between **X** and the reservoir (load-sensing). Please refer to the notes on page 16.

▼ Circuit diagram EP.D

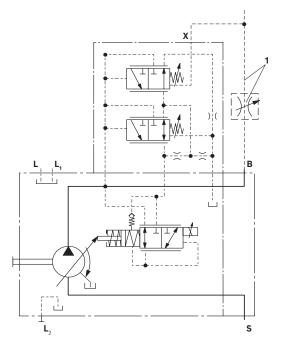


1 The metering orifice (control block) and the line is not included in the scope of delivery.

▼ Circuit diagram EP.DF



▼ Circuit diagram EP.DS



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26 **A10VO series 52 and 53** | Axial piston variable pump EP.ED / EK.ED – with electro-hydraulic pressure control

EP.ED / EK.ED - with electro-hydraulic pressure control

The ED valve is set to a certain pressure by a specified variable solenoid current.

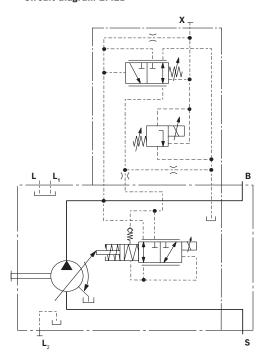
When changing the consumer (load pressure), this causes an increase or decrease in the pump swivel angle (flow) in order to maintain the electrically set pressure level.

The pump thus only delivers as much hydraulic fluid as the consumers can take. The pressure can be set steplessly by the solenoid current.

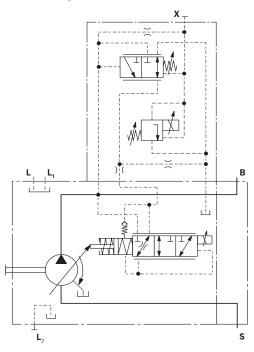
As the solenoid current signal drops towards zero, the pressure will be limited to $p_{\rm max}$ by an adjustable hydraulic pressure cut-off (negative characteristic curve, e.g. for fan speed control). A PWM signal is used to control the solenoid.

For further information and technical data of the solenoids for ED(ER) control please refer to pages 20 to 24.

▼ Circuit diagram EP.ED



▼ Circuit diagram EK.ED





Axial piston variable pump | **A10VO series 52 and 53** EC4 – Electro-hydraulic control valve (positive control)

27

EC4 - Electro-hydraulic control valve (positive control)

The proportional directional valve EC4 serves to control an axial piston variable pump with eOC control functions in an electronically closed control circuit.

The valve spool is clamped between a proportional solenoid and a spring and releases a opening cross-section depending on the stroke.

This results in a proportionality of the solenoid current with respect to the opening cross-section and thus the swiveling speed of the pump.

If the neutral current is above the neutral position ($I_{neutral}$), the pump swivels in the direction of $V_{g \, max}/100\%$; if it is below, the pump swivels in the direction of $V_{g \, min}/0\%$. For control of the pump with BODAS eOC, a swivel angle sensor is required.

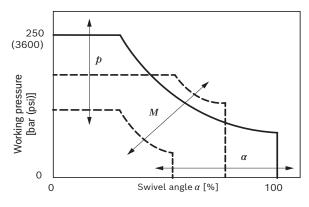
Further information about the swivel angle sensor can be found on page 79 and in data sheet 95153.

Further information on project planning of the BODAS eOC control system including other required system components can be found in data sheet 95345.

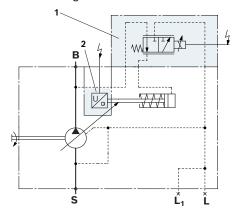
The BODAS eOC control software supports all four basic control types of axial piston variable pumps in electrically closed control circuits:

- ▶ Pressure and differential pressure regulation (p)
- ightharpoonup Swivel angle and flow control (α)
- ► Torque control (*M*)
- ► Power control

▼ Control variants with EC4



▼ Circuit diagram EC4



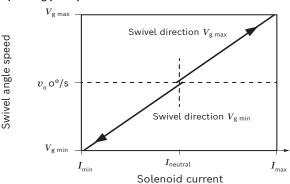
- 1 Proportional directional valve EC4
- 2 Swivel angle sensor (see data sheet 95153)

The following electronic control units are available for control:

BODAS Controllers	Data sheet	
RC5-6, series 40	95207	
RC18-12, series 40	95208	
RC27-18, series 40	95208	

For further technical data on the solenoid with respective information, see pages 28 and 78

▼ Operating principle EC4





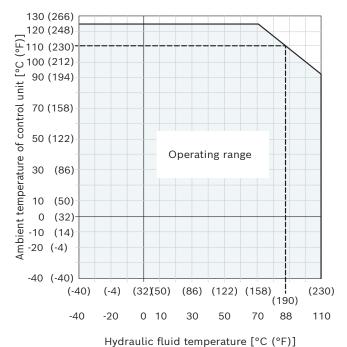
28 **A10VO series 52 and 53** | Axial piston variable pump EC4 – Electro-hydraulic control valve (positive control)

Solenoid technical data

	EC4
Maximum solenoid current	1900 mA
Nominal resistance at 20 °C (68 °F) winding temperature	4.26 ±0.26 Ω
Hot resistance 180 °C (356 °F) winding temperature	6.92 ±0.42 Ω
Limit temperature for winding	Insulating material class H (180 °C (356 °F))
Hydraulic fluid or operating temperature	From -40 °C to 110 °C (-40 °F to 230 °F)

Notice

- ► The coil has a limit voltage of 100 V. In general, the maximum current must not be exceeded by the actual current.
- ► For calculation of the hot resistance, a temperature coefficient of 0.0039k⁻¹ is to be applied.
- ▼ Characteristic curve of permitted operating range Example: At a hydraulic fluid temperature of 88 °C (190 °F), an ambient temperature of 110 °C (230 °F) is permitted.





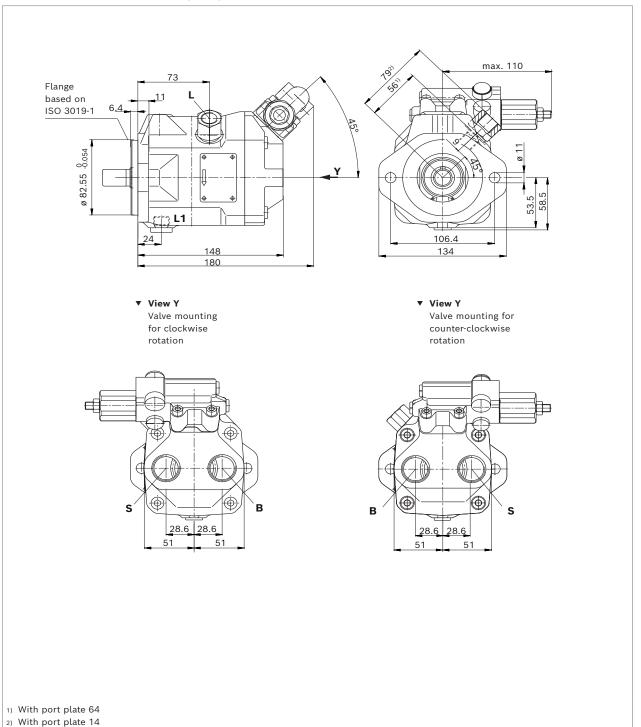
Dimensions [mm]

Axial piston variable pump | **A10VO series 52 and 53** 29

Dimensions, size 10

Dimensions, size 10

DR - Pressure controller; mounting flange C SAE version; port plate 14 (64); series 52



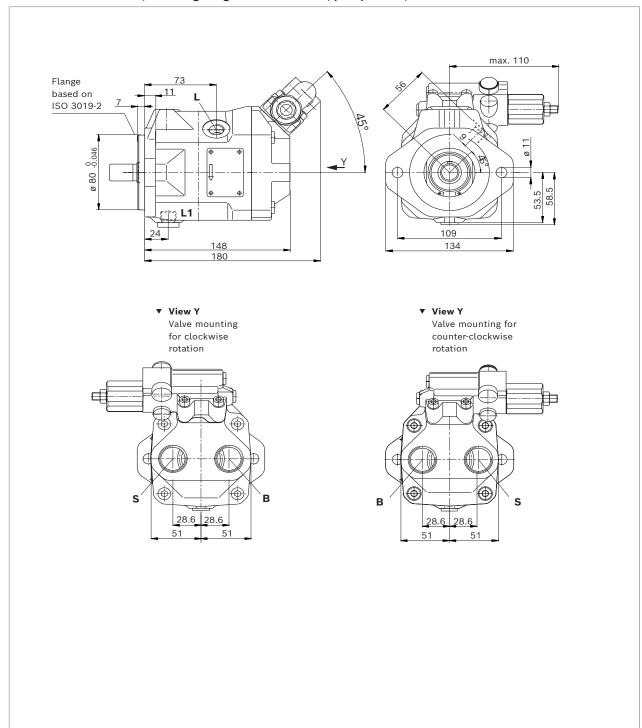


30 **A10VO series 52 and 53** | Axial piston variable pump Dimensions, size 10

Dimensions [mm]

Dimensions, size 10

DR - Pressure controller; mounting flange A metric version; port plate 14; series 52



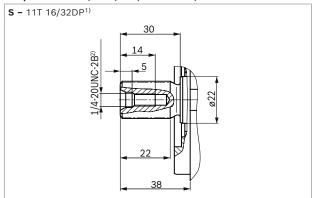


Dimensions [mm (inch)]

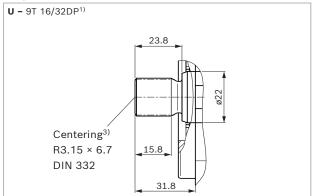
Axial piston variable pump | **A10VO series 52 and 53** 31

Dimensions, size 10

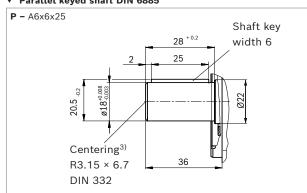
▼ Splined shaft 3/4 in (19-4, ISO 3019-1)



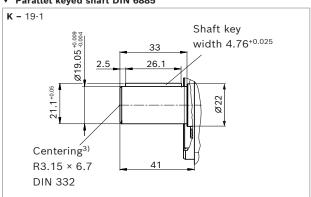
▼ Splined shaft 5/8 in (16-4, ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



▼ Parallel keyed shaft DIN 6885



Mounting flange	A ports (metric); port plate 14	Standard	Size	$p_{\sf max}$ [bar (psi)] $^{4)}$	State ⁷⁾
В	Working port	DIN 3852	M27 × 2; 16 (0.63) deep	315 (4550)	0
S	Suction port	DIN 3852	M27 × 2; 16 (0.63) deep	5 (75)	0
L	Drain port	DIN 3852 ⁵⁾	M16 × 1.5; 12 (0.47) deep	2 (30)	O ⁶⁾
L ₁	Drain port	DIN 3852 ⁵⁾	M16 × 1.5; 12 (0.47) deep	2 (30)	X ⁶⁾
X with adapter	Pilot pressure	DIN 3852	M14 × 1.5; 12 (0.47) deep	315 (4550)	0
Mounting flange C ports (SAE); port plate 64		Standard	Size	p_{max} [bar (psi)] $^{4)}$	State ⁷⁾
В	Working port	ISO 11926	1 1/16-12UNF-2B; 20 (0.79) deep	315 (4550)	0
S	Suction port	ISO 11926	1 1/16-12UNF-2B; 20 (0.79) deep	5 (75)	0
L without adapter (standard)	Drain port	ISO 11926 ⁵⁾	9/16-18UNF-2B; 12 (0.47) deep	2 (30)	O ⁶⁾
L with adapter	Drain port	ISO 3852 ⁵⁾	M16 × 1.5; 12 (0.47) deep	2 (30)	O ⁶⁾
L ₁ without adapter	Drain port	ISO 11926 ⁵⁾	9/16-18UNF-2B; 12 (0.47) deep	2 (30)	X ⁶⁾
X without adapter (standard)	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 (0.45) deep	315 (4550)	0
X with adapter	Pilot pressure	ISO 3852	M14 × 1.5; 12 (0.47) deep	315 (4550)	0

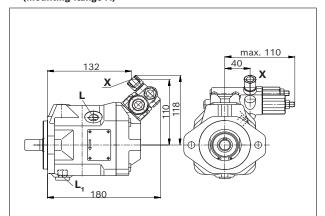
- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to ASME B1.1
- 3) Coupling axially secured, e.g. with a clamp coupling or radially mounted clamping screw
- 4) Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.
- 5) The countersink may be deeper than specified in the standard.
- 6) Depending on the installation position, ${\bf L}$ or ${\bf L}_1$ must be connected (also see installation instructions starting on page 80).
- 7) O = Must be connected (plugged on delivery)
 - X = Plugged (in normal operation)



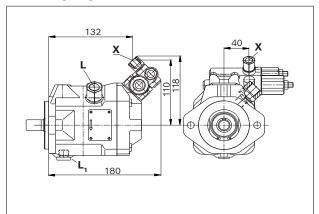
32 **A10VO series 52 and 53** | Axial piston variable pump Dimensions, size 10

Dimensions [mm]

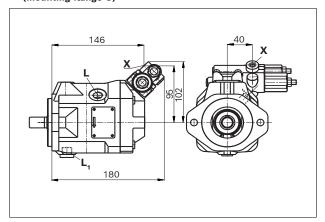
▼ DRG - Pressure controller, remotely controlled (mounting flange A)¹)



▼ DRG - Pressure controller, remotely controlled (mounting flange C)¹⁾²⁾



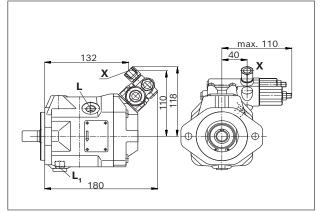
▼ DRG - Pressure controller, remotely controlled (mounting flange C)¹⁾³⁾



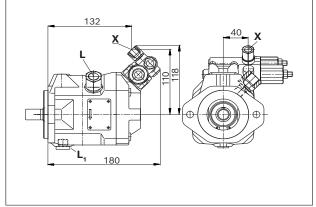
- Valve mounting for clockwise or counter-clockwise rotation see page 29 and 30
- 2) With metric adapter
- 3) Version complete SAE without adapter

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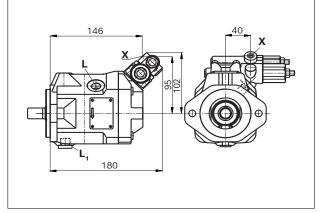
▼ DFR/DFR1 - Pressure, flow controller (mounting flange A)¹)



 DFR/DFR1 - Pressure, flow controller (mounting flange C)¹⁾²⁾



▼ DFR/DFR1 - Pressure, flow controller (mounting flange C)¹⁾³⁾



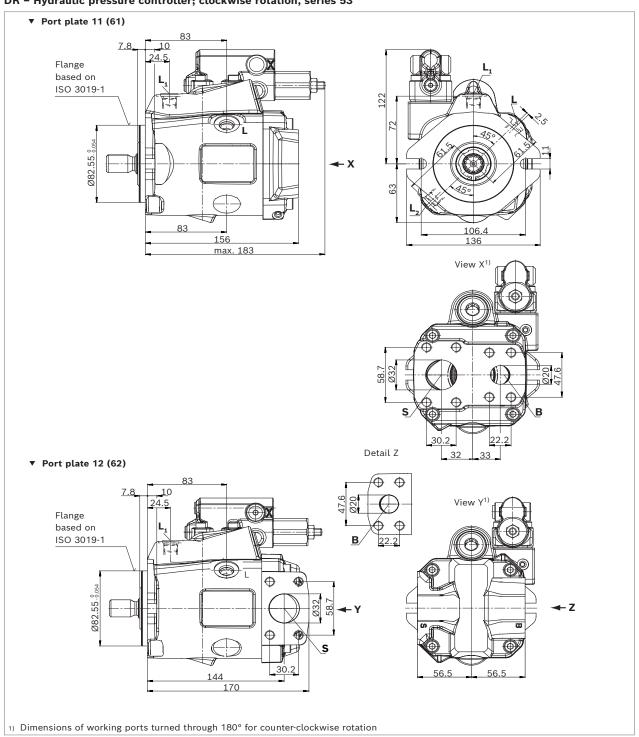


Dimensions [mm]

Axial piston variable pump | **A10VO series 52 and 53**Dimensions, size 18

Dimensions, size 18

DR - Hydraulic pressure controller; clockwise rotation, series 53

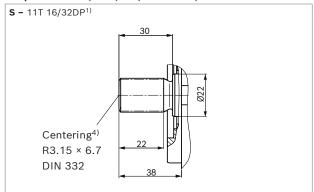




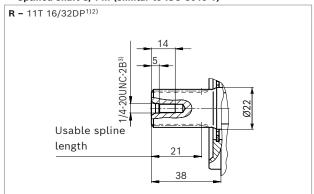
34 **A10VO series 52 and 53** | Axial piston variable pump Dimensions, size 18

Dimensions [mm (inch)]

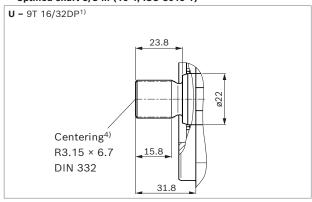
▼ Splined shaft 3/4 in (19-4, ISO 3019-1)



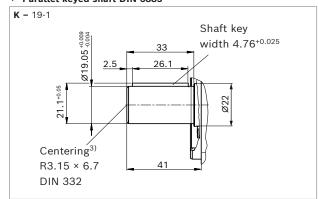
▼ Splined shaft 3/4 in (similar to ISO 3019-1)



▼ Splined shaft 5/8 in (16-4, ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



Port pl	late 11, 12	Standard	Size	$p_{\sf max}$ [bar (psi)] $^{5)}$	State ⁸⁾
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	3/4 in M10 × 1.5; 17 (0.67) deep	315 (4550)	0
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	1 1/4 in M10 × 1.5; 17 (0.67) deep	5 (75)	0
Port plate 61, 62		Standard	Size	$p_{\sf max}$ [bar (psi)] $^{5)}$	State ⁸⁾
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	3/4 in 3/8-16UNC-2B; 19 (0.75) deep	315 (4550)	0
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	1 1/4 in 7/16-14UNC-2B; 24 (0.94) deep	5 (75)	0
Other	ports	Standard	Size	$p_{\sf max}$ [bar (psi)] $^{5)}$	State ⁸⁾
L	Drain port	ISO 11926 ⁶⁾	3/4-16UNF-2B; 12 (0.47) deep	2 (30)	O ⁷⁾
L ₁ , L ₂	Drain port	ISO 11926 ⁶⁾	3/4-16UNF-2B; 12 (0.47) deep	2 (30)	X ⁷⁾
Х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 (0.45) deep	315 (4550)	0

- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.
- 3) Thread according to ASME B1.1
- 4) Coupling axially secured, e.g. with a clamp coupling or radially mounted clamping screw
- 5) Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.
- $_{\rm 6)}\,$ The countersink may be deeper than specified in the standard.
- $_{7)}\,$ Depending on the installation position, $L,\,L_{1}$ or L_{2} must be connected (also see installation instructions starting on page 80).
- 8) O = Must be connected (plugged on delivery)
- X = Plugged (in normal operation)

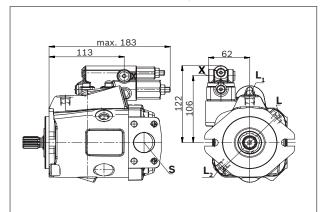


Dimensions [mm]

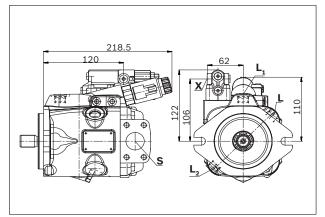
Axial piston variable pump | A10VO series 52 and 53

Dimensions, size 18

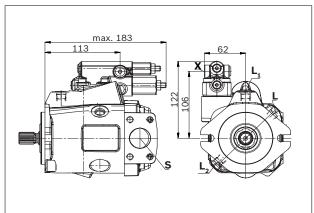
▼ DRG - Pressure controller, remotely controlled, series 53



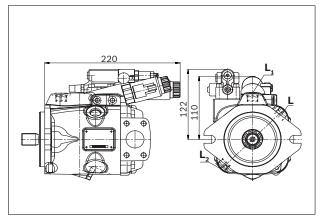
▼ EP.D. / EK.D. - Electro-proportional control, series 53



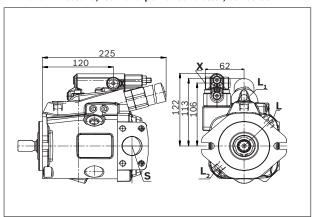
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



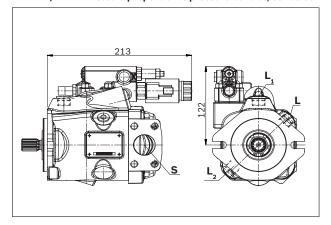
▼ EP.ED. / EK.ED. - Electro-proportional control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-proportional pressure control, series 53



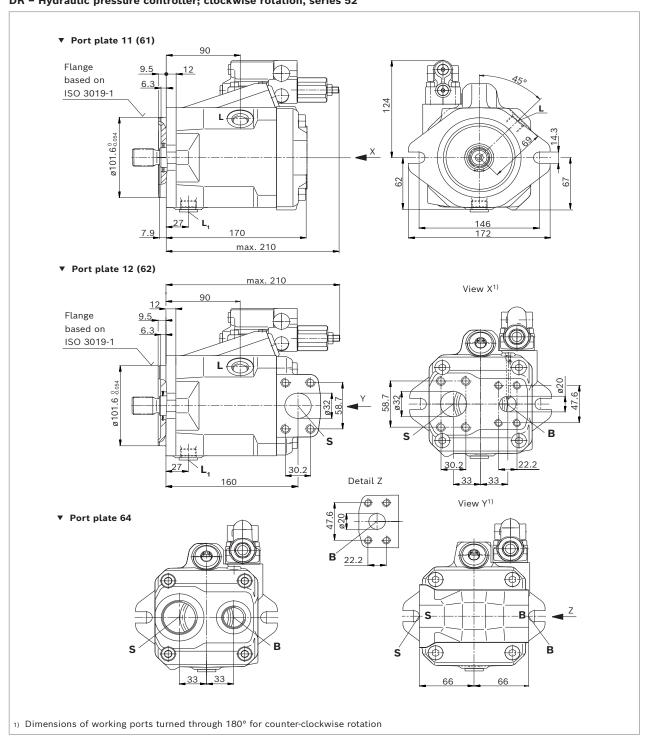


36 **A10VO series 52 and 53** | Axial piston variable pump Dimensions, size 28

Dimensions [mm]

Dimensions, size 28

DR - Hydraulic pressure controller; clockwise rotation, series 52



37

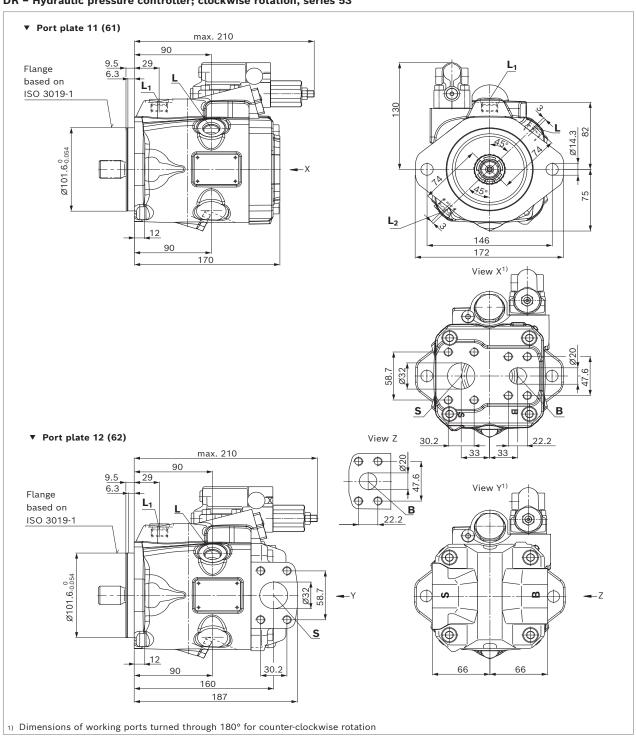


Dimensions [mm]

Axial piston variable pump | **A10VO series 52 and 53**Dimensions, size 28

Dimensions, size 28

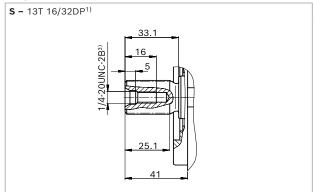
DR - Hydraulic pressure controller; clockwise rotation, series 53



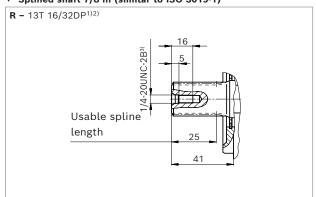


Dimensions [mm]

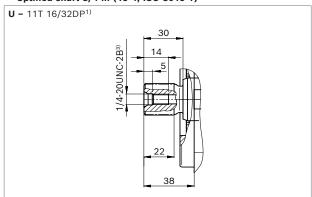
▼ Splined shaft 7/8 in (22-4, ISO 3019-1)



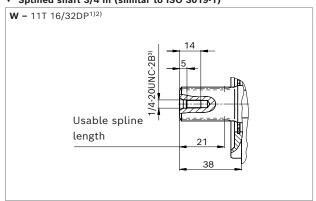
▼ Splined shaft 7/8 in (similar to ISO 3019-1)



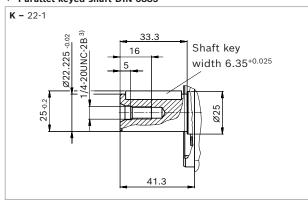
▼ Splined shaft 3/4 in (19-4, ISO 3019-1)



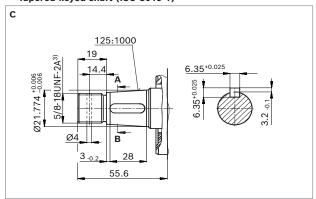
▼ Splined shaft 3/4 in (similar to ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



▼ Tapered keyed shaft (ISO 3019-1)



- Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.
- 3) Thread according to ASME B1.1



Dimensions [mm (inch)]

Axial piston variable pump | A10VO series 52 and 53

Dimensions, size 28

Port pla	ate 11, 12	Standard	Size	$p_{\sf max}$ [bar (psi)] $^{1)}$	State ⁵⁾	
В	Working port (standard pressure series) Fastening thread					
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	1 1/4 in M10 × 1.5; 17 (0.67) deep	5 (75)	0	
Port plate 61, 62		Standard	Standard Size		State ⁵⁾	
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	3/4 in 3/8-16UNC-2B 19 (0.75) deep	315 (4550)	0	
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	1 1/4 in 7/16-14UNC-2B; 24 (0.94) deep	5 (75)	0	
Port pla	ate 64	Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾	
В	Working port	ISO 11926	1 1/16 12 UN-2B; 20 (0.79) deep	315 (4550)	0	
S	Suction port	ISO 11926	1 5/8 12UN-2B; 17 (0.67) deep	5 (75)	0	
Other ports		Standard	Size	$p_{\sf max}$ [bar (psi)] $^{1)}$	State ⁵⁾	
L	Drain port	ISO 11926 ²⁾	3/4-16UNF-2B; 12 (0.47) deep	2 (30)	O ³⁾	
$L_1, \ L_2^{4)}$	Drain port	ISO 11926 ²⁾	3/4-16UNF-2B; 12 (0.47) deep	2 (30)	X ³⁾	
х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 (0.45) deep	315 (4550)	0	

Depending on the application, momentary pressure peaks can occur.

Keep this in mind when selecting measuring devices and fittings.

 $_{\rm 2)}\,$ The countersink may be deeper than specified in the standard.

³⁾ Depending on the installation position, \mathbf{L} , \mathbf{L}_1 or \mathbf{L}_2 must be connected (also see installation instructions starting on page 80).

⁴⁾ Only for series 53

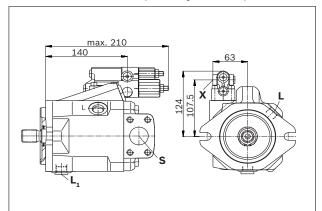
⁵⁾ O = Must be connected (plugged on delivery)

X = Plugged (in normal operation)

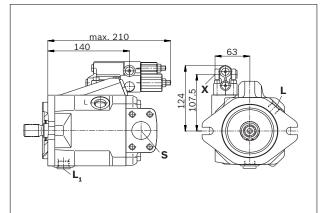


Dimensions [mm]

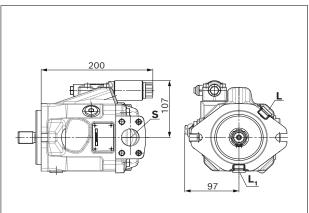
▼ DRG - Pressure controller, remotely controlled, series 52



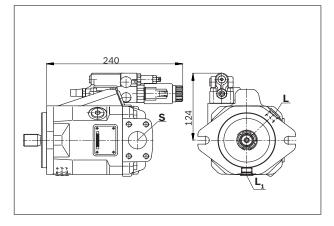
▼ DFR/DFR1 - Pressure and flow controller, series 52



▼ EC4 - Electro-hydraulic control valve, series 52



▼ ED7. / ER7. - Electro-proportional pressure control, series 52

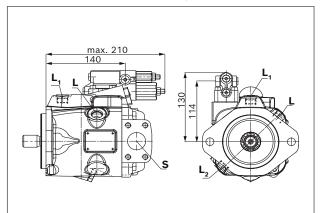




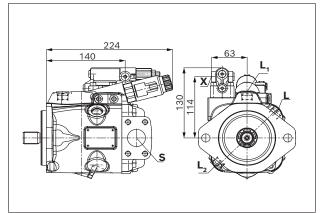
Axial piston variable pump | A10VO series 52 and 53 4

Dimensions, size 28

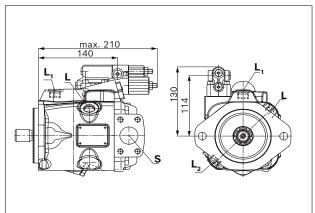
▼ DRG - Pressure controller, remotely controlled, series 53



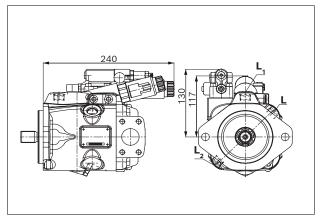
▼ EP.D. / EK.D. - Electro-proportional control, series 53



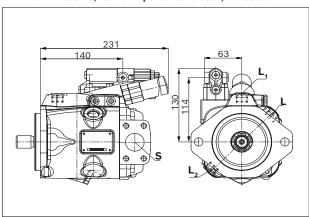
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



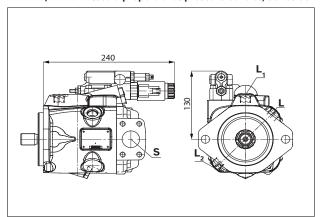
▼ EP.ED. / EK.ED. - Electro-proportional control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-proportional pressure control, series 53

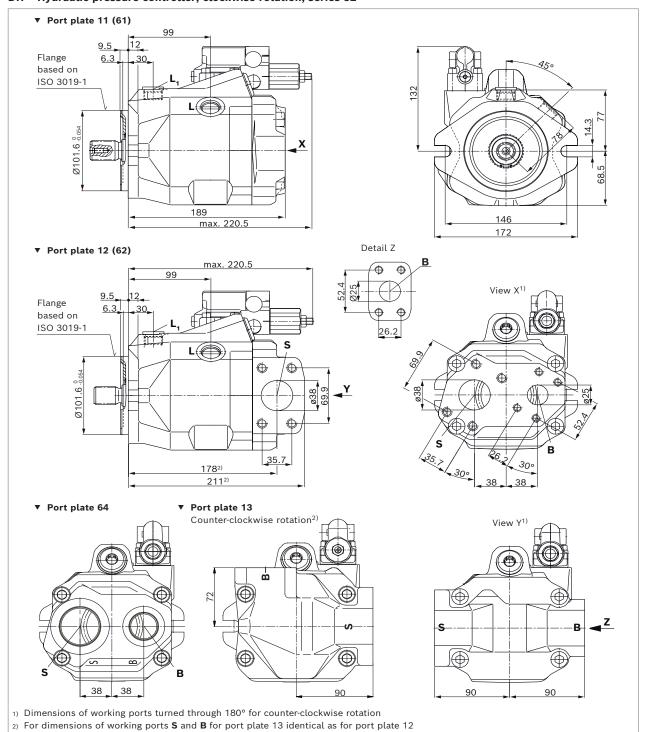




Dimensions [mm]

Dimensions, size 45

DR - Hydraulic pressure controller; clockwise rotation, series 52

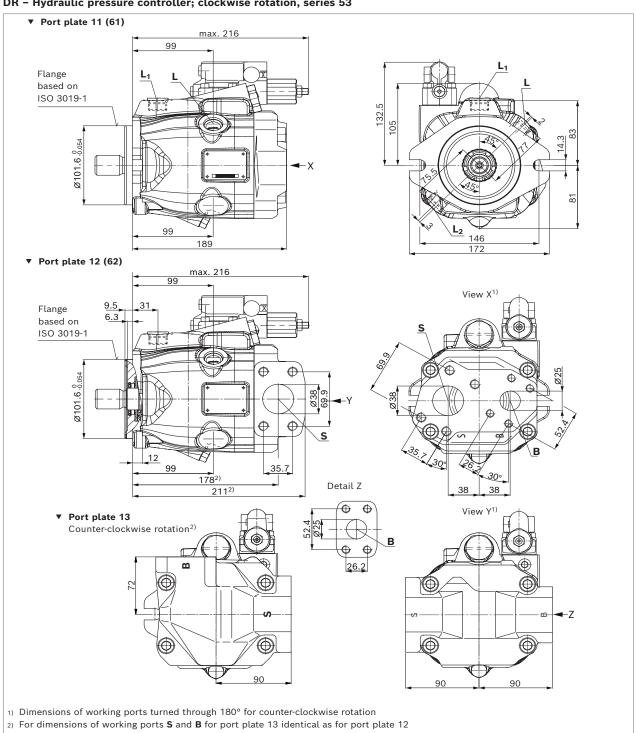




Axial piston variable pump | A10VO series 52 and 53 Dimensions, size 45

Dimensions, size 45

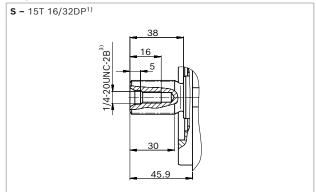
DR - Hydraulic pressure controller; clockwise rotation, series 53



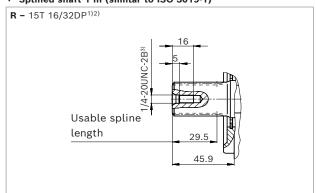


Dimensions [mm]

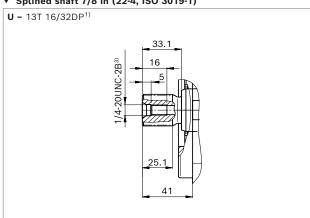
▼ Splined shaft 1 in (25-4, ISO 3019-1)



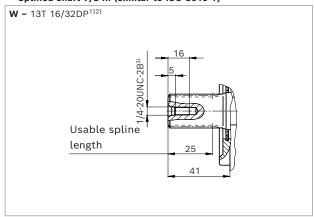
▼ Splined shaft 1 in (similar to ISO 3019-1)



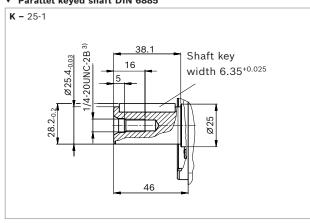
▼ Splined shaft 7/8 in (22-4, ISO 3019-1)



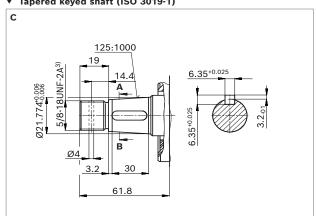
▼ Splined shaft 7/8 in (similar to ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



▼ Tapered keyed shaft (ISO 3019-1)



- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.
- 3) Thread according to ASME B1.1



Dimensions [mm (inch)]

Axial piston variable pump | A10VO series 52 and 53 45

Dimensions, size 45

Port pla	ate 11, 12, 13	Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	1 in M10 × 1.5; 17 (0.67) deep	315 (4550)	0
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	1 1/2 in M12 × 1.75; 20 (0.79) deep	5 (75)	0
Port pla	ate 61, 62	Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	1 in 3/8-16UNC-2B 18 (0.71) deep	315 (4550)	0
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	1 1/2 in 1/2-13UNC-2B; 22 (0.87) deep	5 (75)	0
Port plate 64		Standard	Size	<i>p</i> _{max} [bar (psi)] ¹⁾	State ⁵⁾
В	Working port	ISO 11926	1 5/16 12UN-2B; 20 (0.79) deep	315 (4550)	0
S	Suction port	ISO 11926	1 7/8 12UN-2B; 20 (0.79) deep	5 (75)	0
Other p	orts	Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾
L	Drain port	ISO 11926 ²⁾	7/8-14UNF-2B; 13 (0.51) deep	2 (30)	O ³⁾
L ₁ , L ₂ ⁴⁾	Drain port	ISO 11926 ²⁾	7/8-14UNF-2B; 13 (0.51) deep	2 (30)	X ³⁾
Х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11,5 (0.45) deep	315 (4550)	0

¹⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

 $_{\rm 2)}\,$ The countersink may be deeper than specified in the standard.

 $_{\rm 3)}$ Depending on the installation position, $\boldsymbol{L},\,\boldsymbol{L}_{1}$ or \boldsymbol{L}_{2} must be connected (also see installation instructions starting on page 80).

⁴⁾ Only for series 53

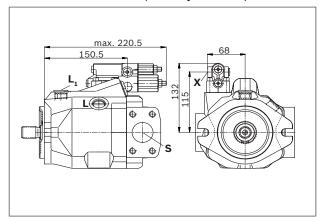
⁵⁾ O = Must be connected (plugged on delivery)

X = Plugged (in normal operation)

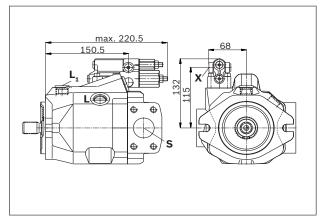


Dimensions [mm]

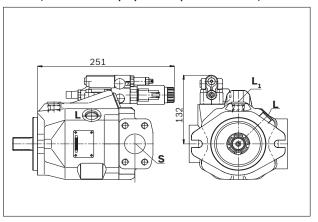
▼ DRG - Pressure controller, remotely controlled, series 52



▼ DFR/DFR1/DRSC - Pressure and flow controller series 52



▼ ED7. / ER7. - Electro-proportional pressure control, series 52

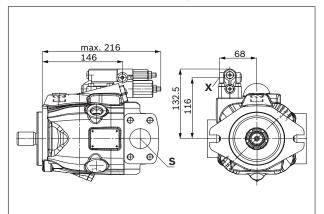




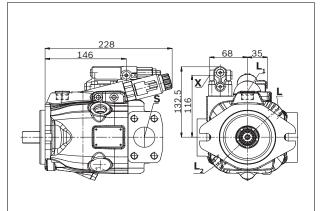
Axial piston variable pump | A10VO series 52 and 53 47

Dimensions, size 45

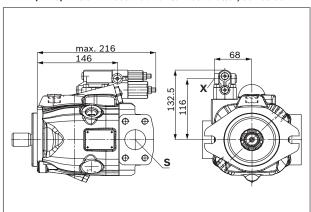
▼ DRG - Pressure controller, remotely controlled, series 53



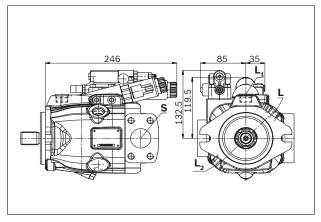
▼ EP.D. / EK.D. - Electro-proportional control, series 53



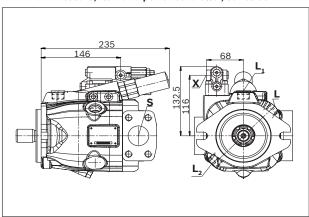
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



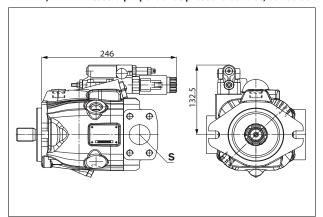
▼ EP.ED. / EK.ED. - Electro-proportional control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-proportional pressure control, series 53

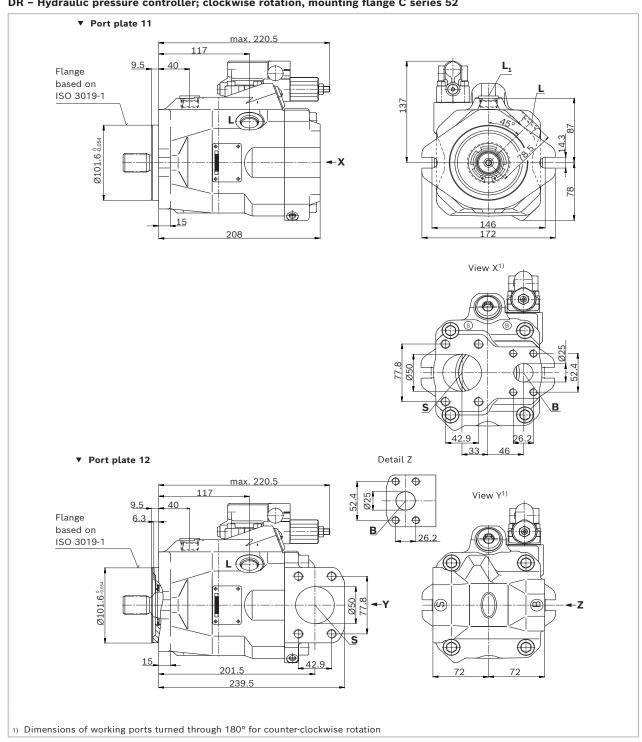




Dimensions [mm]

Dimensions, size 60

DR - Hydraulic pressure controller; clockwise rotation, mounting flange C series 52

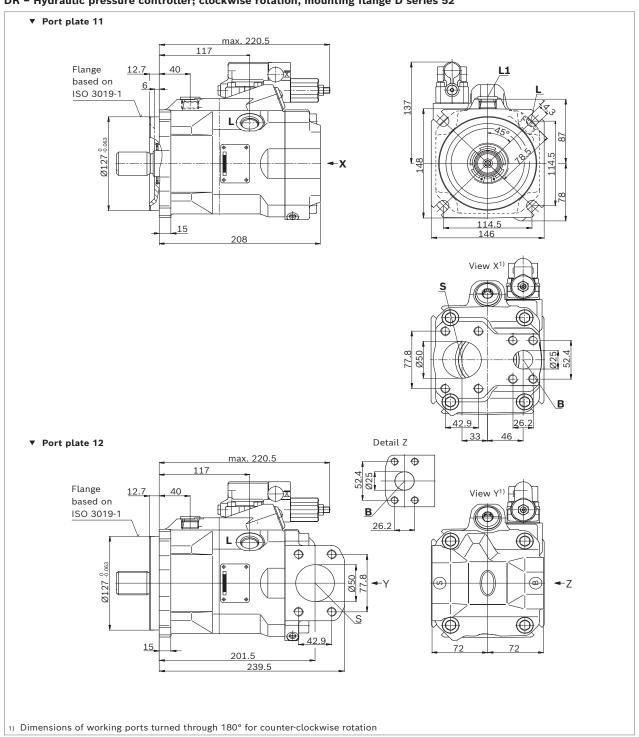




Axial piston variable pump | **A10VO series 52 and 53**Dimensions, size 60

Dimensions, size 60

DR - Hydraulic pressure controller; clockwise rotation, mounting flange D series 52

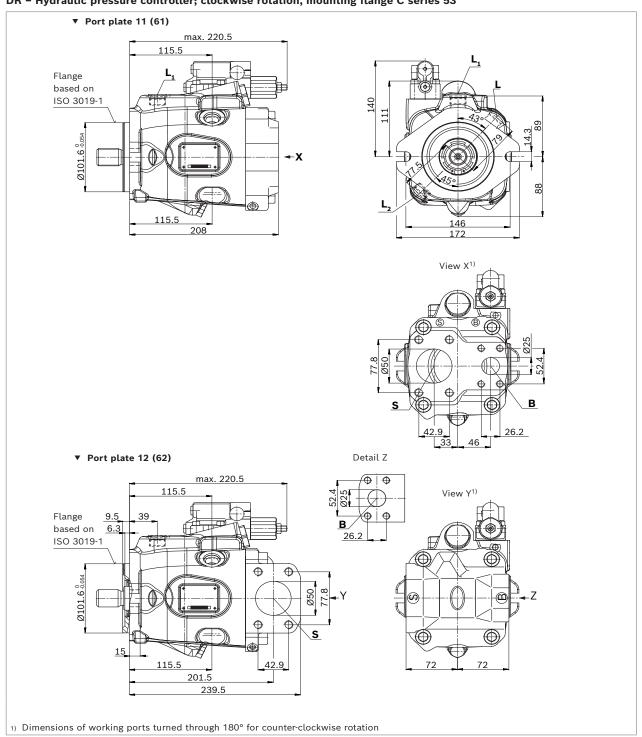




Dimensions [mm]

Dimensions, size 63

DR - Hydraulic pressure controller; clockwise rotation, mounting flange C series 53

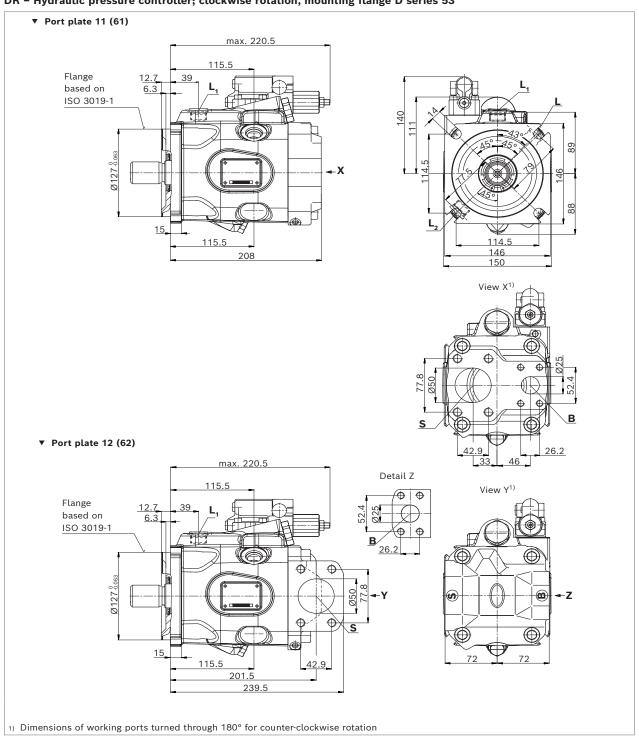




Axial piston variable pump | **A10VO series 52 and 53** 51 Dimensions, size 63

Dimensions, size 63

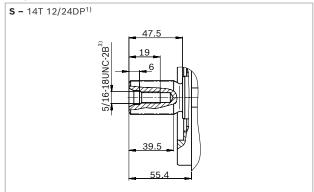
DR - Hydraulic pressure controller; clockwise rotation, mounting flange D series 53



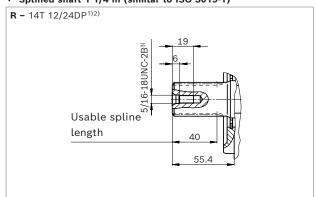


Dimensions [mm]

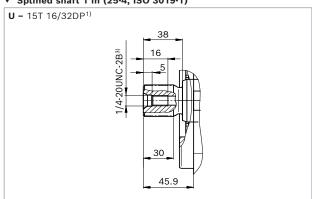
▼ Splined shaft 1 1/4 in (32-4, ISO 3019-1)



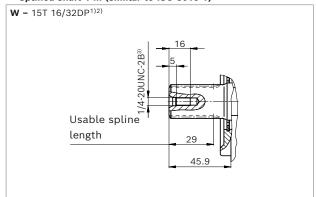
▼ Splined shaft 1 1/4 in (similar to ISO 3019-1)



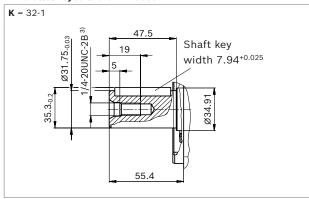
▼ Splined shaft 1 in (25-4, ISO 3019-1)



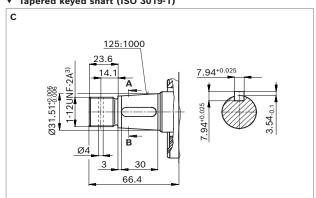
▼ Splined shaft 1 in (similar to ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



▼ Tapered keyed shaft (ISO 3019-1)



- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.
- 3) Thread according to ASME B1.1



Dimensions [mm (inch)]

Axial piston variable pump | **A10VO series 52 and 53**Dimensions, size 63

Port plat	e 11, 12	Standard	Standard Size		State ⁵⁾	
В	Working port (standard pressure series) Fastening thread					
s	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	2 in M12 × 1.75; 20 deep	5 (75)	0	
Port plate 61, 62		Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾	
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	1 in 3/8-16UNC-2B; 18 (0.71) deep	315 (4550)	0	
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	2 in 1/2-13UNC-2B; 22 (0.87) deep	5 (75)	0	
Other ports		Standard	Size	$p_{\rm max}$ [bar (psi)] $^{1)}$	State ⁵⁾	
L	Drain port	ISO 11926 ²⁾	7/8-14UNF-2B; 13 deep	2 (30)	O ³⁾	
$L_{1,} L_{2}^{4)}$	Drain port	ISO 11926 ²⁾	7/8-14UNF-2B; 13 deep	2 (30)	X ³⁾	
Х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 deep	315 (4550)	0	

Depending on the application, momentary pressure peaks can occur.
 Keep this in mind when selecting measuring devices and fittings.

²⁾ The countersink may be deeper than specified in the standard.

 $_{\rm 3)}$ Depending on the installation position, $L,\,L_{\rm 1}$ or $L_{\rm 2}$ must be connected (also see installation instructions starting on page 16).

⁴⁾ Only series 53

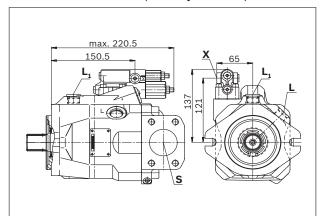
⁵⁾ O = Must be connected (plugged on delivery)

X = Plugged (in normal operation)

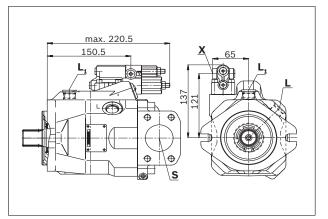


Dimensions [mm]

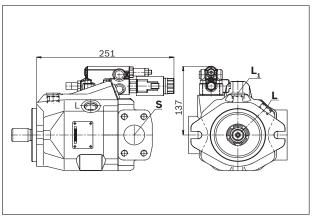
▼ DRG - Pressure controller, remotely controlled, series 52



▼ DFR/DFR1/DRSC - Pressure and flow controller series 52



▼ ED7. / ER7. - Electro-proportional pressure control, series 52

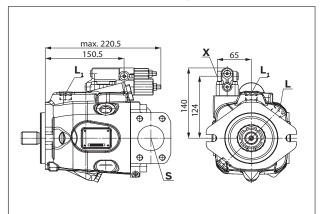




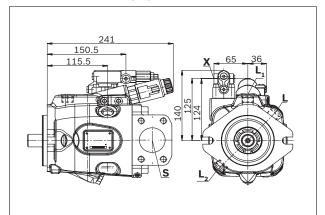
Axial piston variable pump | A10VO series 52 and 53

Dimensions, size 63

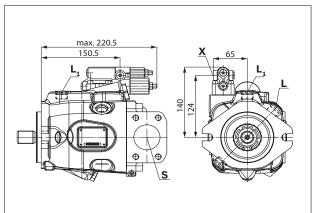
▼ DRG - Pressure controller, remotely controlled, series 53



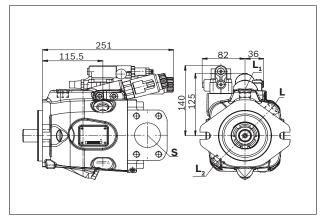
▼ EP.D. / EK.D. - Electro-proportional control, series 53



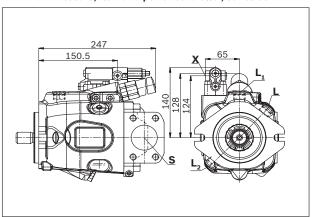
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



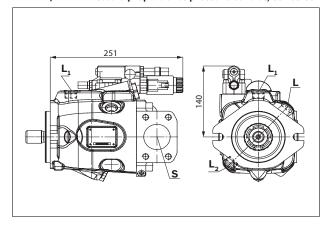
▼ EP.ED. / EK.ED. - Electro-proportional control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-proportional pressure control, series 53

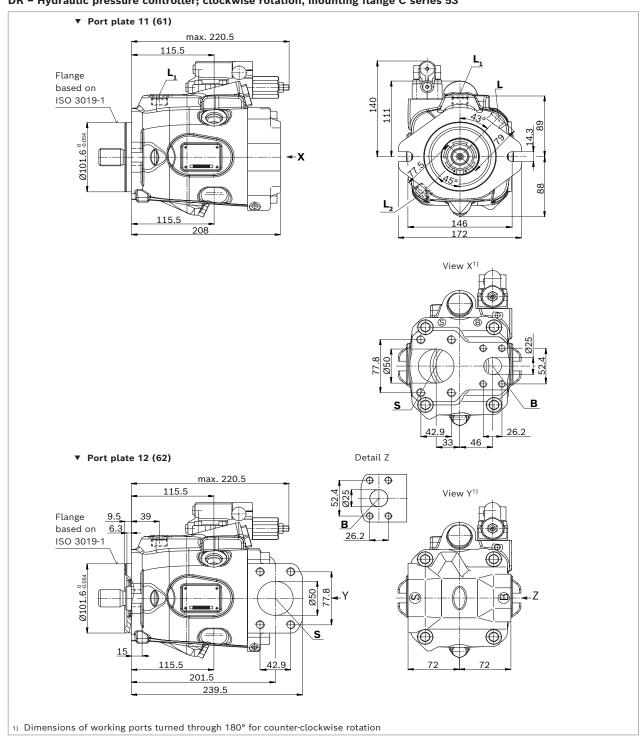




Dimensions [mm]

Dimensions, size 72

DR - Hydraulic pressure controller; clockwise rotation, mounting flange C series 53



57

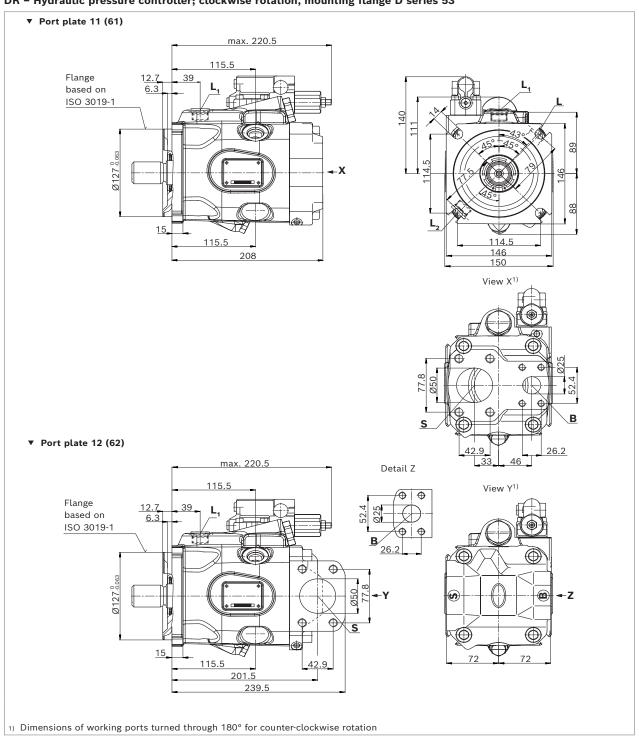


Dimensions [mm]

Axial piston variable pump | **A10VO series 52 and 53**Dimensions, size 72

Dimensions, size 72

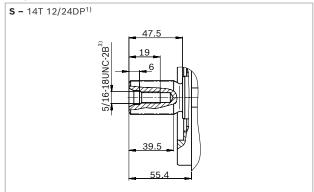
DR - Hydraulic pressure controller; clockwise rotation, mounting flange D series 53



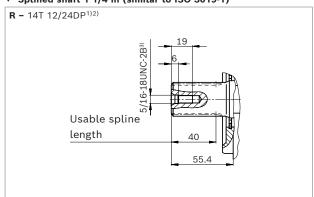


Dimensions [mm]

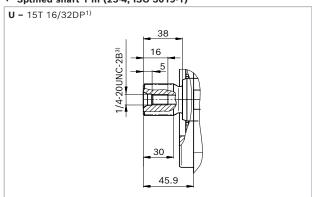
▼ Splined shaft 1 1/4 in (32-4, ISO 3019-1)



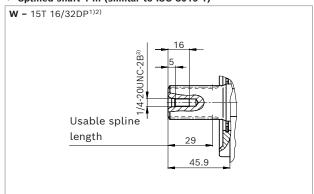
▼ Splined shaft 1 1/4 in (similar to ISO 3019-1)



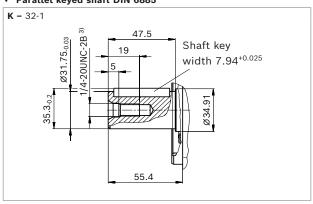
▼ Splined shaft 1 in (25-4, ISO 3019-1)



▼ Splined shaft 1 in (similar to ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.
- 3) Thread according to ASME B1.1



Dimensions [mm (inch)]

Axial piston variable pump | **A10VO series 52 and 53** 59

Dimensions, size 72

Port plat	te 11, 12	Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾	
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	1 in M10 × 1.5; 17 (0.67) deep	315 (4550)	0	
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	2 in M12 × 1.75; 20 (0.79) deep	5 (75)	0	
Port plate 61, 62		Standard	Size	$p_{\sf max}$ [bar (psi)] $^{1)}$	State ⁵⁾	
В	Working port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	1 in 3/8-16UNC-2B; 18 (0.71) deep	315 (4550)	0	
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	2 in 1/2-13UNC-2B; 22 (0.87) deep	5 (75)	0	
Other ports		Standard	Size	$p_{\sf max}$ [bar (psi)] $^{1)}$	State ⁵⁾	
L	Drain port	ISO 11926 ²⁾	7/8-14UNF-2B; 13 (0.51) deep	2 (30)	O ³⁾	
L _{1,} L ₂ ⁴⁾	Drain port	ISO 11926 ²⁾	7/8-14UNF-2B; 13 (0.51) deep	2 (30)	X ³⁾	
Х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 (0.45) deep	315 (4550)	0	

Depending on the application, momentary pressure peaks can occur.
 Keep this in mind when selecting measuring devices and fittings.

 $_{\rm 2)}\,$ The countersink may be deeper than specified in the standard.

 $_{\rm 3)}$ Depending on the installation position, $L,\,L_{\rm 1}$ or $L_{\rm 2}$ must be connected (also see installation instructions starting on page 16).

⁴⁾ Only series 53

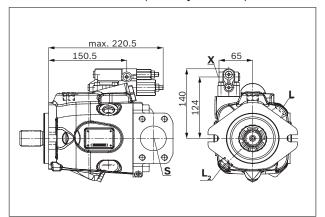
⁵⁾ O = Must be connected (plugged on delivery)

X = Plugged (in normal operation)

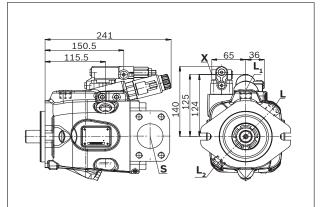


Dimensions [mm]

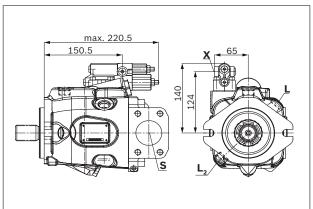
▼ DRG - Pressure controller, remotely controlled, series 53



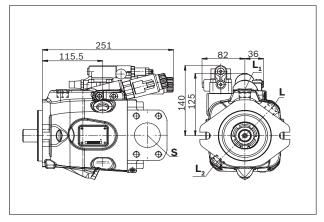
▼ EP.D. / EK.D. - Electro-proportional control, series 53



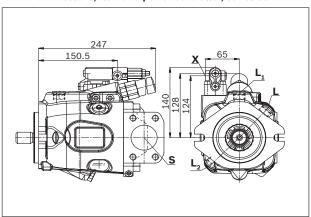
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



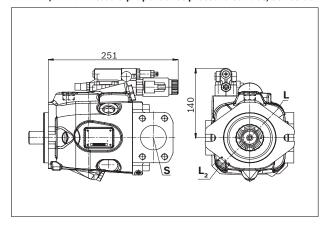
▼ EP.ED. / EK.ED. - Electro-proportional control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-proportional pressure control, series 53

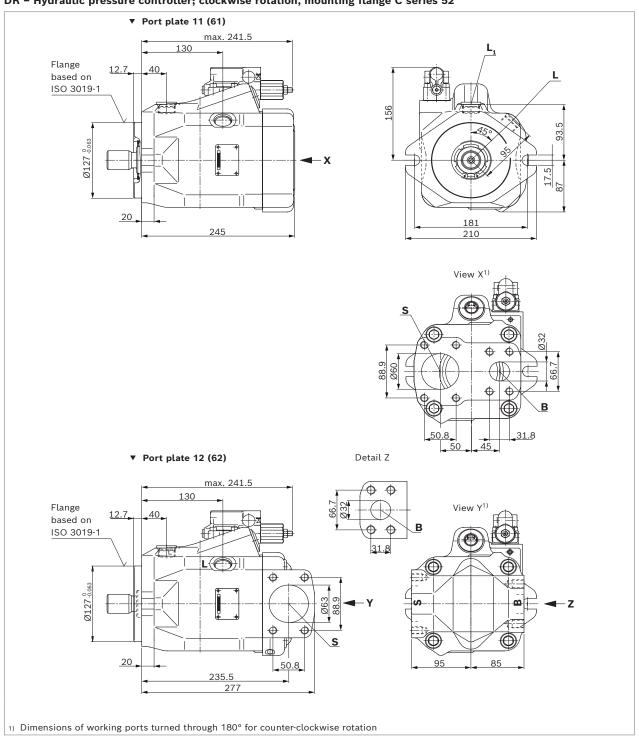




Axial piston variable pump | **A10VO series 52 and 53** 61 Dimensions, size 85

Dimensions, size 85

DR - Hydraulic pressure controller; clockwise rotation, mounting flange C series 52

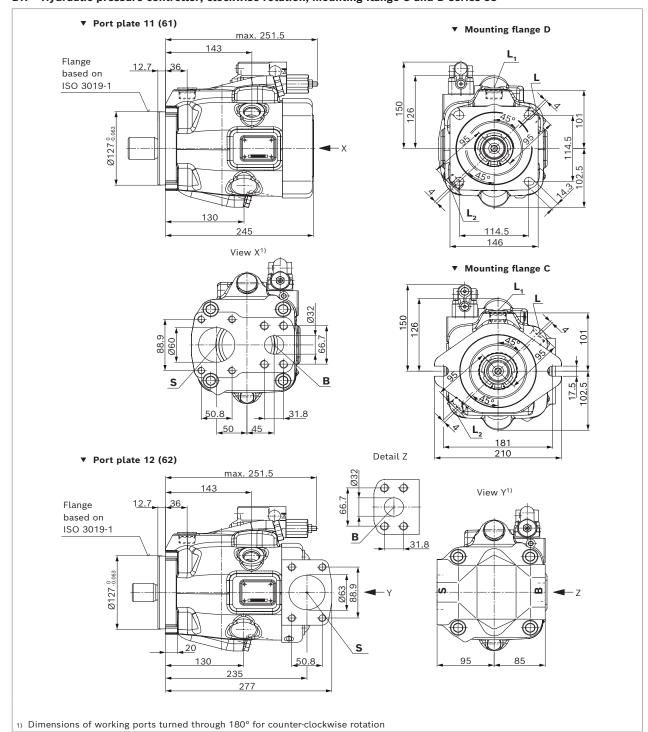




Dimensions [mm]

Dimensions, size 85

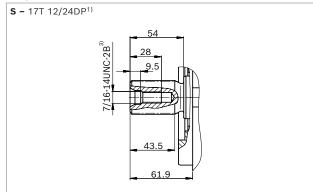
DR - Hydraulic pressure controller; clockwise rotation, mounting flange C and D series 53



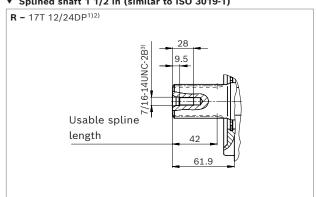


Axial piston variable pump | A10VO series 52 and 53 63 Dimensions, size 85

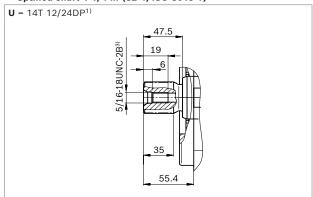
▼ Splined shaft 1 1/2 in (38-4, ISO 3019-1)



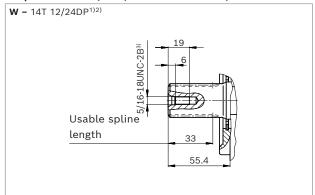
▼ Splined shaft 1 1/2 in (similar to ISO 3019-1)



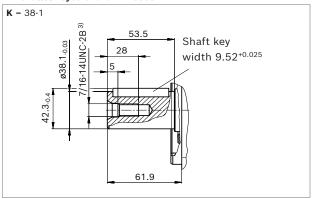
▼ Splined shaft 1 1/4 in (32-4, ISO 3019-1)



▼ Splined shaft 1 1/4 in (similar to ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



- 1) Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.
- 3) Thread according to ASME B1.1



Dimensions [mm (inch)]

Port plat	te 11, 12	Standard	Standard Size		State ⁵⁾		
В	Working port (high-pressure series) Fastening thread						
s	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	2 1/2 in M12 × 1.75; 17 (0.67) deep	5 (75)	0		
Port plate 61, 62		Standard	Size	p_{max} [bar (psi)] ¹⁾	State ⁵⁾		
В	Working port (high-pressure series) Fastening thread	ISO 6162-2 ASME B1.1	1 1/4 in 1/2-13UNC-2B; 19 (0.75) deep	315 (4550)	0		
s	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	2 1/2 in 1/2-13UNC-2B; 27 (1.06) deep	5 (75)	0		
Other ports		Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾		
L	Drain port	ISO 11926 ²⁾	1 1/16-12UNF-2B; 15 (0.59) deep	2 (30)	O ³⁾		
$L_{1,} L_{2}^{4)}$	Drain port	ISO 11926 ²⁾	1 1/16-12UNF-2B; 15 (0.59) deep	2 (30)	X ³⁾		
х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 (0.45) deep	315 (4550)	0		

¹⁾ Depending on the application, momentary pressure peaks can occur. Keep this in mind when selecting measuring devices and fittings.

²⁾ The countersink may be deeper than specified in the standard.

 $_{\rm 3)}$ Depending on the installation position, $L,\,L_{\rm 1}$ or $L_{\rm 2}$ must be connected (also see installation instructions starting on page 80).

⁴⁾ Only series 53

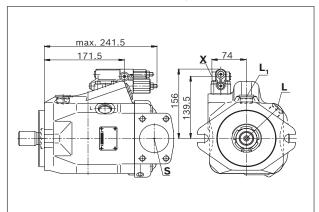
⁵⁾ O = Must be connected (plugged on delivery)

X = Plugged (in normal operation)

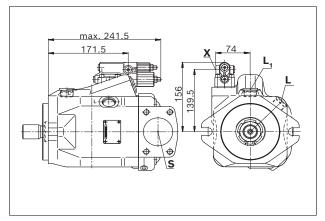


Axial piston variable pump | **A10VO series 52 and 53** Dimensions, size 85

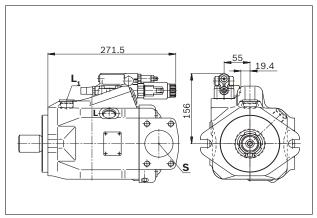
▼ DRG - Pressure controller, remotely controlled, series 52



▼ DFR/DFR1/DRSC - Pressure and flow controller series 52



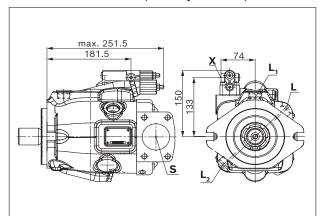
▼ ED7. / ER7. - Electro-prop. pressure control, series 52



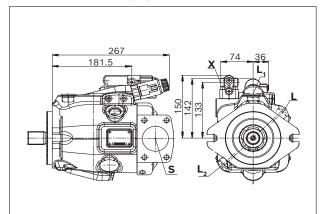


Dimensions [mm]

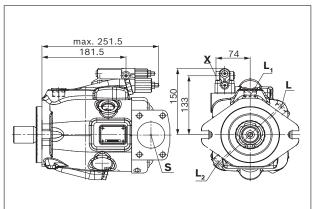
▼ DRG - Pressure controller, remotely controlled, series 53



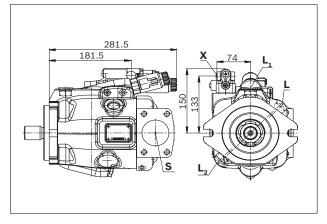
▼ EP.D. / EK.D. - Electro-proportional control, series 53



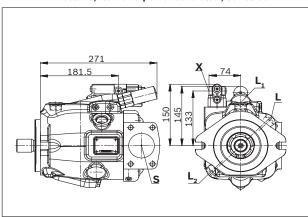
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



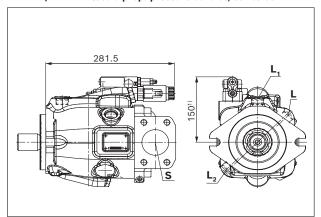
▼ EP.ED. / EK.ED. - Electro-prop. control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-prop. pressure control, series 53

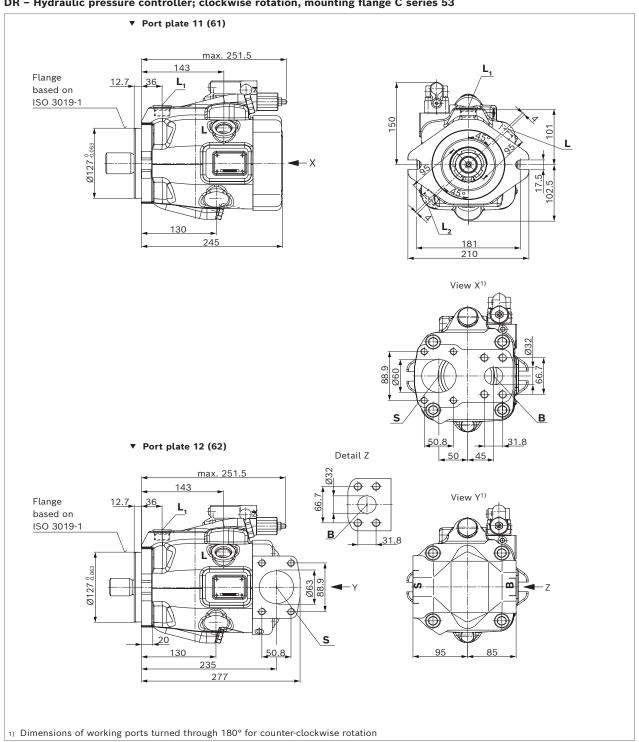




Axial piston variable pump | A10VO series 52 and 53 Dimensions, size 100

Dimensions, size 100

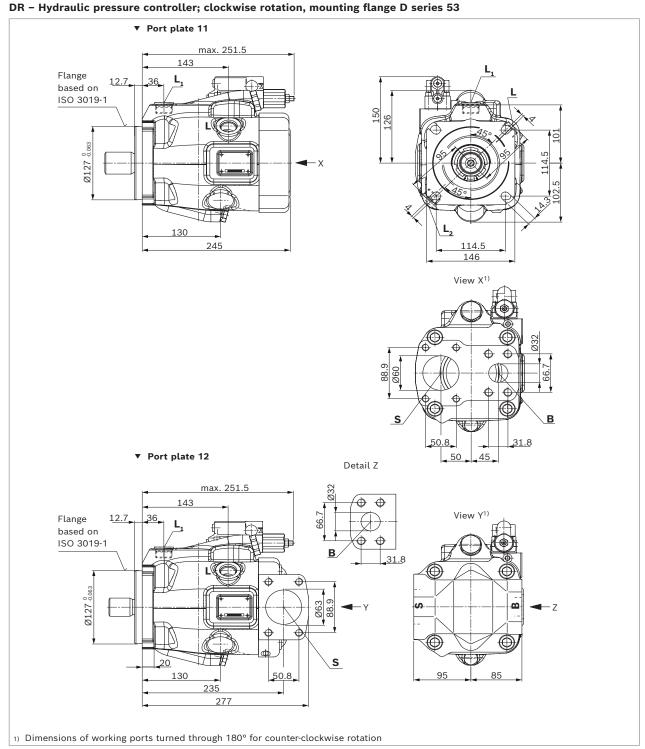
DR - Hydraulic pressure controller; clockwise rotation, mounting flange C series 53





Dimensions [mm]

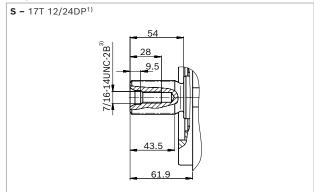
Dimensions, size 100



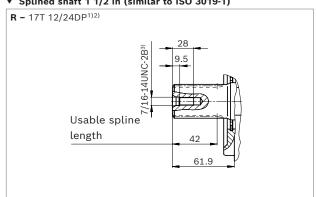


Axial piston variable pump | A10VO series 52 and 53 Dimensions, size 100

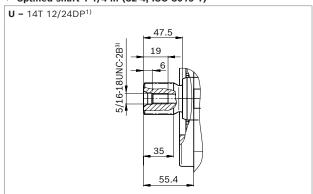
▼ Splined shaft 1 1/2 in (38-4, ISO 3019-1)



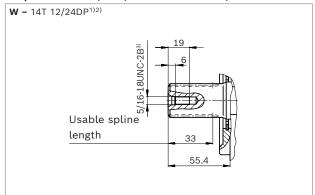
▼ Splined shaft 1 1/2 in (similar to ISO 3019-1)



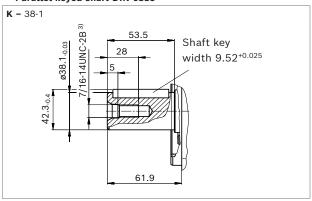
▼ Splined shaft 1 1/4 in (32-4, ISO 3019-1)



▼ Splined shaft 1 1/4 in (similar to ISO 3019-1)



▼ Parallel keyed shaft DIN 6885



¹⁾ Involute spline according to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Splines according to ANSI B92.1a, spline runout is a deviation from standard ISO 3019-1.

³⁾ Thread according to ASME B1.1



Dimensions [mm (inch)]

Port plat	te 11, 12	Standard	Size	p_{max} [bar (psi)] $^{1)}$	State ⁵⁾	
В	Working port (high-pressure series) Fastening thread	ISO 6162-2 DIN 13	1 1/4 in M14 × 2; 19 (0.75) deep	315 (4550)	0	
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 DIN 13	2 1/2 in M12 × 1.75; 17 (0.67) deep	5 (75)	0	
Port plate 61, 62		Standard	Size	p_{max} [bar (psi)] ¹⁾	State ⁵⁾	
В	Working port (high-pressure series) Fastening thread	ISO 6162-2 ASME B1.1	1 1/4 in 1/2-13UNC-2B; 19 (0.75) deep	315 (4550)	0	
S	Suction port (standard pressure series) Fastening thread	ISO 6162-1 ASME B1.1	2 1/2 in 1/2-13UNC-2B; 27 (1.06) deep	5 (75)	0	
Other ports		Standard	Size	p_{max} [bar (psi)] ¹⁾	State ⁵⁾	
L	Drain port	ISO 11926 ²⁾	1 1/16-12UNF-2B; 15 (0.59) deep	2 (30)	O ³⁾	
$L_{1,} L_{2}^{4)}$	Drain port	ISO 11926 ²⁾	1 1/16-12UNF-2B; 15 (0.59) deep	2 (30)	X ³⁾	
Х	Pilot pressure	ISO 11926	7/16-20UNF-2B; 11.5 (0.45) deep	315 (4550)	0	

Depending on the application, momentary pressure peaks can occur.
 Keep this in mind when selecting measuring devices and fittings.

²⁾ The countersink may be deeper than specified in the standard.

 $_{\rm 3)}$ Depending on the installation position, $L,\,L_{\rm 1}$ or $L_{\rm 2}$ must be connected (also see installation instructions starting on page 80).

⁴⁾ Only series 53

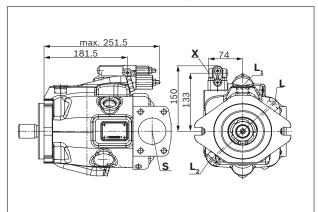
⁵⁾ O = Must be connected (plugged on delivery)

X = Plugged (in normal operation)

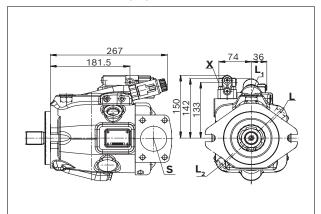


Axial piston variable pump | **A10VO series 52 and 53**Dimensions, size 100

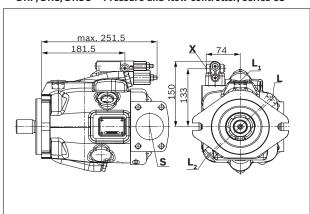
▼ DRG - Pressure controller, remotely controlled, series 53



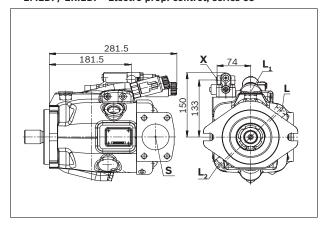
▼ EP.D. / EK.D. - Electro-proportional control, series 53



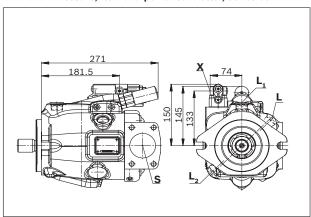
▼ DRF/DRS/DRSC - Pressure and flow controller, series 53



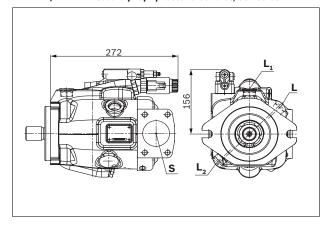
▼ EP.ED. / EK.ED. - Electro-prop. control, series 53



▼ LA.D. - Pressure, flow and power controller, series 53



▼ ED7. / ER7. - Electro-prop. pressure control, series 53





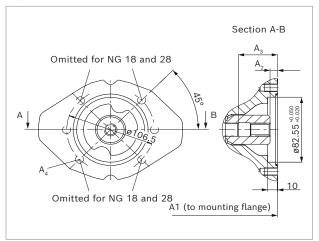
Dimensions [mm (inch)]

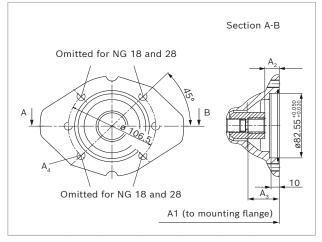
Dimensions, through drive

Flange ISO 3019-1 (SAE)		Hub for	Hub for splined shaft ¹⁾		Availability across sizes						Code
Diameter	Mounting ²⁾	Diamete	r	18	28	45	60/63	72	85	100	
82-2 (A)	σ⁰, ⊶	5/8 in	9T 16/32DP	•	•	•	•	•	•	•	K01
		3/4 in	11T 16/32DP	•	•	•	•	•	•	•	K52

• = Available • = On request - = Not available

▼ 82-2





K01 (SAE J744 16-4 (A))	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
	18	182	9.3	42.5	M10 × 1.5;
		(7.17)	(0.37)	(1.67)	14.5 (0.57) deep
	28	204	9.2	36.2	M10 × 1.5;
		(8.03)	(0.36)	(1.43)	16 (0.63) deep
	45	229	10	52.7	M10 × 1.5;
		(9.02)	(0.39)	(2.07)	16 (0.63) deep
	60/	255	8.7	58.2	M10 × 1.5;
	63	(10.04)	(0.34)	(2.29)	16 (0.63) deep
	72	255	8.7	58.2	M10 × 1.5;
		(10.04)	(0.34)	(2.29)	16 (0.63) deep
	85	302	12.5	67.2	M10 × 1.5;
		(11.89)	(0.49)	(2.65)	20 (0.79) deep
	100	302	12.5	67.2	M10 × 1.5;
		(11.89)	(0.49)	(2.65)	20 (0.79) deep

K52 (SAE J744 19-4 (A-B))	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
	18	182	18.3	39.3	M10 × 1.5;
		(7.17)	(0.71)	(1.54)	14.5 (0.57) deep
	28	204	18.4	39.4	M10 × 1.5;
		(8.03)	(0.72)	(1.55)	16 (0.63) deep
	45	229	18.4	38.8	M10 × 1.5;
		(9.02)	(0.72)	(1.53)	16 (0.63) deep
	60/	255	18.4	38.8	M10 × 1.5;
	63	(10.04)	(0.72)	(1.53)	16 (0.63) deep
	72	255	18.4	38.8	M10 × 1.5;
		(10.04)	(0.72)	(1.53)	16 (0.63) deep
	85	302	21.5	42.5	M10 × 1.5;
		(11.89)	(0.85)	(1.67)	20 (0.79) deep
	100	302	21.5	42.5	M10 × 1.5;
		(11.89)	(0.85)	(1.67)	20 (0.79) deep

According to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Mounting holes pattern viewed on through drive with control at top

³⁾ Thread according to DIN 13.

⁴⁾ Minimum dimensions



Dimensions [mm (inch)]

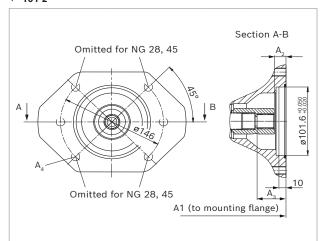
Axial piston variable pump | A10VO series 52 and 53 73

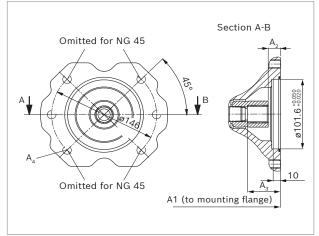
Dimensions, through drive

Flange ISO 3019-1 (SAE)		Hub for	Hub for splined shaft ¹⁾			Availability across sizes						
Diameter	Mounting ²⁾	Diamete	Diameter		28	45	60/63	72	85	100		
101-2 (B)	o°, ₀-₀	7/8 in	13T 16/32DP	-	•	•	•	•	•	•	K68	
		1 in	15T 16/32DP	-	-	•	•	•	•	•	K04	

Available o = On request - = Not available

▼ 101-2





K68	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
(SAE J744 22-4 (B))	Ita	Α.	72	AU	
	28	204	17.4	42.4	M12 × 1.75;
		(8.03)	(0.68)	(1.67)	18 (0.71) deep
	45	229	17.4	41.8	M12 × 1.75;
		(9.02)	(0.68)	(1.65)	18 (0.71) deep
	60/	255	17.4	41.8	M12 × 1.75;
	63	(10.04)	(0.68)	(1.65)	18 (0.71) deep
	72	255	17.4	41.8	M12 × 1.75;
		(10.04)	(0.68)	(1.65)	18 (0.71) deep
	85	302	20.5	44.8	M12 × 1.75;
		(11.89)	(0.81)	(1.76)	20 (0.79) deep
	100	302	20.5	44.8	M12 × 1.75;
		(11.89)	(0.81)	(1.76)	20 (0.79) deep

K04 (SAE J744 25-4 (B-B))	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
	45	229	17.9	47.4	M12 × 1.75;
		(9.02)	(0.70)	(1.87)	18 (0.71) deep
	60/	255	17.9	46.8	M12 × 1.75;
	63	(10.04)	(0.70)	(1.84)	18 (0.71) deep
	72	255	17.9	46.8	M12 × 1.75;
		(10.04)	(0.70)	(1.84)	18 (0.71) deep
	85	302	20.7	49.5	M12 × 1.75;
		(11.89)	(0.81)	(1.95)	20 (0.79) deep
	100	302	20.7	49.5	M12 × 1.75;
		(11.89)	(0.81)	(1.95)	20 (0.79) deep

¹⁾ According to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Mounting holes pattern viewed on through drive with control at top

³⁾ Thread according to DIN 13.

⁴⁾ Minimum dimensions



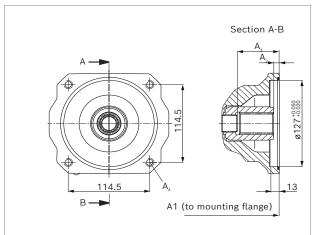
74 **A10VO series 52 and 53** | Axial piston variable pump Dimensions, through drive

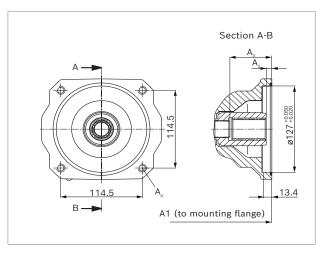
Dimensions [mm (inch)]

Flange ISO 3019-1 (SAE)		Hub for splined shaft ¹⁾	Availa	Code						
Diameter	$Mounting^{2)}$	Diameter	18	28	45	60/63	72	85	100	
127-4 (C)	XX	1 1/4 in 14T 12/24DP	-	-	-	•	•	•	•	K15
		1 1/2 in 17T 12/24DP	-	-	-	-	-	•	•	K16

• = Available • = On request - = Not available

▼ 127-4





K15 (SAE J744 32-4 (C))	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
	60/	255	17.9	55.9	M12 × 1.75;
	63	(10.04)	(0.70)	(0.20)	16 (0.63) deep
	72	255	17.9	55.9	M12 × 1.75;
		(10.04)	(0.70)	(0.20)	16 (0.63) deep
	85	301.5	22	60	M12 × 1.75;
		(11.87)	(0.87)	(2.36)	through
	100	301.5	22	60	M12 × 1.75;
		(11.87)	(0.87)	(2.36)	through

K16 (SAE J744	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
32-4 (C))					
	85	301.5	12.8	67.2	M12 × 1.75;
		(11.87)	(0.50)	(2.65)	through
	100	301.5	12.8	67.2	M12 × 1.75;
		(11.87)	(0.50)	(2.65)	through

According to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

Mounting holes pattern viewed on through drive with control at top

³⁾ Thread according to DIN 13.

⁴⁾ Minimum dimensions

K24



Dimensions [mm (inch)]

Flange ISO 3019-1 (SAE)

 $Mounting^{2)}$

ಿ, ⊶

Axial piston variable pump | A10VO series 52 and 53 75 Dimensions, through drive

Hub for splined shaft1) Availability across sizes Code 18 28 45 60/63 85 100 72 1 1/4 in 14T 12/24DP K07

= Available o = On request - = Not available

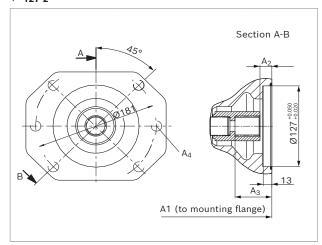
Diameter

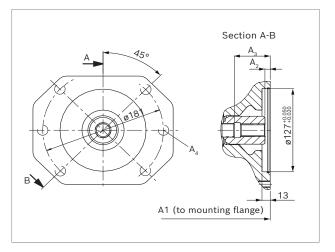
1 1/2 in 17T 12/24DP

▼ 127-2

Diameter

127-2 (B)





K07 (SAE J744 32-4 (C))	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
	85	301.5	22	60	M16×2;
		(11.87)	(0.87)	(2.36)	24 (0.94) deep
	100	301.5	22	60	M16×2;
		(11.87)	(0.87)	(2.36)	24 (0.94) deep

K24 (SAE J744 38-4 (C-C))	NG	A1	A2 ⁴⁾	A3 ⁴⁾	A4 ³⁾
	85	302	12.8	67.2	M16×2;
		(11.89)	(0.50)	(2.65)	24 (0.94) deep
	100	302	12.8	67.2	M16×2;
		(11.89)	(0.50)	(2.65)	24 (0.94) deep

¹⁾ According to ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5

²⁾ Mounting holes pattern viewed on through drive with control at top

³⁾ Thread according to DIN 13.

⁴⁾ Minimum dimensions



76 **A10VO series 52 and 53** | Axial piston variable pump Overview of mounting options

Overview of mounting options

Through dri	ve		Mounting options - 2nd pump								
Flange ISO 3019-1	Hub for splined shaft	Code	A10VO/5x NG (shaft)	A10VO/60 NG (shaft)	A10VSO/31 NG (shaft)	A1VO/10 NG (shaft)	External gear pump				
82-2 (A)	5/8 in	K01	10 (U), 18 (U)	_	18 (U)	18, 28 (S2)	AZPF				
	3/4 in	K52	10 (S), 18 (S, R)	_	18 (S, R)	18, 28 (S3)					
101-2 (B)	7/8 in	K68	28 (S, R) 45 (U, W) ¹⁾	45 (S4)	28 (S, R) 45 (U, W)	35 (S4)	AZPN/AZPG				
	1 in	K04	45 (S, R) 60, 63 (U, W) ²⁾ 72 (U, W) ²⁾	45 (S5)	45 (S, R)	35 (S5)	-				
127-4 (C)	1 1/4 in	K15	60, 63 (S, R) 72 (S, R)	-	-	-	-				
	1 1/2 in	K16	85 (S) 100 (S)	-	-	-	-				
127-2 (C)	1 1/4 in	K07	85 (U) 100 (U)	-	71 (S, R)	-	PGH5				
	1 1/2 in	K24	85 (S) 100 (S)	-	-	-	-				

¹⁾ Not for NG28 with K68

²⁾ Not for NG45 with K04



Axial piston variable pump | **A10VO series 52 and 53** Combination pumps A10VO + A10VO

Combination pumps A10VO + A10VO

By using combination pumps, it is possible to have independent circuits without the need for splitter gearboxes. When ordering combination pumps the type designations for the first and the second pump must be joined by a "+" and are combined into one part number. Each single pump should be ordered according to type code.

Notice

- ► The combination pump type code is shown in shortened form in the order confirmation.
- Each through drive is plugged with a non-pressureresistant cover. This means the units must be sealed with a pressure-resistant cover before commissioning.

Order example:

A10VO85DRS/53R-VSC12K04+ A10VO45DRF/53R-VSC11N00

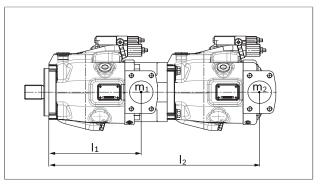
A tandem pump, with two pumps of equal size, is permissible without additional supports, assuming that the dynamic mass acceleration does not exceed maximum 10 g (= 98.1 m/s^2).

For combination pumps consisting of more than two pumps, the mounting flange must be rated for the permissible mass torque (please contact us).

Notice

Through drives with installed hub are supplied with a spacer.

The spacer must be removed before installation of the 2nd pump and before commissioning. For further information, see instruction manual 92703-01-B



m_1, m_2, m_3	Weight of pump	[kg (lbs)]
l_1, l_2, l_3	Distance from center of gravity	[mm (inch)]
$M_m = (m_1 \times l_1)$	$+ m_2 \times l_2 + m_3 \times l_3) \times \frac{1}{102 (12)}$	- [Nm (lb-ft)]

Permissible moments of inertia

NG			10	18	28	45	60/63	72	85	100
Static	M_m	Nm	_	500	890	900	1370	1370	3080	3080
		lb-ft	-	369	656	664	101	101	2270	2270
Dynamic at 10 g (98.1 m/s ²)	M_m	Nm	_	50	89	90	137	137	308	308
		lb-ft	-	37	65	66	101	101	227	227
Weight without through-drive plate		kg	8	11.5	15	18	22	22	36	36
(e.g. 2nd pump)		lb-ft	18	25	33	40	49	49	79	79
Weight with through-drive plate	m	kg	-	13	18	24	28	28	45	45
		lb-ft	-	29	40	53	62	62	99	99
Distance, center of gravity without through drive	l_1	mm	_	78	85	96	105	105	122	122
		inch	-	3.07	3.35	3.78	4.13	4.13	4.80	4.80
Distance, center of gravity with through drive	l_1	mm	_	87	99	115	127	127	150	150
		inch	_	3.43	3.90	4.53	5.00	5.00	5.90	5.90



78 **A10VO series 52 and 53** | Axial piston variable pump Connector for solenoids

Connector for solenoids

DEUTSCH DT04-2P

Molded, 2-pin, without bidirectional suppressor diode. There is the following type of protection with the mounted mating connector:

- ▶ IP67 (DIN/EN 60529) and
- ► IP69K (DIN 40050-9)

▼ Switching symbol



▼ Mating connector DEUTSCH DT06-2S-EP04

Consisting of	DT designation
1 housing	DT06-2S-EP04
1 wedge	W2S
2 sockets	0462-201-16141

The mating connector is not included in the scope of delivery. This can be supplied by Bosch Rexroth on request (material number R902601804).

Notice

If necessary, you can change the position of the connector by turning the solenoid body.

The procedure is defined in instruction manual 92703-01-B.

79



Axial piston variable pump | **A10VO series 52 and 53**Swivel angle sensor

Swivel angle sensor

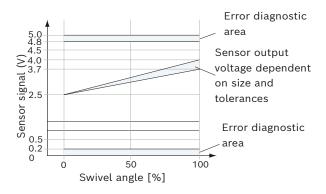
Description

The swivel angle sensor serves the contactless detection of the swivel angle of axial piston units in the swivel axis using a Hall-effect based sensor IC with a supply voltage of 5 V. The measured value determined is converted into an analog signal corresponding to the output characteristic curve shown below.

Features

- ► Contactless angle sensor for contactless detection of the swivel angle of axial piston units in the pivot axis using the Hall effect. The determined angle value is output as an analog voltage signal
- ▶ High temperature stability of the output signal
- ▶ Shock and vibration resistance
- ► Type of protection (with plugged mating connector and cable) IPx9k, IP6kx, IPx6 and IPx7 (ISO 20653)

▼ Output characteristic curve for A10VO series 5x



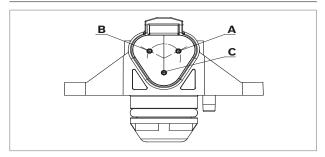
Туре	SWS25
Supply voltage U_{B}	4.75 to 5.25 V DC
Nominal voltage	5 V DC
Current consumption without load	Normal operation ≤20 mA
Output signal	0.5 V to 4.5 V, ratiometric
Load resistance	Minimum 5 kΩ
Operation and storage temperature	-40 °C to +110 °C
Supply overvoltage resistance	16 V DC
Type of protection (with plugged mating connector and cable)	IPx9k, IP6kx, IPx6 and IPx7 (ISO 20653)

Notice

- Information on environmental and EMC conditions upon request.
- Further information such as type codes, technical data, dimensions and safety instructions for the swivel angle sensor can be found in the associated data sheet 95153.
- Painting the sensor with electrostatic charge is not permitted (danger: ESD damage).

▼ Pin assignment

PIN	Port
В	Supply voltage Ub
A	Ground GND
С	Sensor signal OUT



Electrostatic discharge (ESD)

According to ISO 10605:2008

- Contact discharge (probe touches the sensor) ±8 kV (sensor operated actively and passively)
- Air discharge (arc between probe and sensor) ±15 kV (sensor operated actively and passively)

▼ Mating connector DEUTSCH DT06-3S

Consisting of	DT designation
1 housing, 3-pin	DT06-3S-EP04
1 wedge	W3S
3 sockets	0462-201-16141

The mating connector is not included in the scope of delivery. This can be supplied by Bosch Rexroth on request.



80 **A10VO series 52 and 53** | Axial piston variable pump Installation instructions

Installation instructions

General

The axial piston unit must be filled with hydraulic fluid and air bled during commissioning and operation. This must also be observed following a longer standstill as the axial piston unit may empty via the hydraulic lines. Particularly with the "drive shaft up/down" installation position, filling and air bleeding must be carried out completely as there is, for example, a danger of dry running. The leakage in the housing area must be directed to the reservoir via the highest positioned drain port (L, L_1, L_2) . If a shared drain line is used for several units, make sure that the respective case pressure in each unit is not exceeded. The shared drain line must be dimensioned to ensure that the maximum permissible case pressure of all connected units is not exceeded in any operating condition, particularly at cold start. If this is not possible, separate drain line must be laid, if necessary. To prevent the transmission of structure-borne noise, use elastic elements to decouple all connecting lines from all vibration-capable components (e.g., reservoir, frame parts).

Under all operating conditions, the suction lines and the drain lines must flow into the reservoir below the minimum fluid level. The permissible suction height $h_{\text{\scriptsize S}}$ results from the total pressure loss. However, it must not be higher than $h_{S max}$ = 800 mm (31.5 inch). The minimum suction pressure at port **S** must not fall below 0.8 bar (12 psi) absolute during operation and during cold start. When designing the reservoir, ensure that there is adequate distance between the suction line and the drain line. We recommend using a baffle (baffle plate) between suction line and drain line. A baffle improves the air separation ability as it gives the hydraulic fluid more time for desorption. Apart from that, this prevents the heated return flow from being drawn directly back into the suction line. The suction port must be supplied with air-free, calmed and cooled hydraulic fluid.

Notice

In certain installation positions, an influence on the adjustment or control can be expected. Gravity, dead weight and case pressure can cause minor characteristic shifts and changes in actuating time.

Installation position

See the following examples 1 to 12.
Further installation positions are available upon request.
Recommended installation positions: 1 and 3

Key	
F	Filling / Air bleeding
S	Suction port
$L;\ L_1;\ L_2$	Drain port
SB	Baffle (baffle plate)
h _{t min}	Minimum required immersion depth (200 mm (7.87 inch))
h _{min}	Minimum required distance to reservoir bottom (100 mm (3.94 inch))
h _{ES min}	Minimum height required to prevent axial piston unit from draining (25 mm (0.98 inch))
h _{S max}	Maximum permissible suction height (800 mm (21.50 inch))

Notice

Port **F** is part of the external piping and must be provided on the customer side to make filling and air bleeding easier.



Axial piston variable pump | **A10VO series 52 and 53** 81 Installation instructions

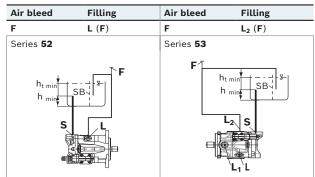
Below-reservoir installation (standard)

Below-reservoir installation means that the axial piston unit is installed outside of the reservoir below the minimum fluid level.

▼ Installation position 1

Air bleed	Filling	Air bleed	Filling
F	L (F)	F	L ₁ (F)
Series 52		Series 53	
F L	h _{t min}	F Li Li	h _{t min} h min

▼ Installation position 4



▼ Installation position 2¹⁾

Air bleed	Filling	Air bleed	Filling
F	L ₁ (F)	F	L ₁ (F)
Series 52		Series 53	
F L ₁	h _{t min} SB	F	h _{t min} SB ₁ y h min

▼ Installation position 3¹⁾

Air bleed	Filling	Air bleed	Filling
F	L (F)	F	L (F)
Series 52 h _{t min} h min		ht min h min	F SB

For key, see page 80.

¹⁾ Because complete air bleeding and filling are not possible in this position, the pump should be air bled and filled in a horizontal position before installation.



82 **A10VO series 52 and 53** | Axial piston variable pump Installation instructions

Dimensions [mm]

Above-reservoir installation

Above-reservoir installation means that the axial piston unit is installed above the minimum fluid level of the reservoir. To prevent the axial piston unit from draining, a height difference $h_{\text{ES min}}$ of at least 25 mm (0.98 inch) is required in position 6. Observe the maximum permissible suction height $h_{\text{S max}}$ = 800 mm (31.50 inch).

▼ Installation position 5

Air bleed	Filling	Air bleed	Filling
F	L (F)	F	L ₁ (F)
Series 52 F L S h _{t min} h min	h _{s max}	Series 53	h _{s max}

▼ Installation position 6¹⁾

Air bleed	Filling	Air bleed	Filling
F	L ₁ (F)	F	L ₁ (F)
Series 52		Series 53	
h _{ES min}	L	h _{ES min}	L ₁
h _{s max}		h _{s max}	
h _{t min} h _{min}	SB,	h _{t min}	SB 1

▼ Installation position 7¹)

Air bleed	Filling	Air bleed	Filling
F	L (F)	F	L (F)
Series 52		Series 53	
	S h _{s max}	F L ₁	h _{s max}

A check valve in the case drain line is only permissible in individual cases. Consult us for approval.

For key, see page 80.

▼ Installation position 8

Air bleed	Filling	Air bleed	Filling
F	L ₁ (F)	F	L ₂ (F)
Series 52 L1 h _{t min} h _{min}	S h _{s max}	Series 53 L L h _{t mir} h _{min}	

Because complete air bleeding and filling are not possible in this position, the pump should be air bled and filled in a horizontal position before installation.



Dimensions [mm]

Axial piston variable pump | **A10VO series 52 and 53** 83 Installation instructions

Inside-reservoir installation

Inside-reservoir installation is when the axial piston unit is installed in the reservoir below the minimum fluid level. The axial piston unit is completely below the hydraulic fluid.

If the minimum fluid level is equal to or below the upper edge of the pump, see chapter "Above-reservoir installation". Axial piston units with electrical components (e.g. electric control, sensors) may not be installed in a reservoir below the fluid level.

▼ Installation position 9

Air bleed	Filling	Air bleed	Filling
L	L	L ₁	L ₁
Series 52		Series 53	
L	SB unim ht min	L ₁ , L	SS SB unin ht min

▼ Installation position 10¹)

Air bleed	Filling	Air bleed	Filling
L ₁	L ₁	L ₁	L ₁
Series 52 L ₁	SB S	Series 53	P SB

▼ Installation position 11¹)

Air bleed	Filling	Air bleed	Filling
L	L	L	L
Series 52	S SB SB P I I I I I I I I I I I I I I I I I I	Series 53	S SB.

For key, see page 80.

Notice

▶ Our advice is to fit a suction pipe to the suction port S and to fit a pipe to case drain port L, L₁ or L₂. In this case, the other drain port must be plugged. The housing of the axial piston unit is to be filled via L, L₁ or L₂ (see installation position 9 to 12) before the pipework is fitted and the reservoir is filled with hydraulic fluid.

▼ Installation position 12

Air bleed	Filling	Air bleed	Filling
L ₁	L ₁	L ₂	L ₂
Series 52	S S S S S S S S S S S S S S S S S S S	Series 53	SB SB William Pt min

 Because complete air bleeding and filling are not possible in this position, the pump should be air bled and filled in a horizontal position before installation.



84 **A10VO series 52 and 53** | Axial piston variable pump Project planning notes

Project planning notes

- ► The A10VO axial piston variable pump is designed to be used in open circuit.
- The project planning, installation and commissioning of the axial piston unit requires the involvement of skilled personnel.
- ▶ Before using the axial piston unit, please read the corresponding instruction manual completely and thoroughly. If necessary, this can be requested from Bosch Rexroth.
- Before finalizing your design, please request a binding installation drawing.
- The specified data and notes contained herein must be observed.
- ▶ Depending on the operating conditions of the axial piston unit (working pressure, fluid temperature), the characteristic curve may shift. The characteristic curve may also shift due to the dither frequency or control electronics.
- ▶ Preservation: Our axial piston units are supplied as standard with preservation protection for a maximum of 12 months. If longer preservation protection is required (maximum 24 months), please specify this in plain text when placing your order. The preservation periods apply under optimal storage conditions, details of which can be found in the data sheet 90312 or the instruction manual.
- ▶ Not all configuration variants of the product are approved for use in a safety function according to ISO 13849. Please consult the proper contact at Bosch Rexroth if you require reliability parameters (e.g., MTTF_d) for functional safety.
- ▶ Depending on the type of control used, electromagnetic effects can be produced when using solenoids.

 Applying a direct voltage signal (DC) to solenoids does not create electromagnetic interference (EMI) nor is the solenoid affected by EMI. Electromagnetic interference (EMI) potential exists when operating and controlling a solenoid with a modulated direct voltage signal (e.g. PWM signal) Appropriate testing and measures should be taken by the machine manufacturer to ensure other components or operators (e.g. with pacemaker) are not affected by this potential.

- Pressure controllers are not safeguards against pressure overload. Be sure to add a pressure relief valve to the hydraulic system.
- ▶ Please note that a hydraulic system is an oscillating system. This can lead, for example, to the stimulation the natural frequency within the hydraulic system during operation at constant rotational speed over a long period of time. The excitation frequency of the pump is 9 times the rotational speed frequency. This can be prevented, for example, with suitably designed hydraulic lines.
- Please note the details regarding the tightening torques of port threads and other threaded joints in the instruction manual.
- ▶ The ports and fastening threads are designed for the p_{max} permissible pressures of the respective ports, see the connection tables. The machine or system manufacturer must ensure that the connecting elements and lines correspond to the specified application conditions (pressure, flow, hydraulic fluid, temperature) with the necessary safety factors.
- The service ports and function ports are only intended to accommodate hydraulic lines.



Axial piston variable pump | **A10VO series 52 and 53** 89 Safety instructions

Safety instructions

- ▶ During and shortly after operation, there is a risk of getting burnt on the axial piston unit and especially on the solenoids. Take the appropriate safety measures (e.g. by wearing protective clothing).
- Moving parts in control equipment (e.g. valve spools) can, under certain circumstances, get stuck in position as a result of contamination (e.g. contaminated hydraulic fluid, abrasion, or residual dirt from components). As a result, the hydraulic fluid flow and the build-up of torque in the axial piston unit can no longer respond correctly to the operator's specifications. Even the use of various filter elements (external or internal flow filtration) will not rule out a fault but merely reduce the risk.

 The machine/system manufacturer must test whether remedial measures are needed on the machine for the application concerned in order to bring the driven

consumer into a safe position (e.g., safe stop) and ensure any measures are properly implemented.